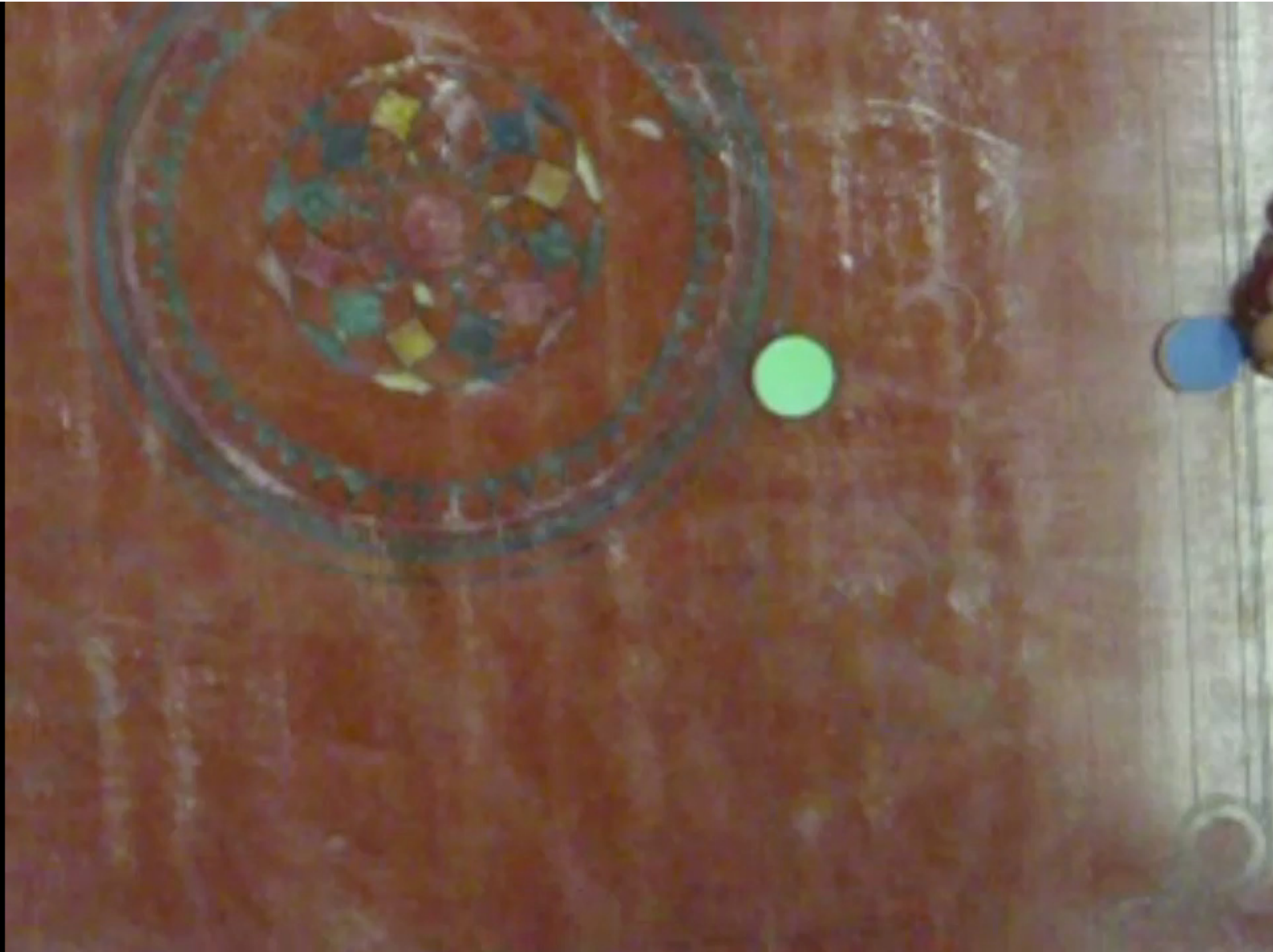
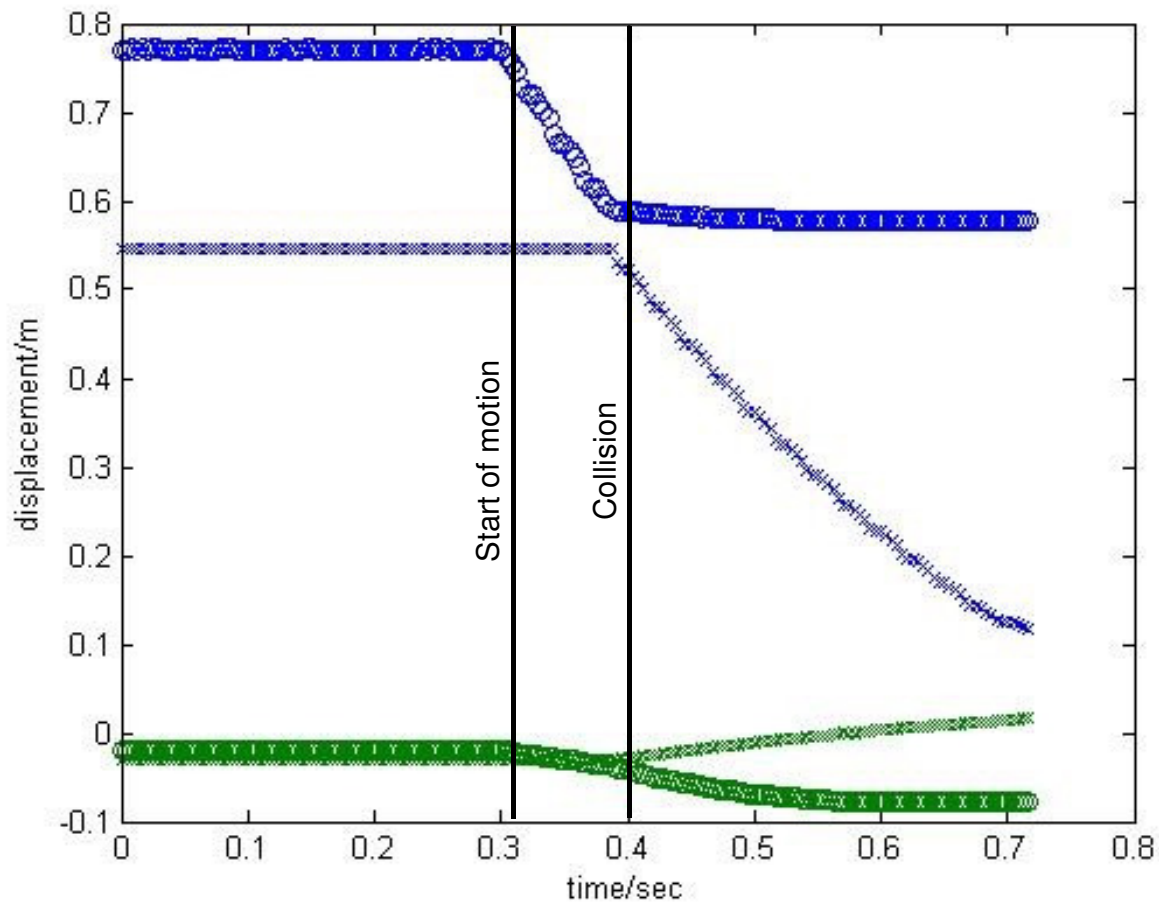


# CONSERVATION OF LINEAR MOMENTUM

Adil Ghaznavi  
Bisma Malik  
Ifrah Idrees

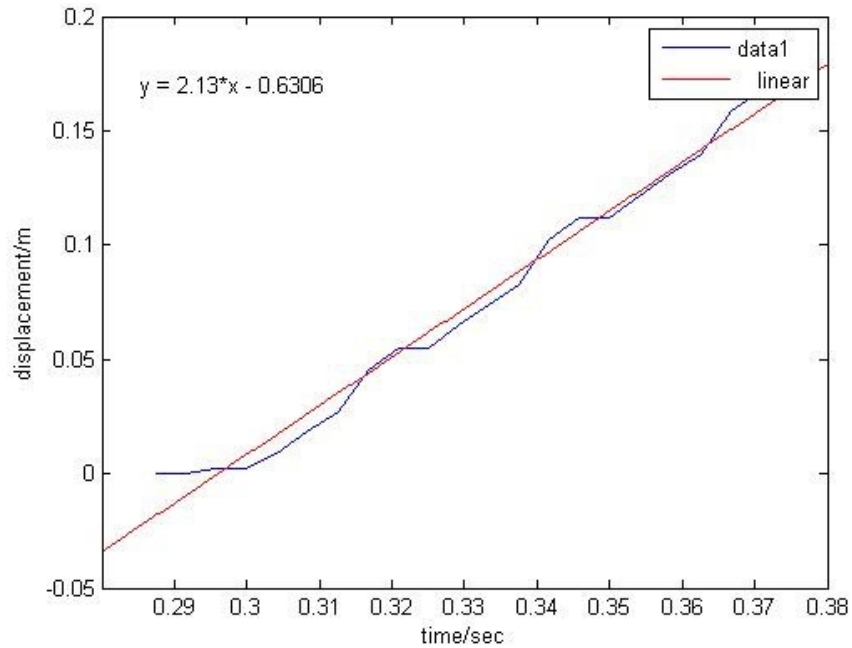
# Head on Collision ( $M_{\text{target}}=M_{\text{attacker}}$ )





- Taking time frames of the order of  $1 \times 10^{-1}$  seconds to minimise the affect of friction on the results.
- Run the x,y co-ordinates through the process data function to obtain a distance-time graph.
- The gradient of the graph gives us the velocity.

### Attacker Puck before Collision

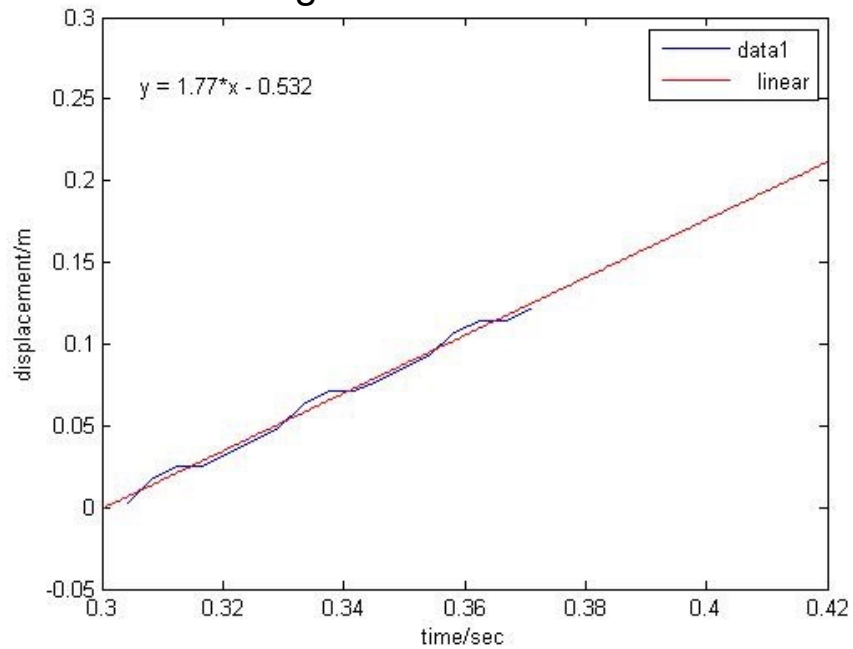


$$1.77\text{m/s} + 0.2648\text{m/s} = 2.0348\text{m/s}$$

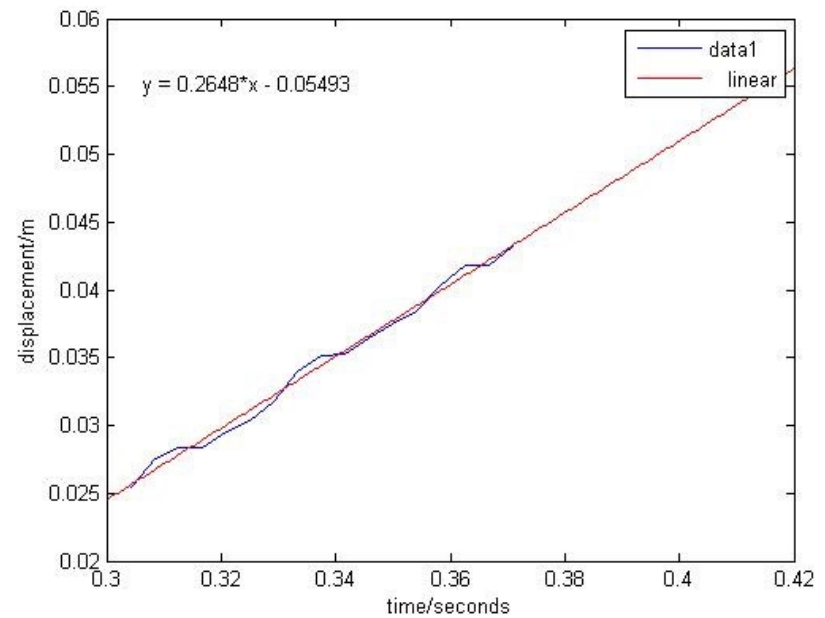
$$2.13\text{m/s} - 2.0348\text{m/s} = 0.095\text{m/s}$$

$$0.095/2.13 \times 100 = 4.5\% \text{ error}$$

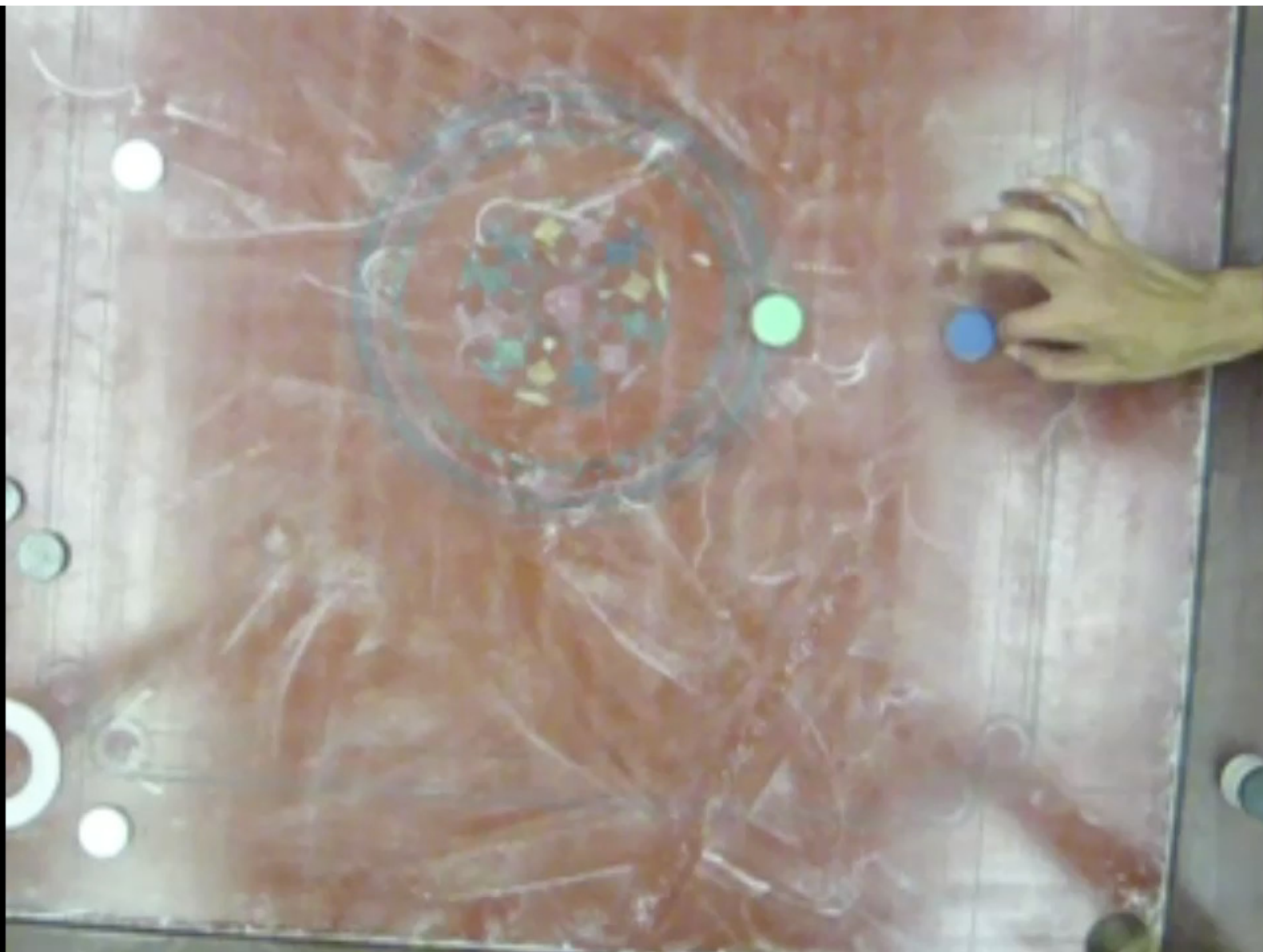
### Target Puck after Collision

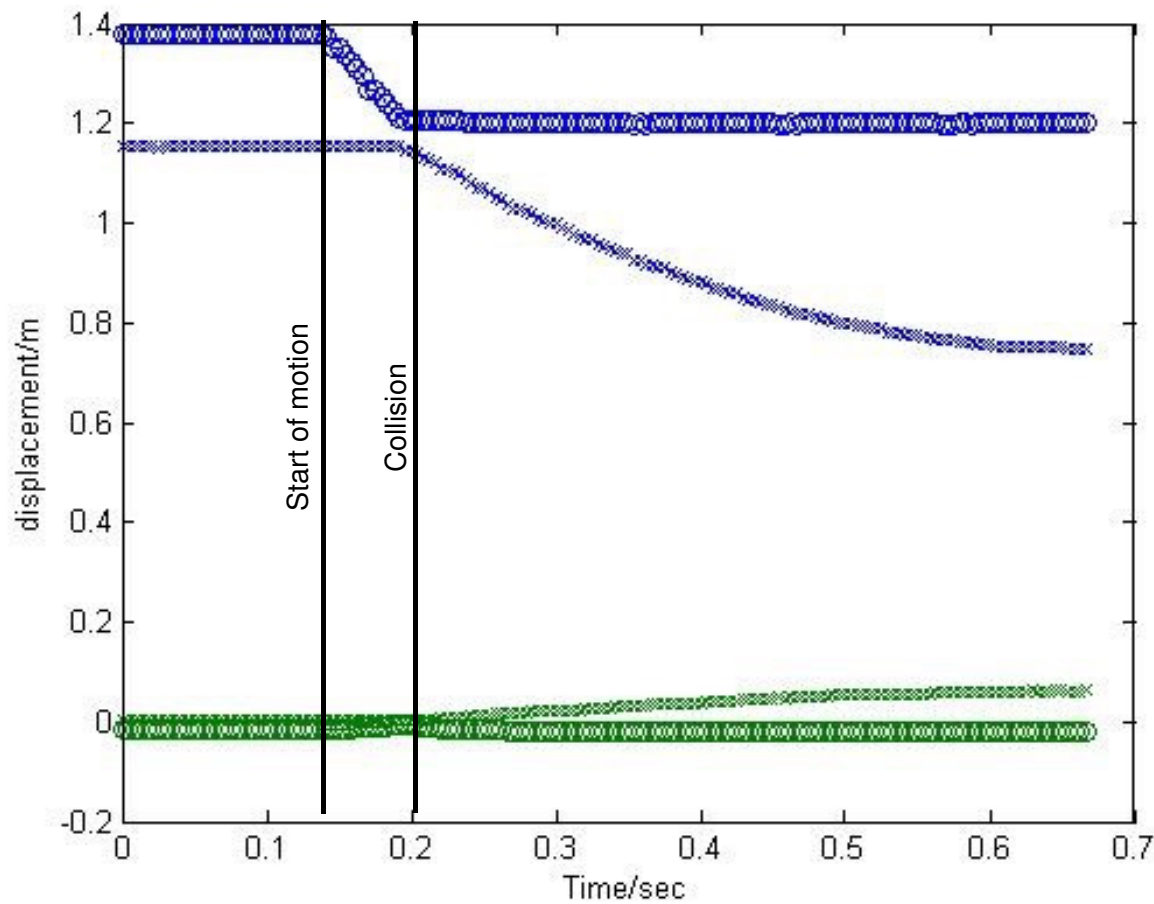


### Attacker Puck after Collision



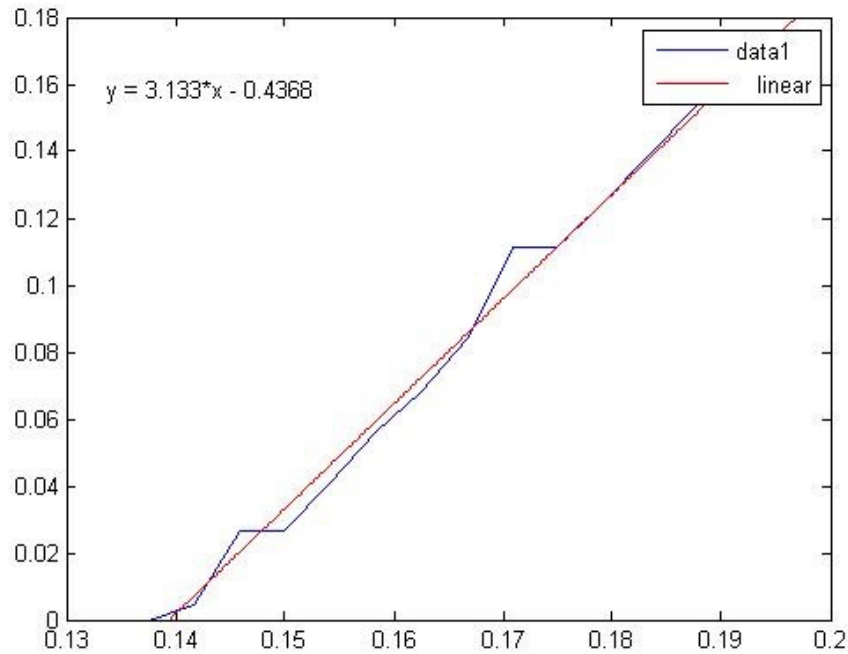
# Head on Collision ( $M_{\text{target}}=2M_{\text{attacker}}$ )





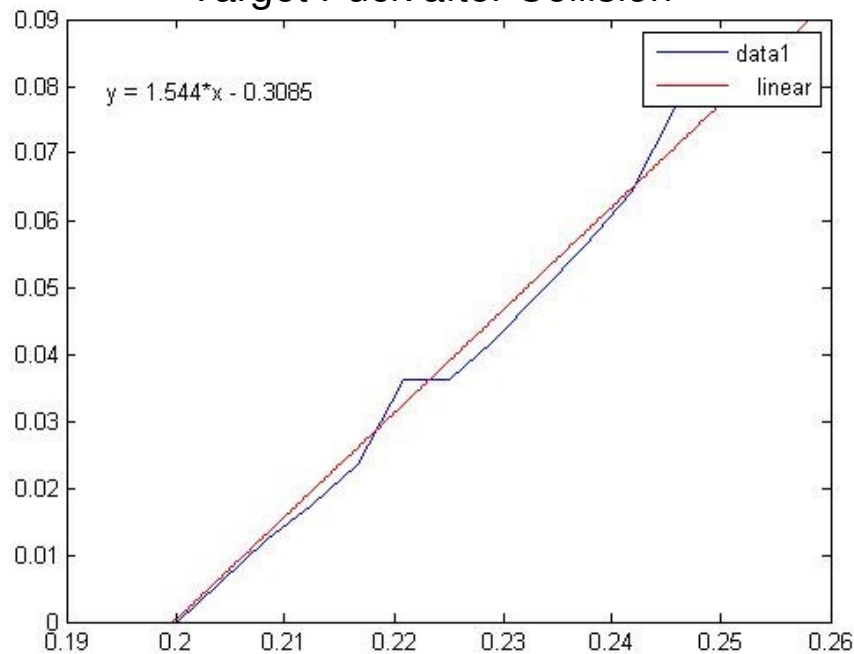
- We took a smaller time-frame because the effects of friction on the double mass body would be greater.

### Attacker Puck before Collision

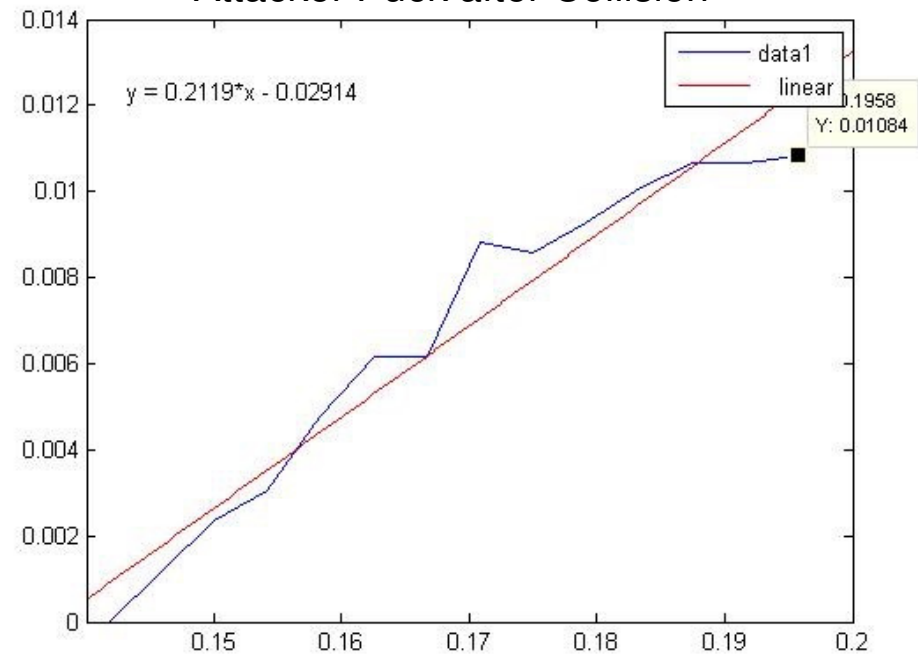


- initial momentum = final momentum
- $3.133(m) = 1.544(2m) + 0.2119(m)$
- Cancelling out the masses gives us
  - RHS = 3.113 m/s
  - LHS = 3.299 m/s
- $3.299 \text{ m/s} - 3.113 \text{ m/s} = 0.186 \text{ m/s}$
- $0.186/3.113 \times 100 = 5.9\% \text{ error}$

### Target Puck after Collision



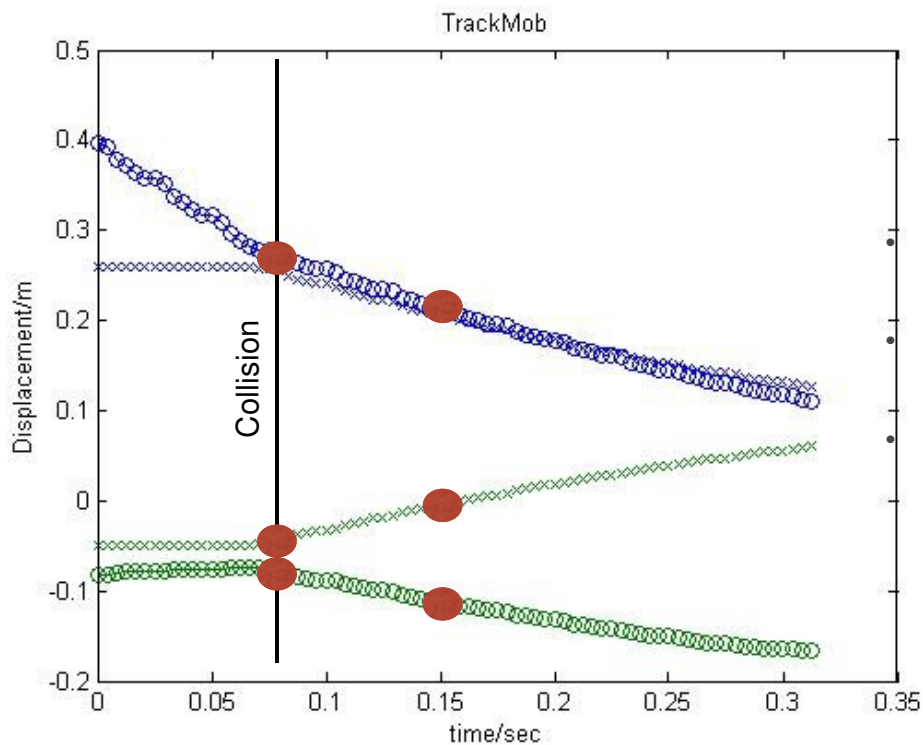
### Attacker Puck after Collision



## Collision at an Angle (Same mass)





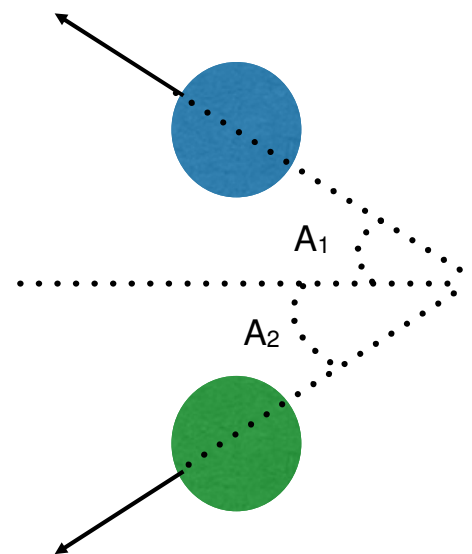


## Calculating the Angles

- We took the co-ordinates of the points marked in red.
- We know they lie on the line that the pucks are travelling on.
- The inverse tangents of the gradients gave us the angles relative to the initial trajectory of the attacker puck.

$$\begin{aligned} &\text{Gradient of path of blue puck} \\ &= ((-0.0104) - (-0.125)) / (0.3475 - 0.466) \\ &A_1 = \tan^{-1}(0.967) = 44^\circ \end{aligned}$$

$$\begin{aligned} &\text{Gradient of path of green puck} \\ &= (0.06981) / (0.0837) \\ &A_1 = \tan^{-1}(0.834) = 39.8^\circ \end{aligned}$$



$$p_x(\text{initial})=p_x(\text{final})=1.7\text{m}$$

$$p_y(\text{initial})=p_y(\text{final})=0$$

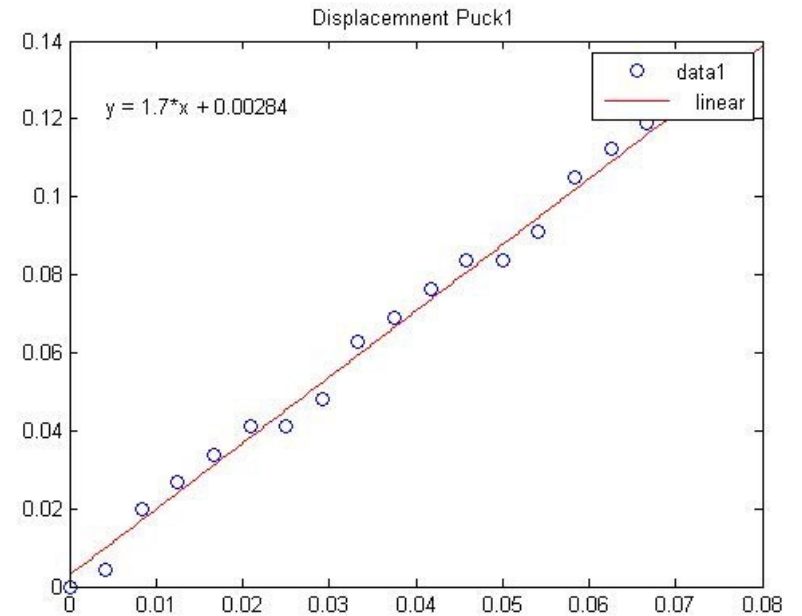
$$p_x(\text{final})=1*\cos(44)+0.9*\cos(39.8)=1.4$$

$$1.7-1.4=.3$$

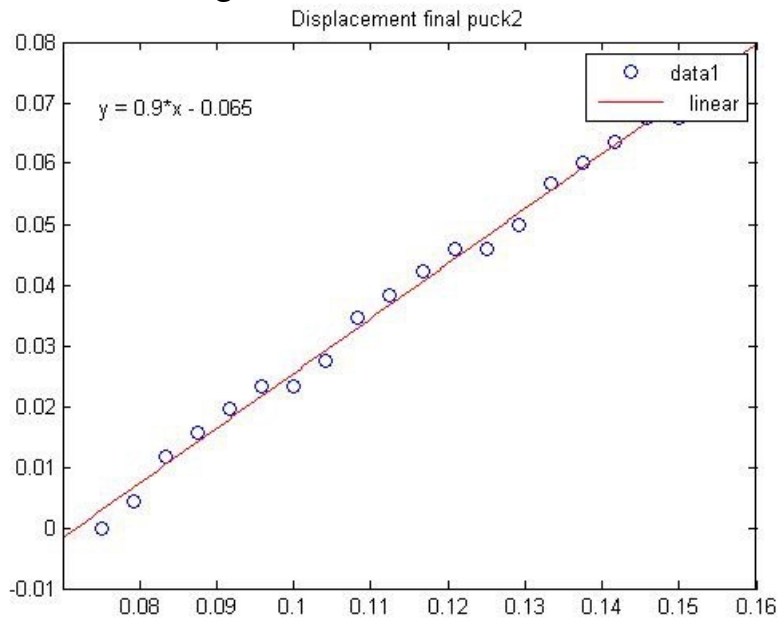
$$.3/1.7 \times 100 = 17.6\% \text{ error}$$

$$p_y(\text{final})=1*\sin(44)-0.9*\sin(39.8)=0.12$$

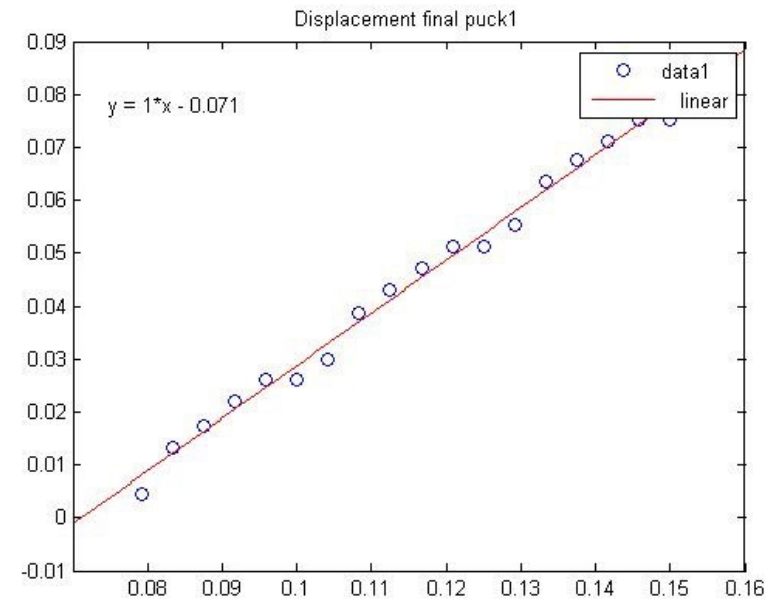
## Attacker Puck before Collision



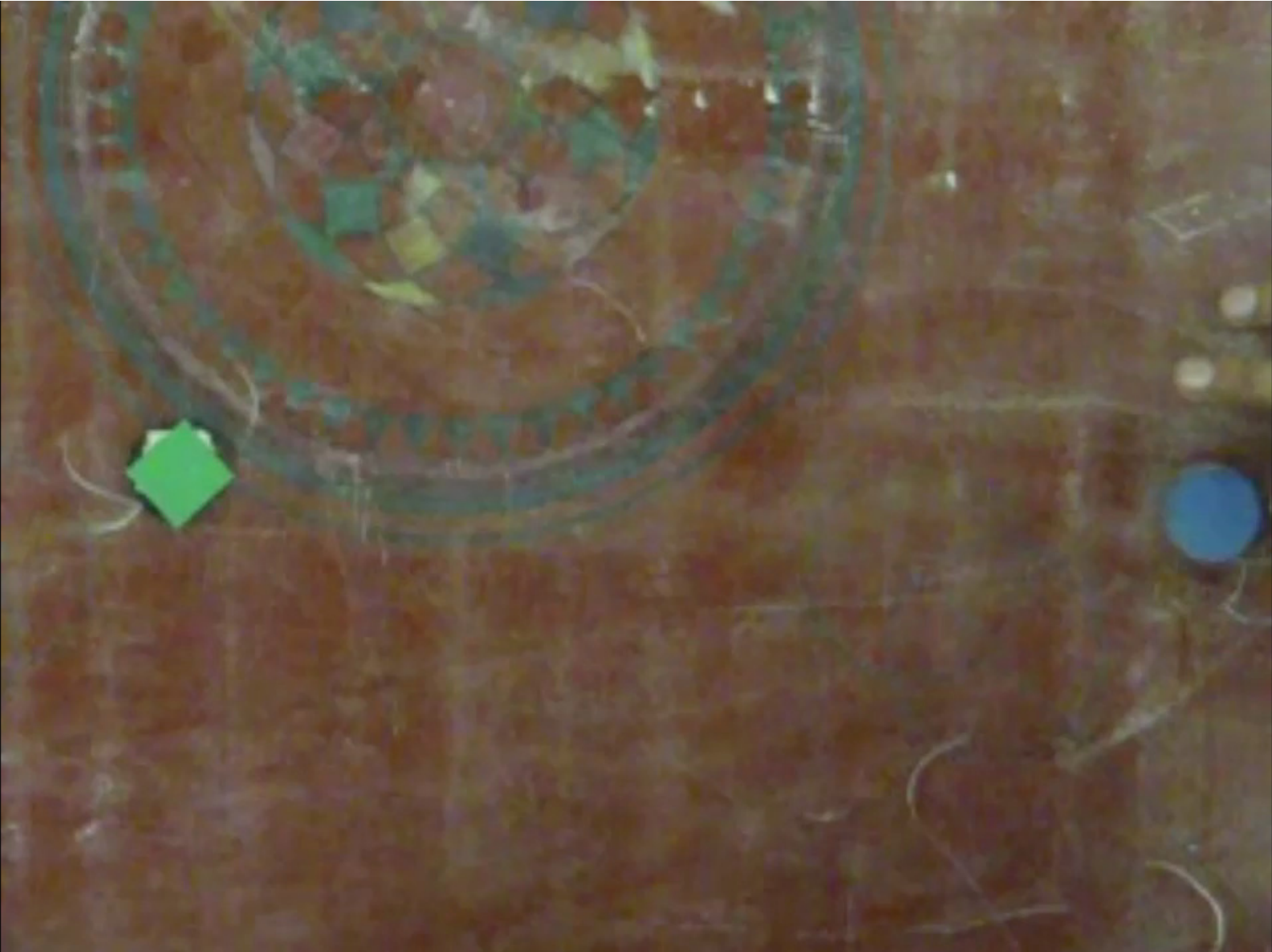
## Target Puck after Collision

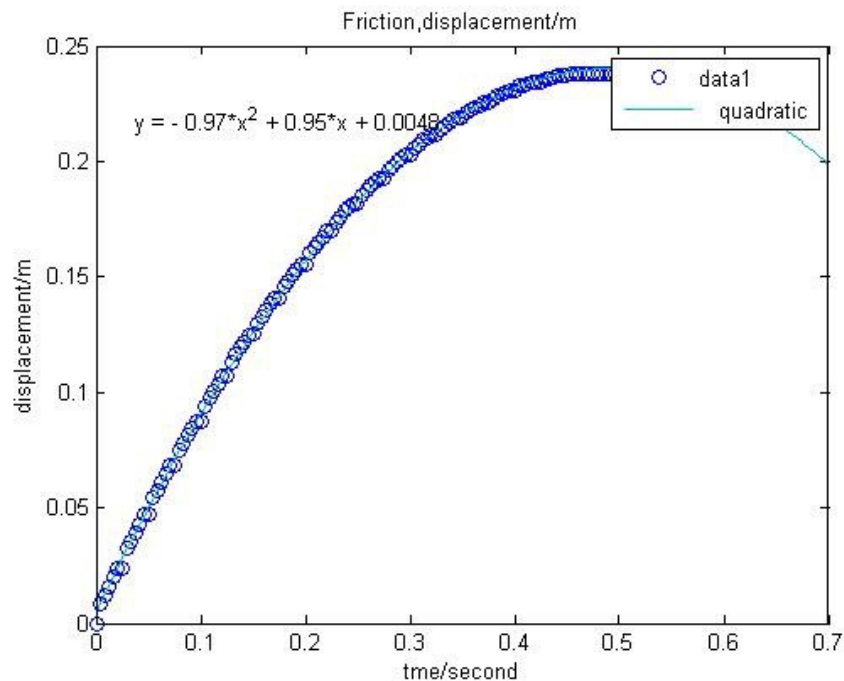
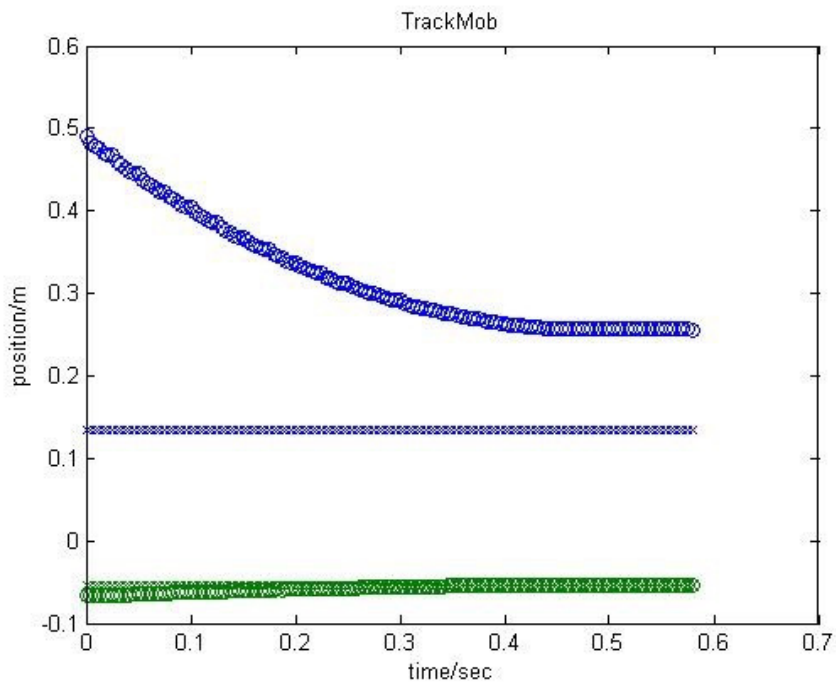


## Attacker Puck after Collision



# Co-efficient of Friction Analysis



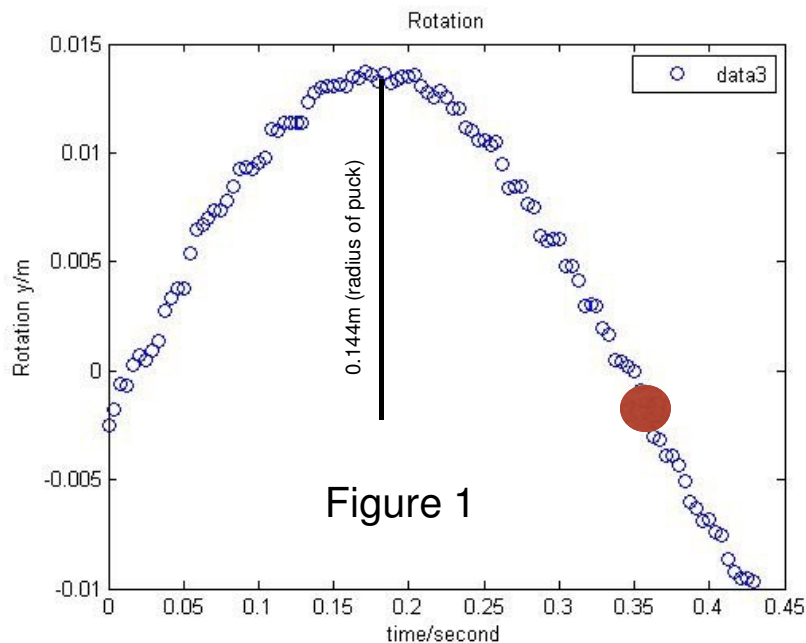
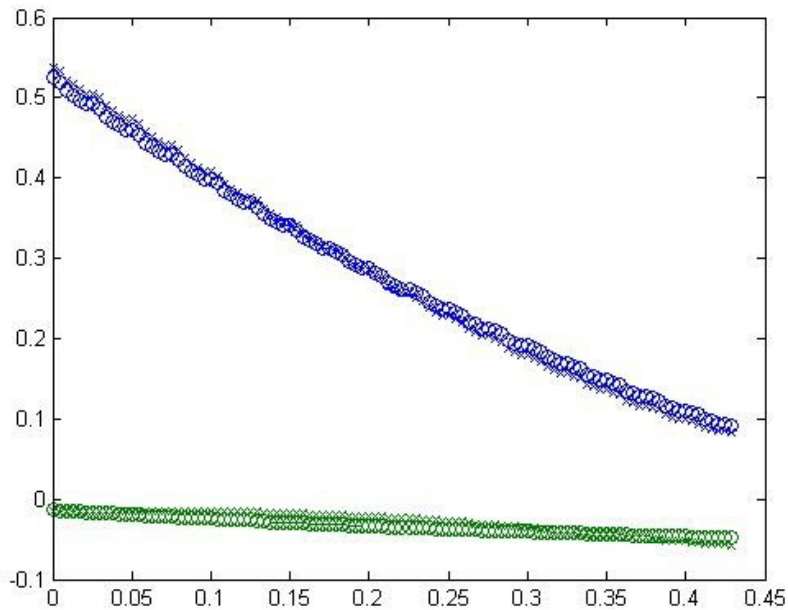


- Use the Processdata function to obtain the displacement/time curve.
  - Use basic fitting to obtain a quadratic fit for the curve
  - Different twice with respect to time to obtain deceleration
  - Deceleration in the direction of friction is given by  $= 2 \cdot 0.97 = 1.94$
- $$F = ma = \mu R$$
- $$R = W = mg$$
- $$\mu mg = ma$$
- $$\mu g = a$$
- $$\mu = a/g = 9.81/1.94 = 5.1$$
- This can give us a possible explanation for any errors in the readings

# Rotational Motion Analysis



## Track mob Data



- Trackmob gives us the roto-translational motion of the marker on the edge of the puck.
- To analyse the rotational motion, we needed to apply a frame shift, and move to the frame of reference of the centre of mass.
- This was done by placing a marker on the centre and then subtracting the position vectors of the two markers and plotting the resultant against time (figure 1)
- Completion of one half cycle took 0.36s.
- Using  $\Omega * t = \pi/2$  gives us  $\Omega$  (angular speed) = 8.72 rad/s
- $Y = 0.144 \sin(8.72 * t)$