

1. Uniformly charged ring of radius R , and negligible thickness.
i. Monopole Charge: $\&$ total charge Q .

$$Q' = \int \rho(r') d^3r' \quad Q = \lambda(2\pi R)$$

$$Q' = \int \left(\frac{Q}{2\pi R} \right) (R d\phi)$$

$$Q' = \frac{Q}{2\pi} \int d\phi = \frac{Q}{2\pi} (2\pi) = Q$$

$$Q' = Q \quad \text{or} \quad \boxed{Q = \lambda(2\pi R)}$$

- ii. Dipole Moment:

$$\vec{P} = \int d^3r \rho(\vec{r}) \vec{r} \quad \vec{r} = R(\cos\phi \hat{e}_x + \sin\phi \hat{e}_y)$$

$$\vec{P} = \int \lambda R d\phi \vec{r}$$

$$\vec{P}_x = \lambda R^2 \int_0^{2\pi} \cos\phi d\phi$$

$$\vec{P}_x = \lambda R^2 [\sin\phi]_0^{2\pi} = 0$$

$$\vec{P}_y = \lambda R^2 \int \sin\phi d\phi$$

$$\vec{P}_y = \lambda R^2 [-\cos\phi]_0^{2\pi} = 0$$

$$\vec{P}_z = 0$$

Dipole moment of a uniformly charged ring is 0.

- iii. Quadrupole Moment:

$$dq = R(\theta) R d\theta$$

$$(r_1, r_2, r_3) = (x, y, z)$$

$$Q_{ij} = \int_0^{2\pi} d\theta \rho(\theta) R (3r_i r_j - r^2 \delta_{ij})$$

$$(x, y) = (R \cos\theta, R \sin\theta), \quad z = 0 \quad (\text{since ring is in the } xy \text{ plane where } z = 0)$$

Since, $z=0$, this means that $Q_{xz} = Q_{yz} = Q_{zx} = Q_{zy} = 0$

$Q_{zz} = 0$ because:

$$Q_{zz} = - \int_0^{2\pi} d\theta \rho(\theta) R^2 = 0$$

$$Q_{xz} = \int_0^{2\pi} d\theta \rho(\theta) R^3 (3\cos^2\theta - 1)$$

$$= 2R^3 \int_0^{\pi/2} d\theta \rho(\theta) (3\cos(2\theta) + 2) + 2R^3 \int_{\pi/2}^{\pi} d\theta \rho(\theta) (3\cos(2\theta) + 2)$$

$$= 2R^3 \int_0^{\pi/2} d\theta \rho(\theta) [3\cos(2\theta) + 2] + 2R^3 \lambda \int_0^{\pi/2} \rho(\theta + \pi/2) d\theta [3\cos(2\theta + \pi) + 2]$$

$$= 6R^3 \int_0^{\pi/2} d\theta [\rho(\theta) - \rho(\theta)] [3\cos(2\theta) + 2]$$

$$= 0$$

Similarly $Q_{yy} = 0$

$$Q_{xy} = Q_{yz} = \int_0^{2\pi} d\theta \rho(\theta) R^3 (3\cos\theta \sin\theta)$$

$$= \frac{3R^3}{2} \int_0^{2\pi} d\theta \rho(\theta) \sin 2\theta$$

$$= \frac{3R^3}{2} \lambda \int_0^{2\pi} d\theta (\sin 2\theta)$$

$$= \frac{3R^3}{2} \lambda (4) = 6R^3 \lambda$$

$$Q_{ij} = \begin{pmatrix} 0 & 6R^3 \lambda & 0 \\ 6R^3 \lambda & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\frac{\lambda \pi R^2}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

[2.] a). Show that $\nabla_j \nabla_i \frac{1}{r} = \frac{3r_i r_j - \delta_{ij} r^2}{r^5}$

$$\checkmark \nabla_i \left(\frac{1}{r} \right) = \left(\nabla \frac{1}{r} \right)_i = - \left(\frac{\hat{r}}{r^2} \right)_i = - \left(\frac{\vec{r}}{r^3} \right)_i = \frac{-\phi_i \hat{r}}{r^3}$$

$$- \nabla_j \left(\frac{r_i}{r^3} \right) = - \left[\frac{1}{r^3} \underbrace{\nabla_j r_i}_{\delta_{ij}} + r_i \nabla_j \frac{1}{r^3} \right] \quad (a)$$

$$\rho(\vec{r}) = \lambda \delta(z) \delta(r-R)$$

$$Q_{xz} = Q_{yz} = Q_{zx} = Q_{zy} = Q_{zz} = 0$$

$$Q_{iy} = Q_{yx} = 0 \text{ (show yourself)}$$

$$Q_{xx} = \frac{1}{2} \int d^3 r \rho(\vec{r}) x_i x_i$$

(since $\sin\theta = 1$)

$$= \frac{\lambda}{2} \int_0^{2\pi} d\phi \int_0^\infty r^2 dr$$

$$= \frac{\lambda}{2} \int_0^{2\pi} \sin\phi d\phi \int_0^R R \delta(r-R) dr$$

$$= \frac{\lambda}{2} R^2 \int_0^{2\pi} \sin\phi d\phi$$

$$= \frac{\lambda R^2}{4} \int_0^{2\pi} (1 + \cos 2\phi) d\phi$$

$$= \frac{\lambda R^2}{4} \cdot 2\pi$$

$$= \frac{\lambda \pi R^2}{2}$$

$$\nabla_j \frac{1}{r^3} = \left(\nabla \frac{1}{r^3} \right)_j = -3 \left(\frac{\vec{r}}{r^4} \right)_j = -3 \left(\frac{\vec{r}}{r^5} \right)_j = -\frac{3r_j}{r^5}$$

Eq(a) now becomes:

$$\nabla_j \nabla_i \frac{1}{r} = -\frac{\delta_{ij}}{r^3} + \frac{3r_i r_j}{r^5}$$

$$\boxed{\nabla_j \nabla_i \frac{1}{r} = \frac{3r_i r_j - \delta_{ij} r^2}{r^5}} \quad \checkmark$$

b). $\phi(r) = \frac{1}{4\pi\epsilon_0} \int d^3r' \frac{\rho(r')}{|\vec{r} - \vec{r}'|} \quad \checkmark$

this sign
is
inverted

$$= -\frac{1}{4\pi\epsilon_0} \int d^3r' \frac{Q_{ij} \nabla'_i \nabla'_j \delta(r' - r_0)}{|\vec{r} - \vec{r}'|} \quad \checkmark$$

$$= \frac{+1}{4\pi\epsilon_0} \int d^3r' \delta(r' - r_0) Q_{ij} \nabla'_i \nabla'_j \frac{1}{|\vec{r} - \vec{r}'|} \quad \checkmark$$

(Using Integration by parts)

$$= \frac{+1}{4\pi\epsilon_0} Q_{ij} \cancel{\nabla'_i \nabla'_j} \int d^3r' \delta(r' - r_0) \frac{1}{|\vec{r} - \vec{r}'|} \quad \checkmark$$

(Using sampling theorem
 $r' = r_0$)

$$\boxed{\phi(r) = -\frac{1}{4\pi\epsilon_0} Q_{ij} \nabla_i \nabla_j \frac{1}{|\vec{r} - \vec{r}_0|}} \quad \checkmark$$

c). $F = \int d^3r \rho(r) E(r) \quad \checkmark$

$$= Q_{ij} \int d^3r E(r) \nabla_i \nabla_j \delta(r - r_0) \quad \checkmark$$

$$\boxed{F = Q_{ij} \nabla_i \nabla_j E(r_0)} \quad \checkmark$$

d). $U_E = \int d^3r \phi(r) \rho(r) = Q_{ij} \int d^3r \phi(r) \nabla_i \nabla_j \delta(r - r_0) \leftarrow \text{Apply integration by parts}$

$$= Q_{ij} \int d^3r \delta(\vec{r} - \vec{r}_0) \nabla_i \nabla_j \phi(r) \quad \leftarrow \text{Using:}$$

$$E(r) = -\nabla \phi(\vec{r})$$

$$= -Q_{ij} \int d^3r \delta(r - r_0) \nabla_i E_j(r)$$

Label your

vectors properly.

$$\boxed{U_E = -Q_{ij} \nabla_i E_j(\vec{r}_0)} \quad \checkmark$$

Let's do it!

$$3. \quad N = \int d^3r' \times E(r') \rho_D(r')$$

$$N = \int d^3r' \delta(r'-r) (p \cdot \nabla) (r' \times E) \quad \checkmark$$

$$N_i = \epsilon_{ijk} \int d^3r' \delta(r'-r) p_m \nabla_L (r_j E_k) \quad \checkmark$$

$$N_i = \epsilon_{ijk} \int d^3r' \delta(r'-r) p_m \{ E_k \nabla_L r_j + r_j \nabla_L E_k \}$$

$$= \epsilon_{ijk} \int d^3r' \delta(r'-r) p_m \{ \delta_{Lj} E_k + r_j \nabla_L E_k \} \quad \checkmark$$

$$N_i = \epsilon_{ijk} p_m \{ \delta_{Lj} E_k + r_j \nabla_L E_m \} \quad \checkmark$$

Using $F = (p \cdot \nabla) E(r)$, we get: ✓

$$N_i = \epsilon_{ijk} p_m \delta_{Lj} E_k + r_j \epsilon_{ijk} p_m \nabla_L E_m \quad \checkmark$$

$$N_i = (p \times E)_i + (r \times F)_i \quad \checkmark$$

$$N = (p \times E) + (r \times F)$$

$$4. \quad a). \quad \rho_D(r) = -p \cdot \nabla \delta(r-r_0)$$

$$\phi(r) = \frac{1}{4\pi\epsilon_0} \int d^3r' \frac{\rho_D(r')}{|r-r'|}$$

$$= \frac{-1}{4\pi\epsilon_0} \int d^3r' \frac{\vec{p} \cdot \nabla \delta(r-r_0)}{|r-r'|}$$

$$= \frac{-\vec{p}}{4\pi\epsilon_0} \cdot \int d^3r' \underbrace{\frac{1}{|r-r'|}}_u \underbrace{\vec{\nabla} \delta(\vec{r}-\vec{r}_0)}_v \quad \text{--- ①}$$

We will use integration by parts for the above:

$$\int_{x \rightarrow -\infty}^{x \rightarrow +\infty} dx \left[\frac{d}{dx} (\delta(x)) \right] f(x)$$

$$= \int \underbrace{dx f(x)}_u \underbrace{\frac{d}{dx} \delta(x)}_{v'}$$

$$= \left. f(x) \delta(x) \right|_{-\infty}^{+\infty} - \int_{-\infty}^{+\infty} dx \delta(x) \frac{df}{dx}$$

potentials at ∞
is 0 (for bound
functions).

$$= - \int dx \delta(x) \frac{df}{dx}$$

We will use the above result on ①

$$\phi(r) = \frac{\vec{p}}{4\pi\epsilon_0} \cdot \int d^3r' \delta(r'-r_0) \nabla' \frac{1}{|\vec{r}-\vec{r}'|}$$

Now use the sampling theorem, $r' = r_0$.

$$\phi(r) = \frac{\vec{p}}{4\pi\epsilon_0} \cdot \nabla \frac{1}{|\vec{r}-\vec{r}_0|}$$

$$\phi(r) = \frac{\vec{p} \cdot (\vec{r}-\vec{r}_0)}{4\pi\epsilon_0 |\vec{r}-\vec{r}_0|^3}$$

For $\vec{r}_0 \equiv \text{origin}$ $\phi(\vec{r}) = \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 |\vec{r}|^3}$

Be rigorous about vector notation.

For $r \neq 0$

$$\vec{E} = -\nabla \phi(r)$$

$$E_j = -\frac{1}{4\pi\epsilon_0} p_i \nabla_j \left(\frac{\vec{r}_i}{r^3} \right) \quad \text{unclear } r = |\vec{r}-\vec{r}_0|$$

Solving the term in bracket:

$$\nabla_j \left(\frac{r_i}{r^3} \right) = \frac{1}{r^3} \nabla_j r_i + r_i \nabla_j \frac{1}{r^3}$$

$$= \frac{1}{r^3} \delta_{ij} + r_i \nabla_j \frac{1}{r^3} \quad \text{--- ②}$$

$$\nabla_j \frac{1}{r^3} = \left(\nabla \frac{1}{r^3} \right)_j = -3 \left(\frac{\hat{r}}{r^4} \right)_j = -3 \left(\frac{\vec{r}}{r^5} \right)_j = -\frac{3r_j}{r^5}$$

The eq ② now becomes:

$$\nabla_j \left(\frac{r_i}{r^3} \right) = \frac{1}{r^3} \left(\delta_{ij} - 3 \frac{r_i r_j}{r^2} \right)$$

Show

$$\vec{E} = -\vec{\nabla} \frac{1}{4\pi\epsilon_0} \left(\frac{\vec{p} \cdot \hat{r}}{r^2} \right)$$

So, \vec{E}_j now becomes:

$$= -\vec{\nabla} \frac{1}{4\pi\epsilon_0} \left(\frac{\vec{p} \cdot \hat{r}}{r^3} \right)$$

$$E_j = -\frac{1}{4\pi\epsilon_0} p_i \frac{1}{r^3} \left(\delta_{ij} - 3 \frac{r_i r_j}{r^2} \right)$$

$$= \frac{1}{4\pi\epsilon_0 r^3} \left(\frac{3r_i r_j p_i}{r^2} - p_i \delta_{ij} \right)$$

$$E_j = \frac{1}{4\pi\epsilon_0 r^3} \left(\frac{3r_i r_j p_i}{r^2} - p_i \right)$$

$$\boxed{\vec{E} = \frac{1}{4\pi\epsilon_0 r^3} (3\hat{r}(\hat{r} \cdot \vec{p}) - \vec{p})}$$

~~impdgn~~

b). The work done by us to bring p_2 into position (with p_1 already present) is exactly the interaction energy with the "electric field of p_1 playing the role of E_{ext} ."

$$V_E = -\vec{p}_2 \cdot \vec{E}_1(r_2)$$

$$= \frac{1}{4\pi\epsilon_0} \left\{ \frac{\vec{p}_1 \cdot \vec{p}_2}{|r_2 - r_1|^3} - \frac{3\vec{p}_1 \cdot (r_2 - r_1) \vec{p}_2 \cdot (r_2 - r_1)}{|r_2 - r_1|^5} \right\} \quad \checkmark$$

$$r = |r_2 - r_1|$$

$$= \frac{1}{4\pi\epsilon_0} \left\{ \frac{\vec{p}_1 \cdot \vec{p}_2}{r^3} - \frac{3(\vec{p}_1 \cdot \hat{r})(\vec{p}_2 \cdot \hat{r})}{r^3} \right\}$$

$$\boxed{V_E = \frac{1}{4\pi\epsilon_0 r^3} (\vec{p}_1 \cdot \vec{p}_2 - 3(\vec{p}_1 \cdot \hat{r})(\vec{p}_2 \cdot \hat{r}))}$$

$$\hat{z} = \hat{r} \cos \theta - \hat{\theta} \sin \theta$$

c). We choose a polar coordinate system with $p_1 \parallel \hat{z}$. The field produced by p_1 in this system is:

$$\vec{E}_1 = \frac{p_1}{4\pi\epsilon_0 r^3} (2\cos\theta_1 \hat{r} + \sin\theta_1 \hat{\theta})$$

At equilibrium, the potential energy $V_E = -\vec{p}_2 \cdot \vec{E}_1$ is a minimum.

$$\vec{p}_2 = p_2 \cos\theta_2 \hat{r} + p_2 \sin\theta_2 \hat{\theta}$$

$$\begin{aligned} V_E &= -\vec{p}_2 \cdot \vec{E}_1 \\ &= \frac{1}{4\pi\epsilon_0} \left[-p_1 p_2 2\cos\theta_1 \cos\theta_2 - p_1 p_2 \sin\theta_1 \sin\theta_2 \right] \end{aligned}$$

To find minimum V_E , we take its derivative & set it equal to 0.

$$0 = \frac{\partial V_E}{\partial \theta_2} = \frac{-p_1 p_2}{4\pi\epsilon_0} \left[-2\cos\theta_1 \sin\theta_2 + \sin\theta_1 \cos\theta_2 \right]$$

$$\begin{aligned} 2\cos\theta_1 \sin\theta_2 &= \sin\theta_1 \cos\theta_2 \\ \tan\theta_1 &= 2\tan\theta_2 \end{aligned}$$

$$\begin{aligned} \text{If } \theta_1 &= \frac{\pi}{4}, \text{ then } \theta_2 = \tan^{-1}(0.5) \\ &= 0.463 \text{ radians} \end{aligned}$$

5.

$$p(r) = \frac{R}{r^2} (R - 2r) \sin \theta$$

Let us first calculate the monopole charge:

$$\begin{aligned} Q &= \int d^3r p(r) \\ &= \int \frac{R}{r^2} (R - 2r) \sin \theta (r^2 \sin \theta d\theta d\phi dr) \\ &= \int (R^2 - 2Rr) \sin^2 \theta d\theta d\phi dr \\ &= \int (R^2 - 2Rr) dr \int \sin^2 \theta d\theta \int d\phi \\ &= \left[\frac{R^2 r}{2} - \frac{2Rr^2}{2} \right]_0^R \left[\frac{\sin 2\theta}{4} - \frac{1}{2} \theta \right]_0^\pi \left[\phi \right]_0^{2\pi} \end{aligned}$$

$$Q = 0$$

Now, let's calculate the dipole moment:

$$\begin{aligned} \vec{p} &= \int d^3r p(r) \vec{r} \quad \vec{r} = r(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta) \\ &= \int (R^2 - 2Rr) \sin^2 \theta d\theta d\phi dr \vec{r} \end{aligned}$$

$$\vec{p}_x = \int (R^2 - 2Rr) \sin^2 \theta d\theta d\phi dr r \sin \theta \cos \phi$$

$$\vec{p}_x = \int R^2 r - 2Rr^2 dr \int \sin \theta \frac{\cos 2\theta}{2} - \frac{\sin \theta}{2} d\theta \int \cos \phi d\phi$$

$$\vec{p}_x = \left[\frac{R^2 r^2}{2} - \frac{2Rr^3}{3} \right] \left[\frac{1}{3} \cos^3 \theta - \cos \theta \right] [\sin \phi]$$

$$\boxed{\vec{p}_x = 0}$$

$$\vec{p}_y = \left[\frac{R^2 r^2}{2} - \frac{2Rr^3}{3} \right] \left[\frac{1}{3} \cos^3 \theta - \cos \theta \right] [\cos \phi]$$

$$\boxed{\vec{p}_y = 0}$$

$$p_z = \left[\frac{R^2 r^2}{2} - \frac{2Rr^3}{3} \right] \left[\frac{\sin^3 \theta}{3} \right]_0^\pi = \left[\frac{R^4}{2} - \frac{2R^4}{3} \right] [0]$$

$$\boxed{\vec{p}_z = 0}$$

- Lowest order term - the multipole expansion is

$$Q_{xx} = Q_{yy} = \frac{1}{2} \int d^3x \rho(\vec{r}) x^2$$

$$= \frac{1}{2} \int d^3x \frac{R}{r^4} (R-2r) \sin \theta \cancel{r^3} \sin^2 \theta \cos^2 \phi$$

$$= \frac{1}{2} \int d\theta d\phi dr \left(r^2 \sin^4 \theta \right) R (R-2r) \cos^2 \phi$$

$$= \frac{1}{2} \int_{\phi=0}^{2\pi} d\phi \cos^2 \phi \int_{\theta=0}^{\pi} d\theta \sin^4 \theta \int_{r=0}^R R r^2 (R-2r) dr$$

$$= -\pi^2 R^5 / 32$$

Similarly $Q_{zz} = -\pi^2 R^5 / 48$

$$\vec{Q} = \frac{-\pi^2 R^5}{32} \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1/2 \end{pmatrix}$$

One can show that other terms are zero.