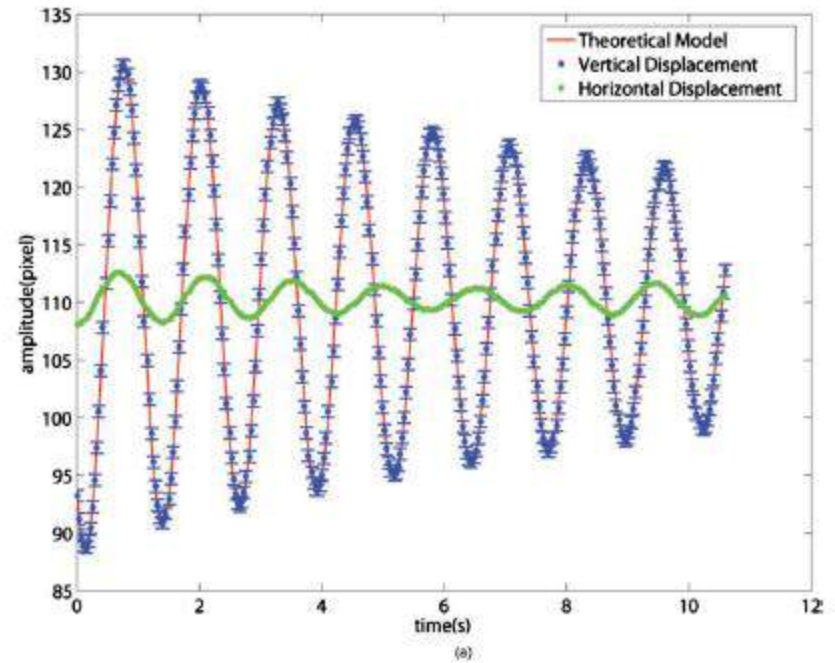
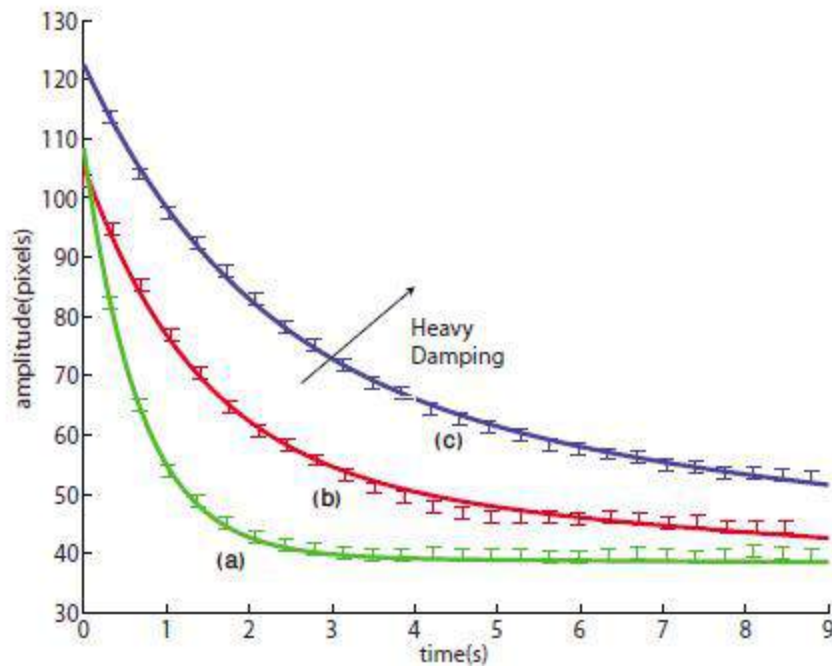
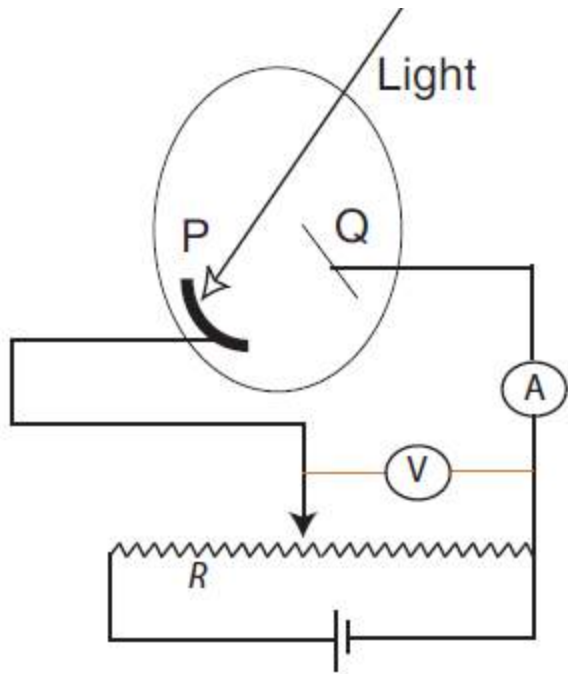


Graphical Presentation of Data



Dr. Muhammad Sabieh Anwar and his Physlab colleagues



$$\frac{1}{2}mv^2 = V_o e = hf - W$$

$$V_o = \frac{h}{e} f - \frac{W}{e}$$

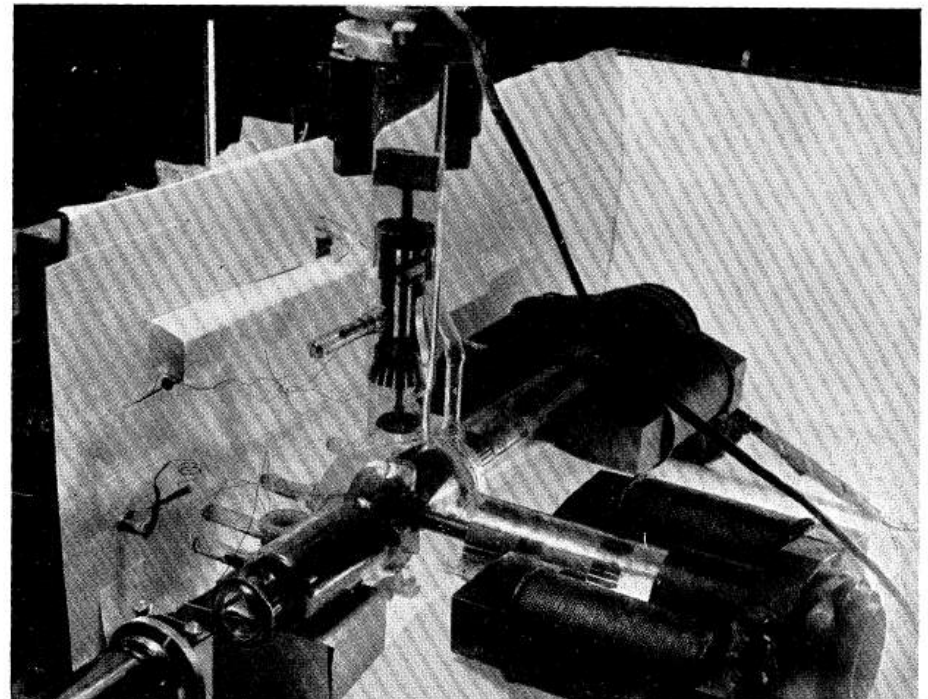


TABLE I.

5,461.		4,339.		4,047.		3,650.		3,126.		2,535.	
Volts.	Def'n., mm.	Volts.	Def'n., mm.	Volts.	Def'n., mm.	Volts.	Def'n., mm.	Volts.	Def'n., mm.	Volts.	Def'n., mm.
2.257	28	1.581	44	1.576	82	1.157	67½	.5812	52	-.0576	68
2.205	14	1.629	20	1.524	55	1.105	36	.5288	29	+.0576	38
2.152	7	1.576	10	1.471	36	1.0525	19	.4765	12	+.1620	26
2.100	3	1.524	4	1.419	24	1.0002	11	.4242	5	+.2670	16½
				1.367	3	.9478	4	.3718	2½	+.3720	8

TABLE III.

[illegible]

Photocurrents

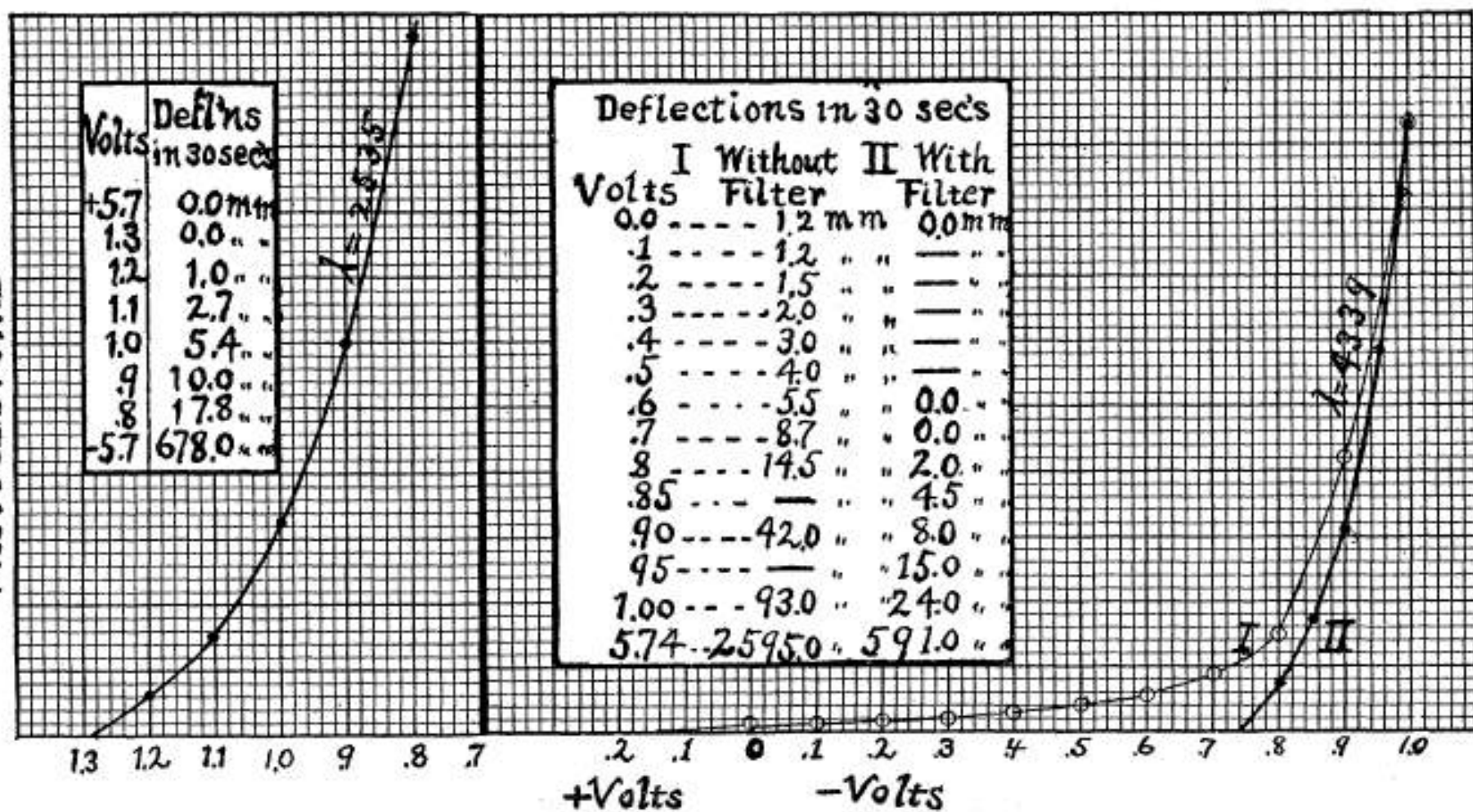
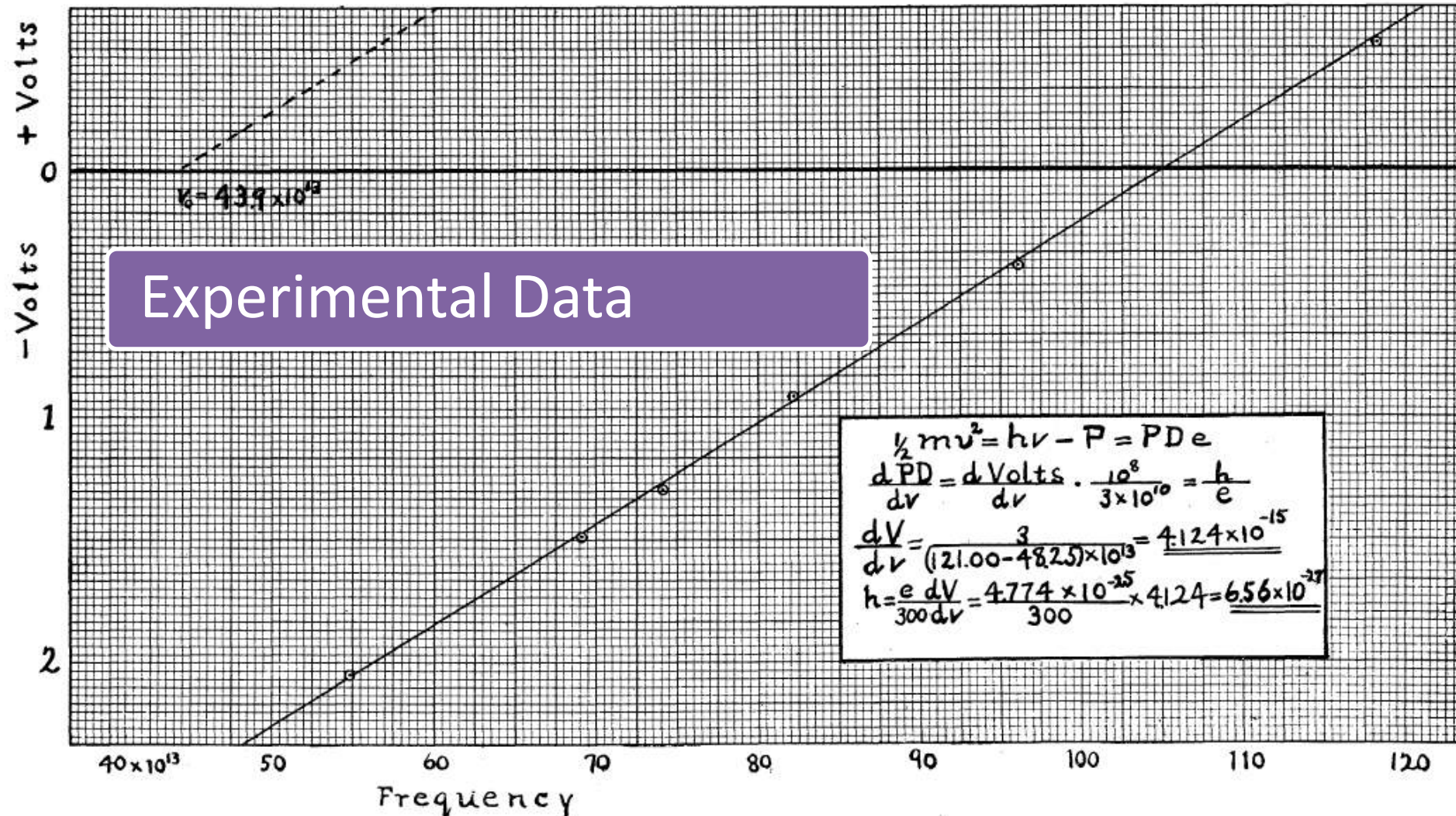


Fig. 4.

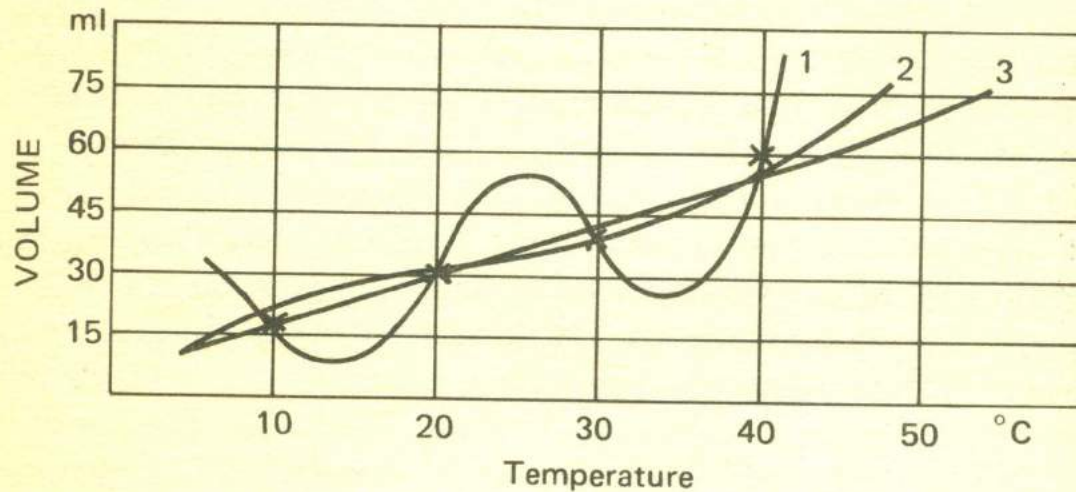
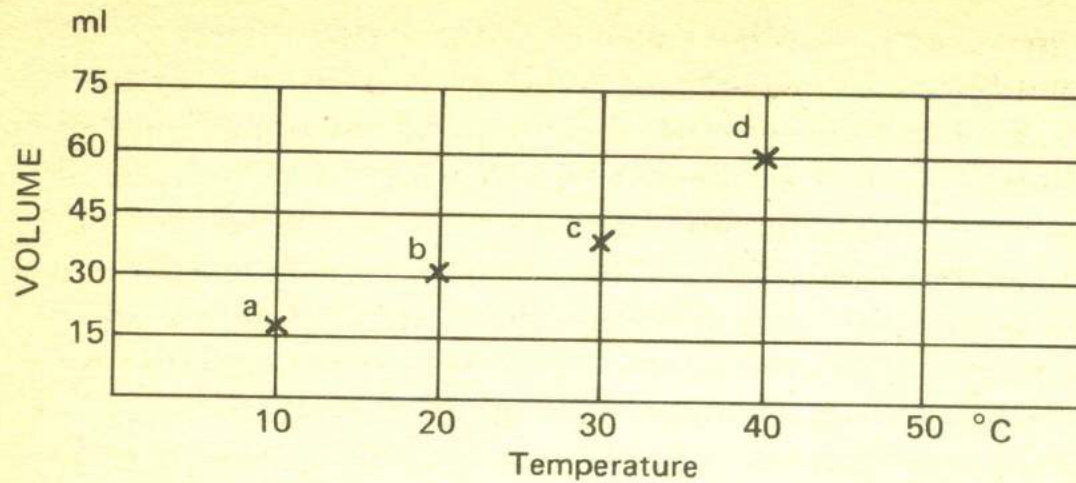
$$V_o = \frac{h}{e} f - \frac{W}{e}$$

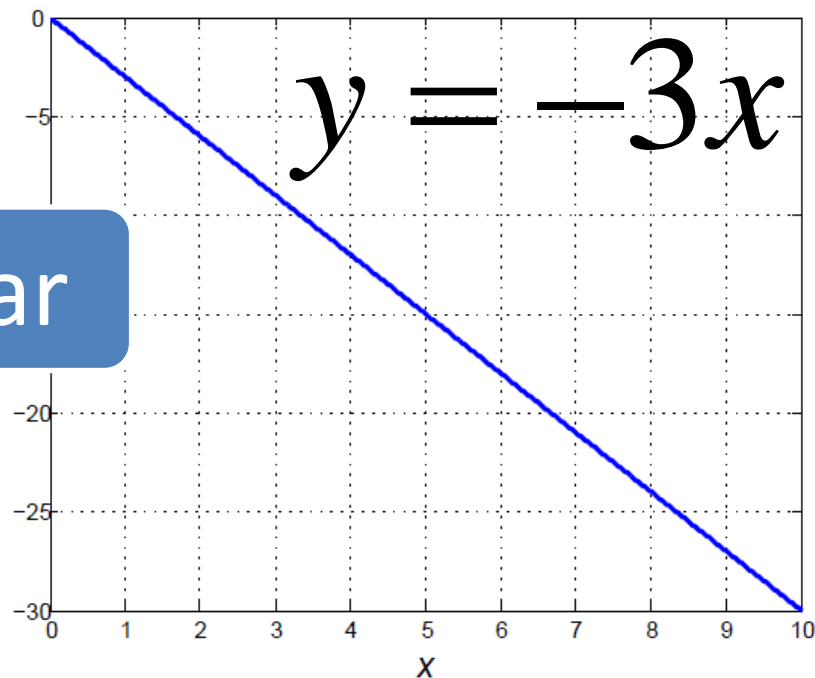
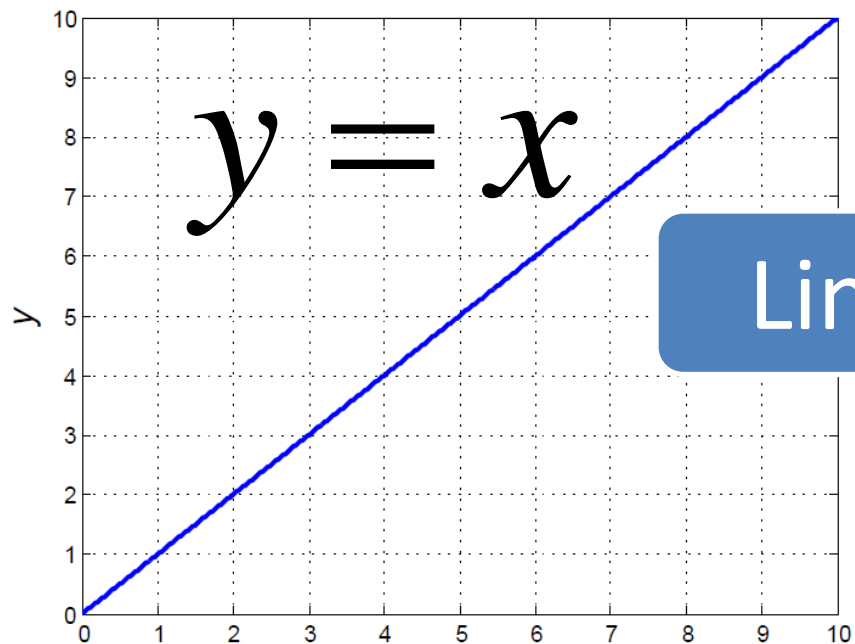
Model

Experimental Data

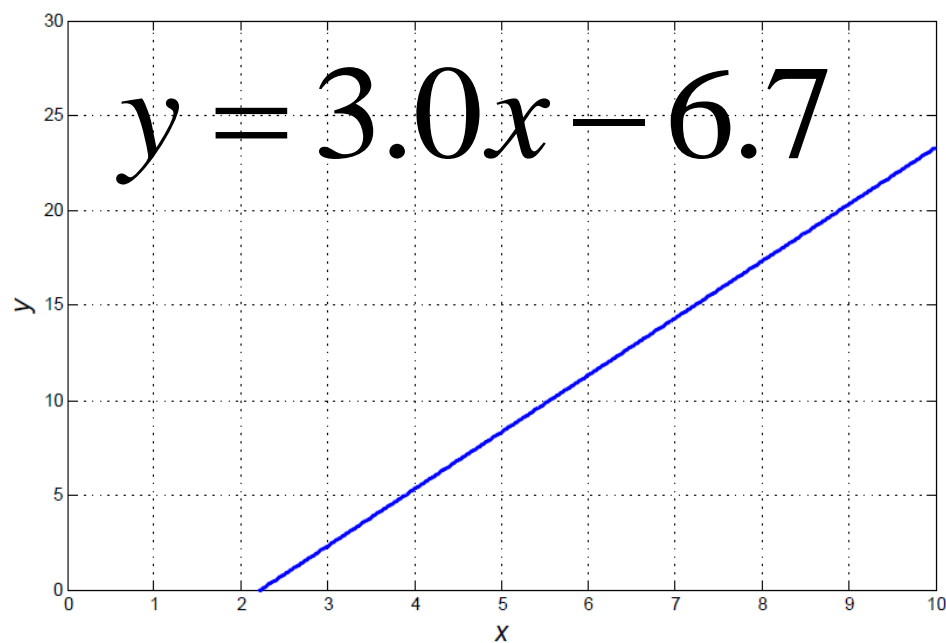
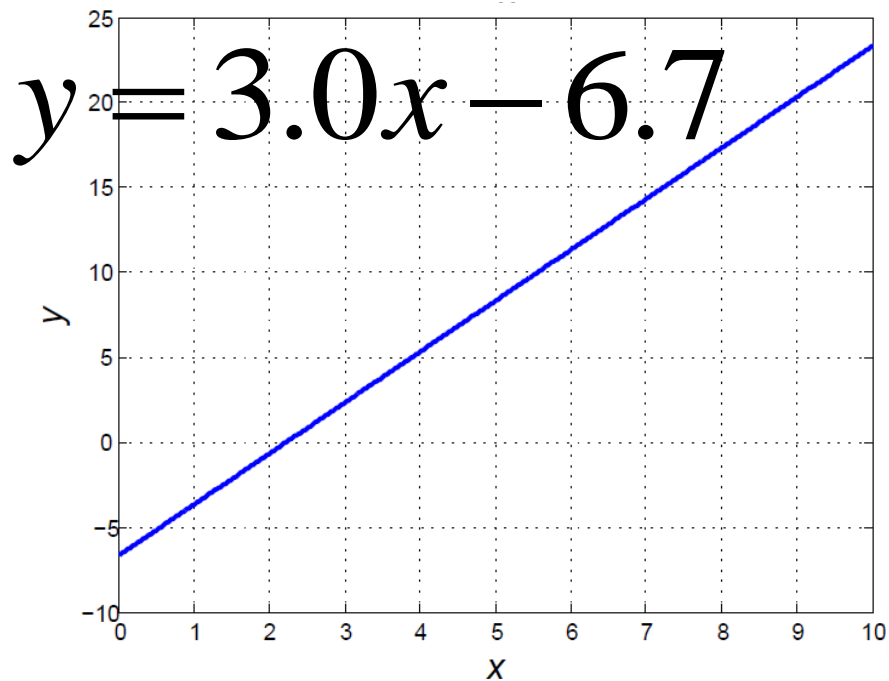


Typical models that fit typical experimental data



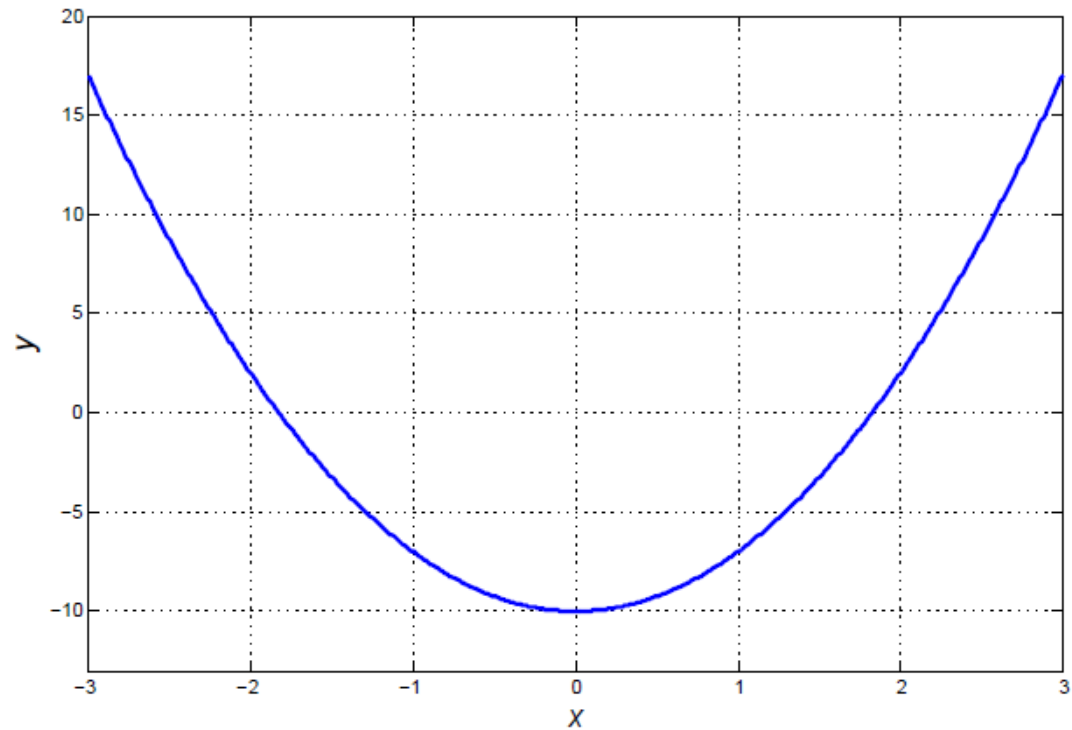
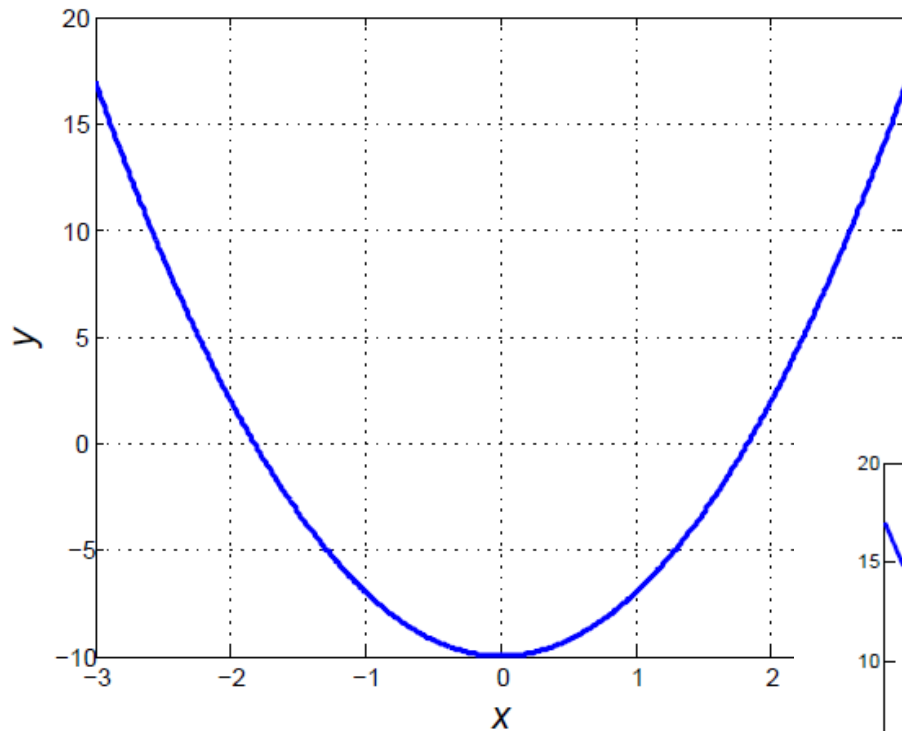


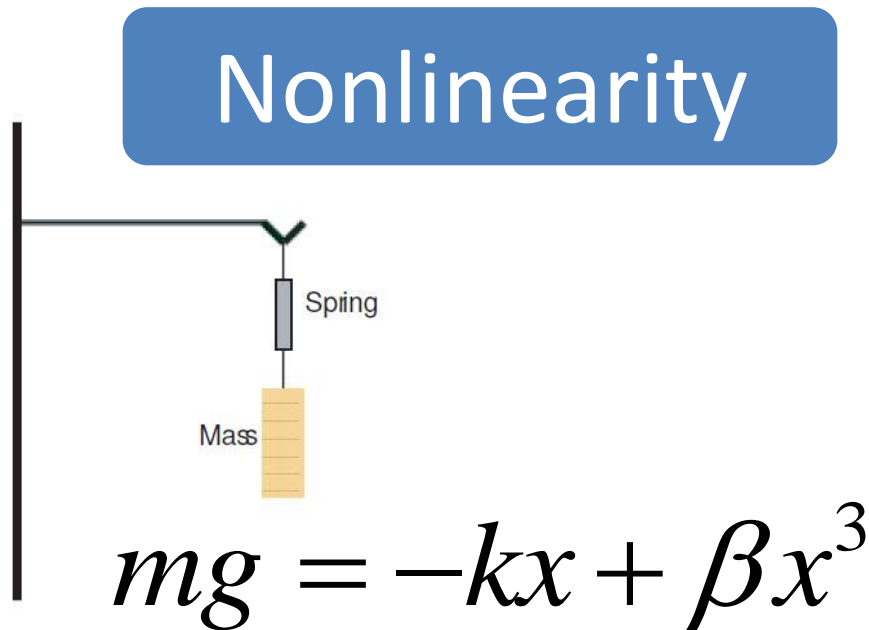
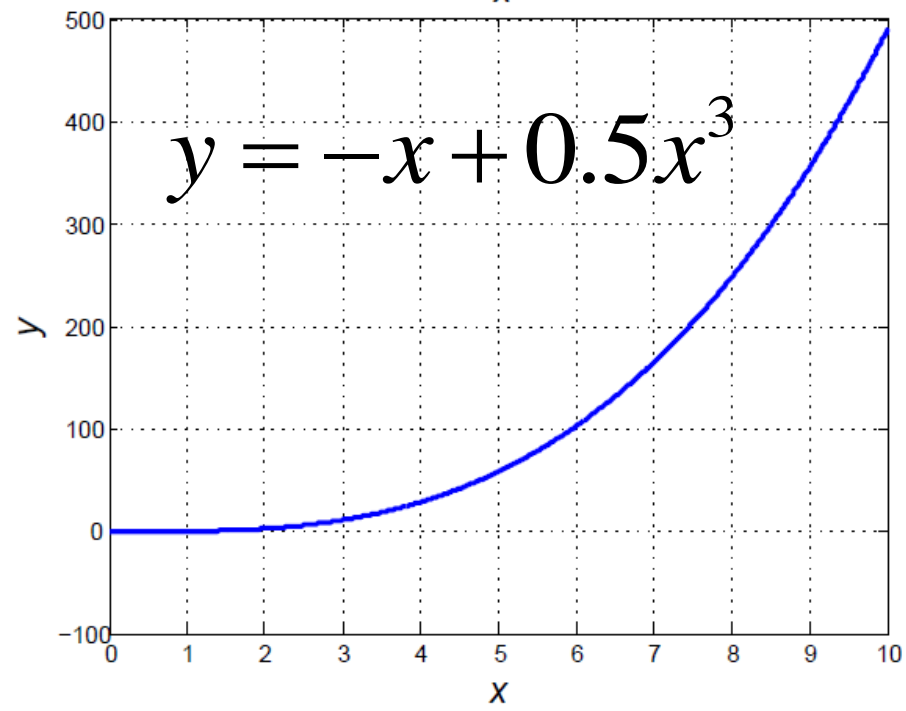
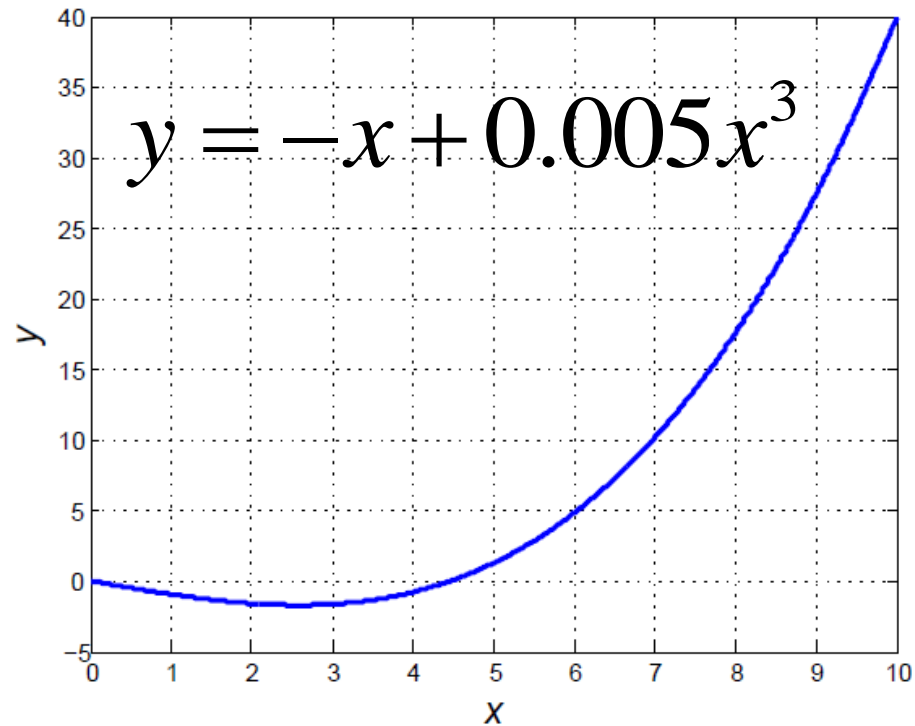
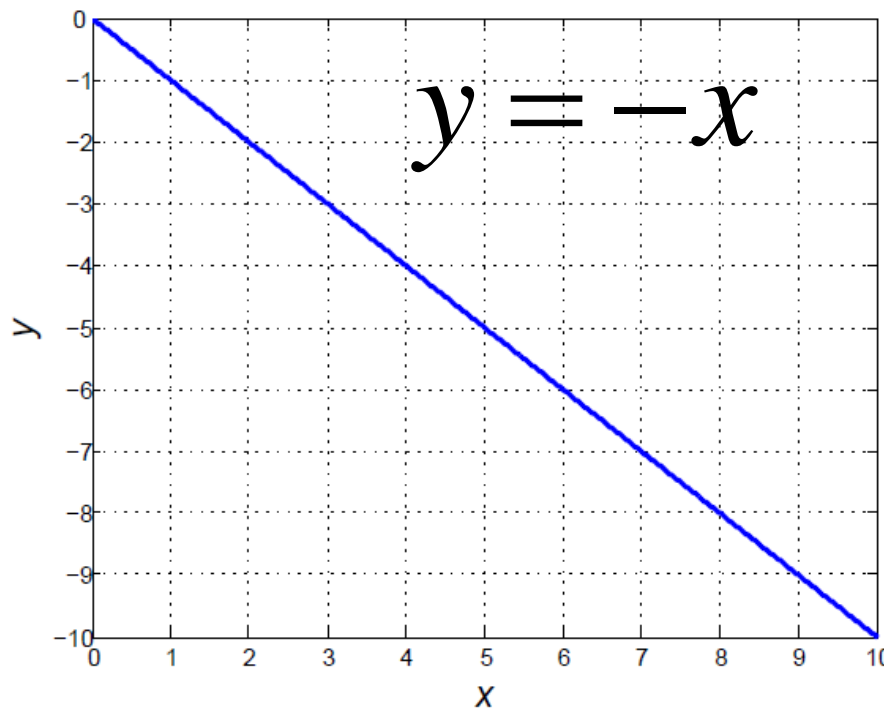
Linear



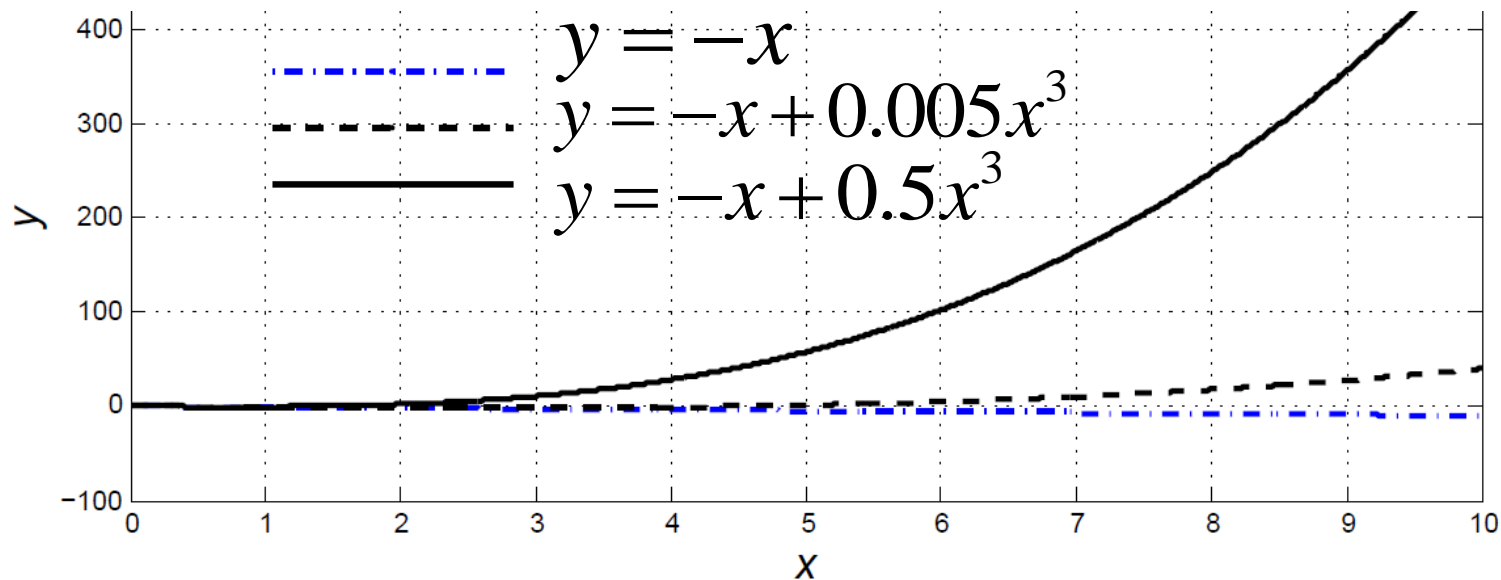
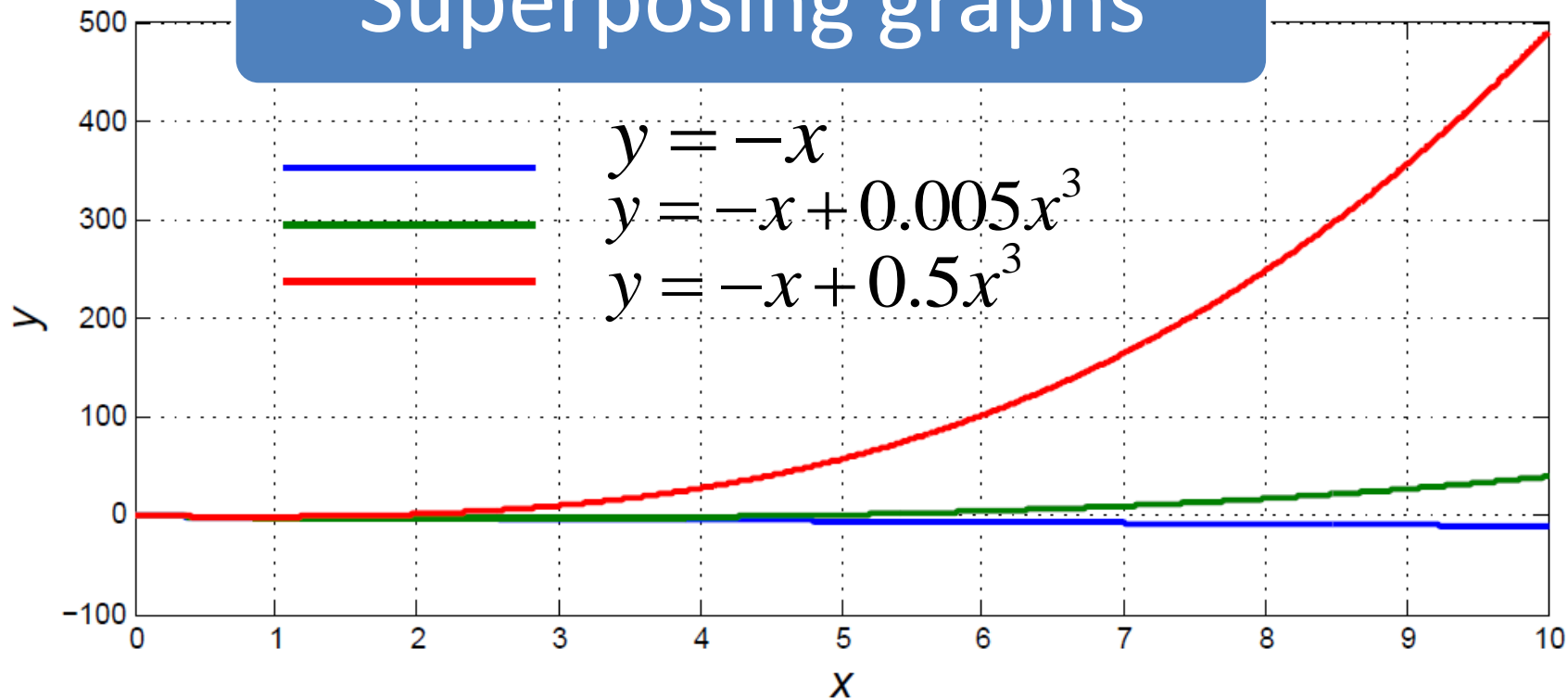
$$y = 3x^2 - 10$$

Quadratic



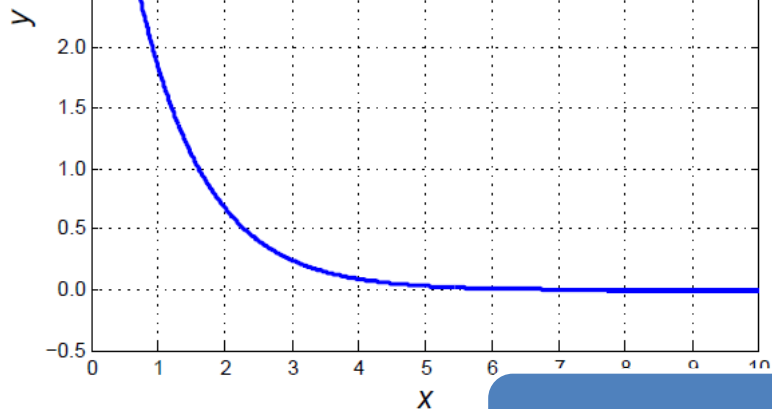


Superposing graphs

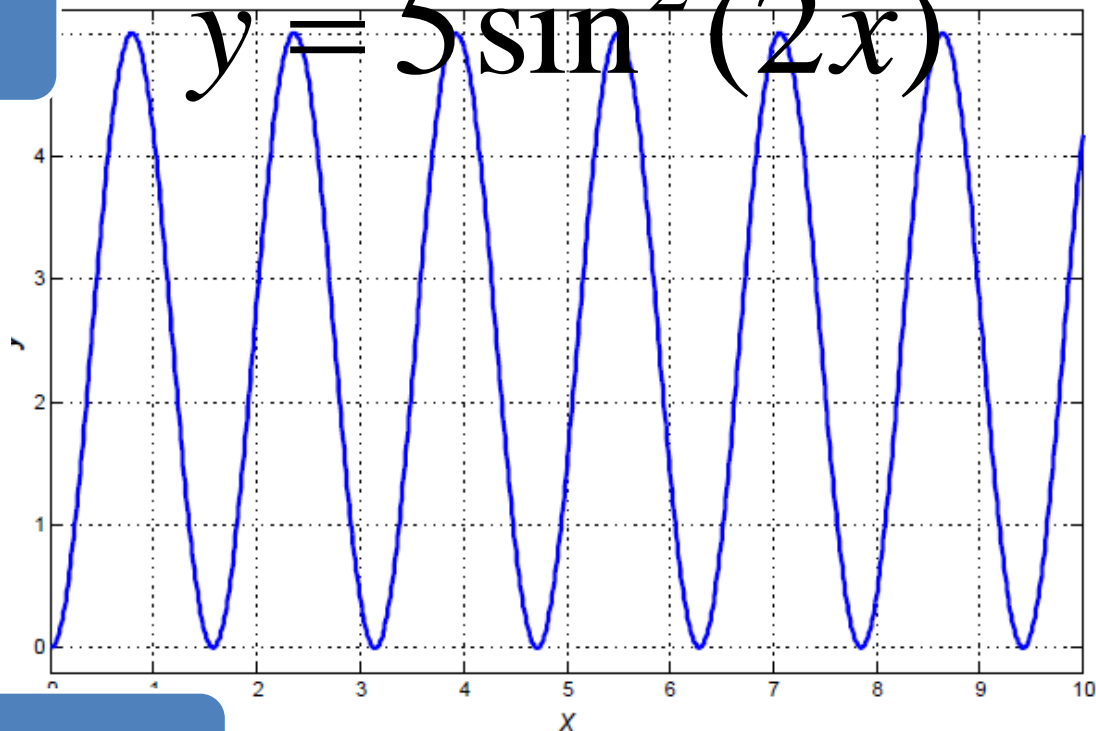


Exponentials

$$y = 5e^{-x}$$

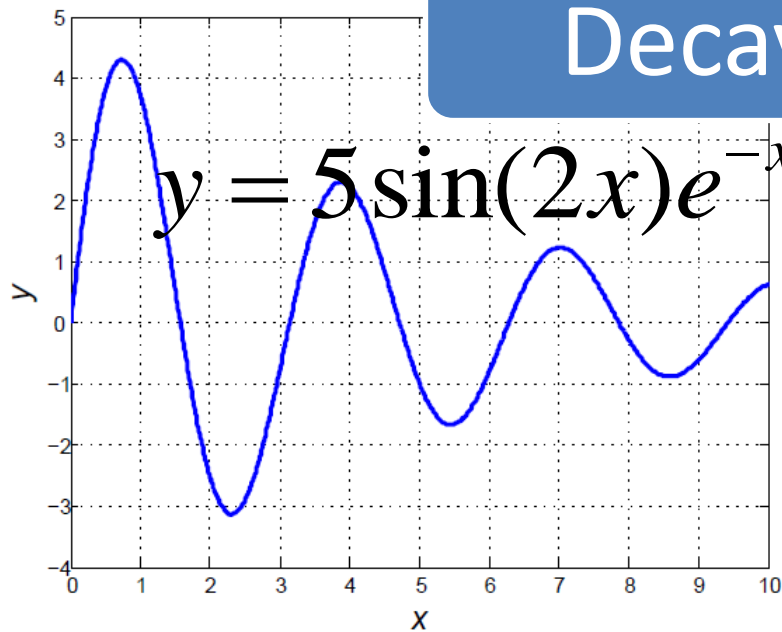


$$y = 5\sin^2(2x)$$

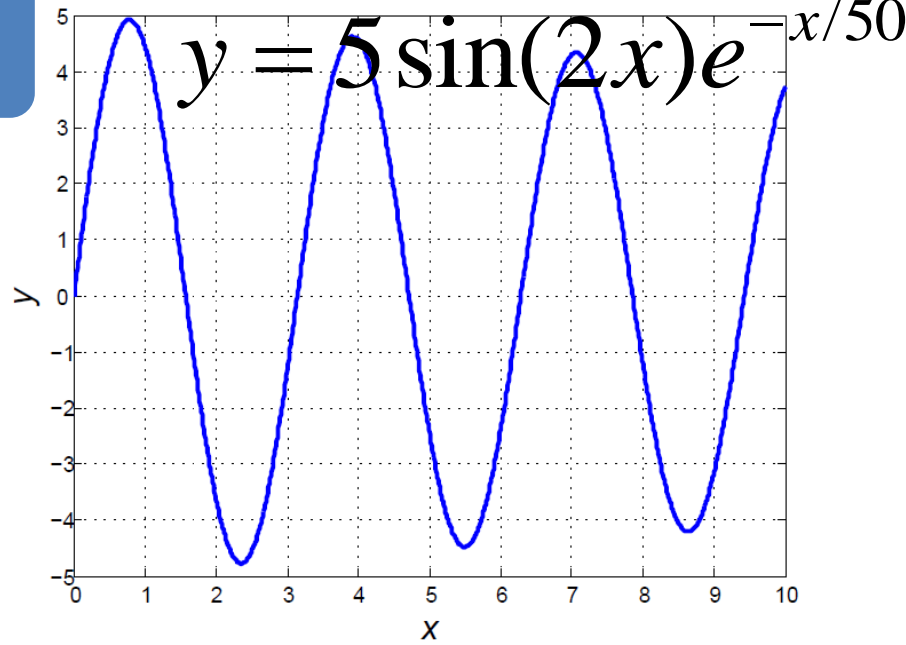


Decay

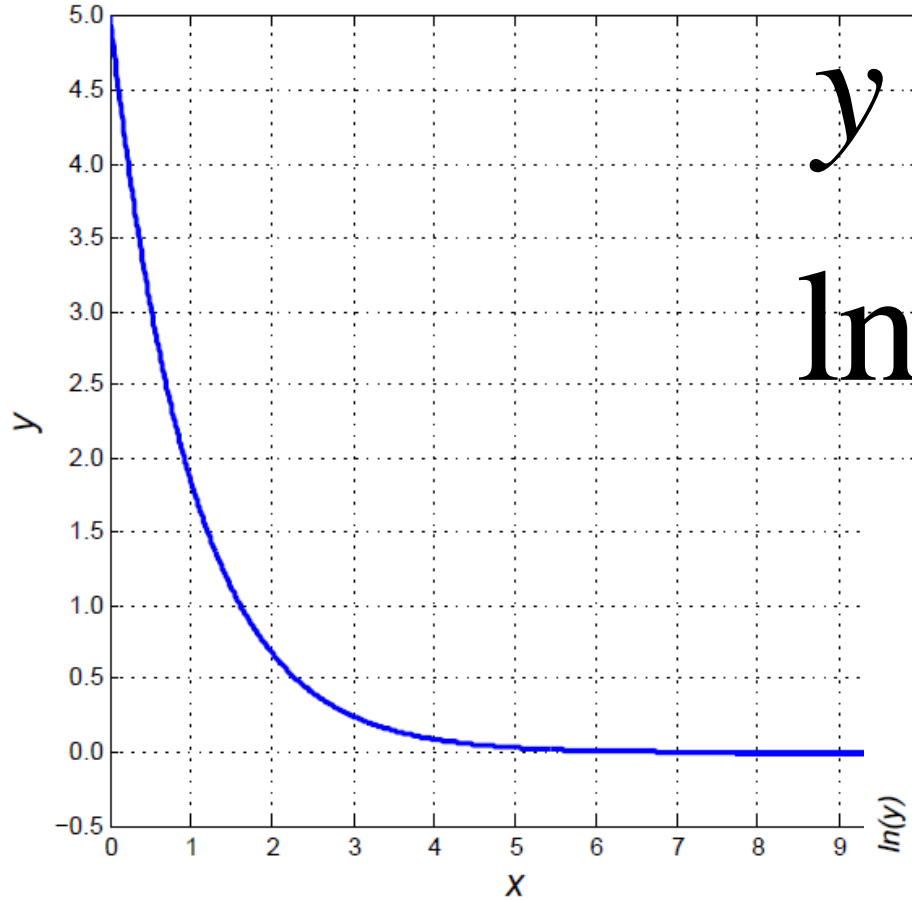
$$y = 5\sin(2x)e^{-x/5}$$



$$y = 5\sin(2x)e^{-x/50}$$

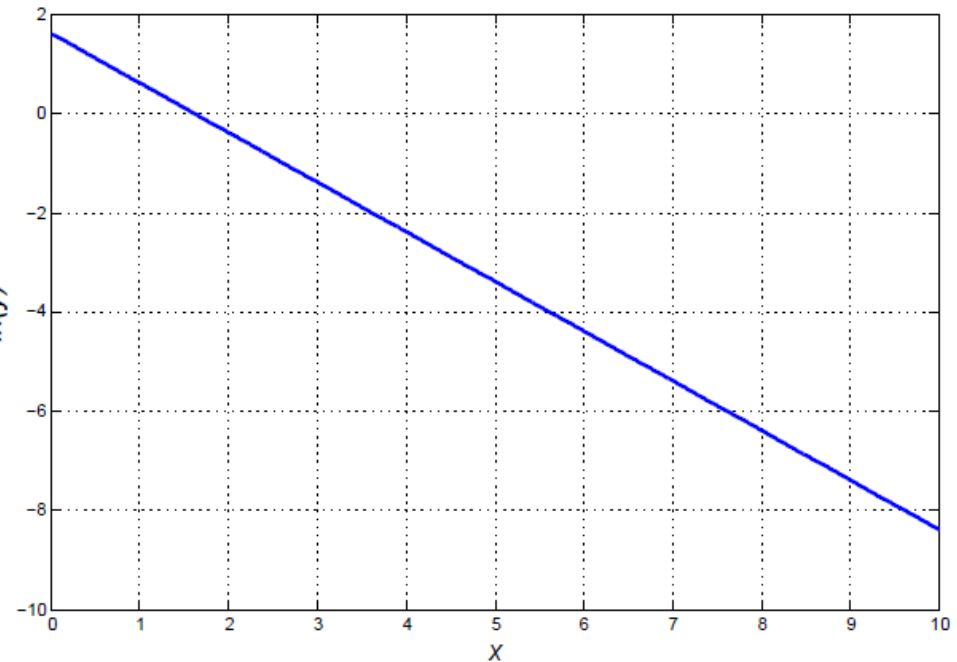


Linearization



$$y = 5e^{-x}$$

$$\ln(y) = \ln(5) - x$$

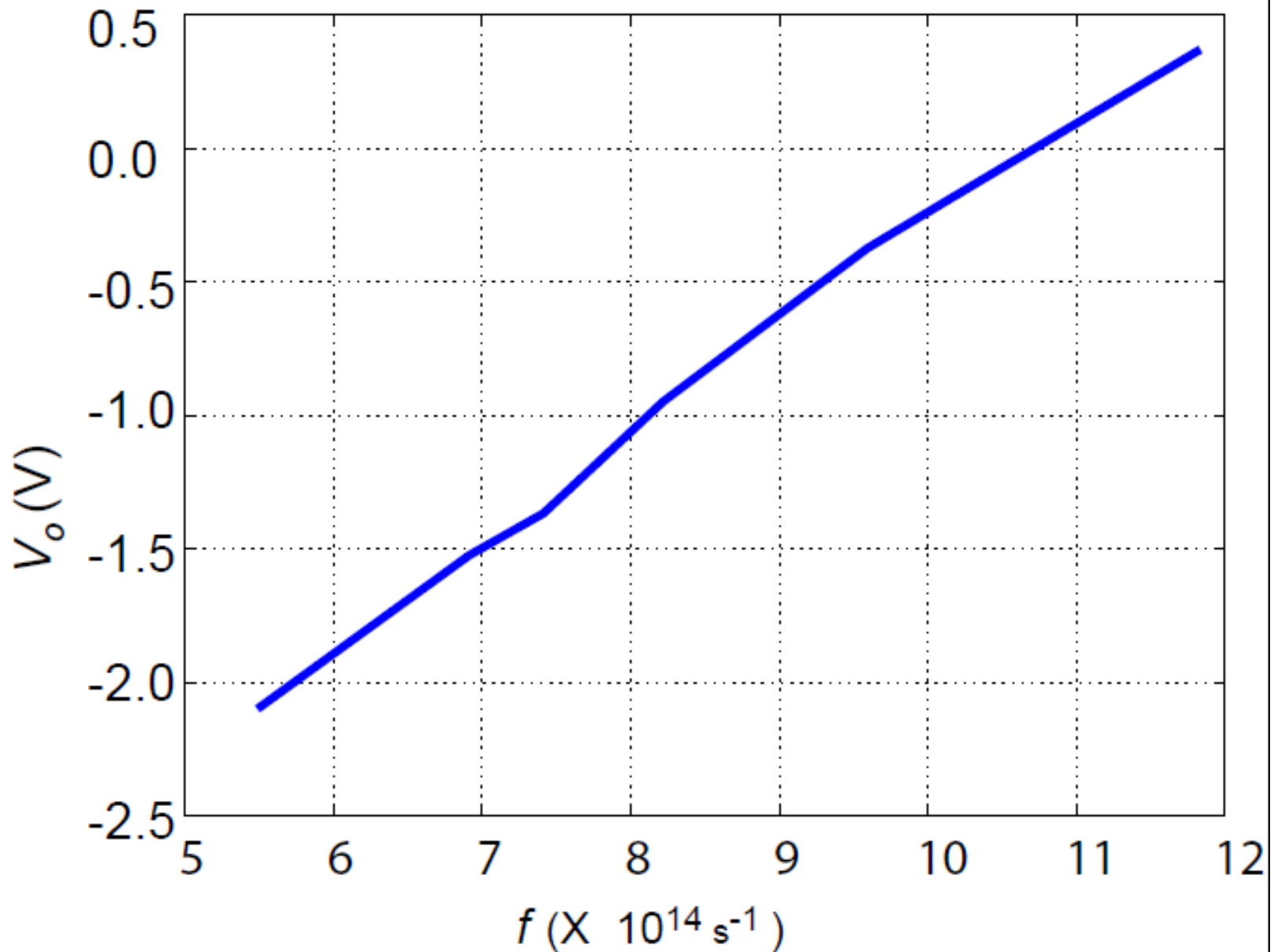


Plotting Experimental Data

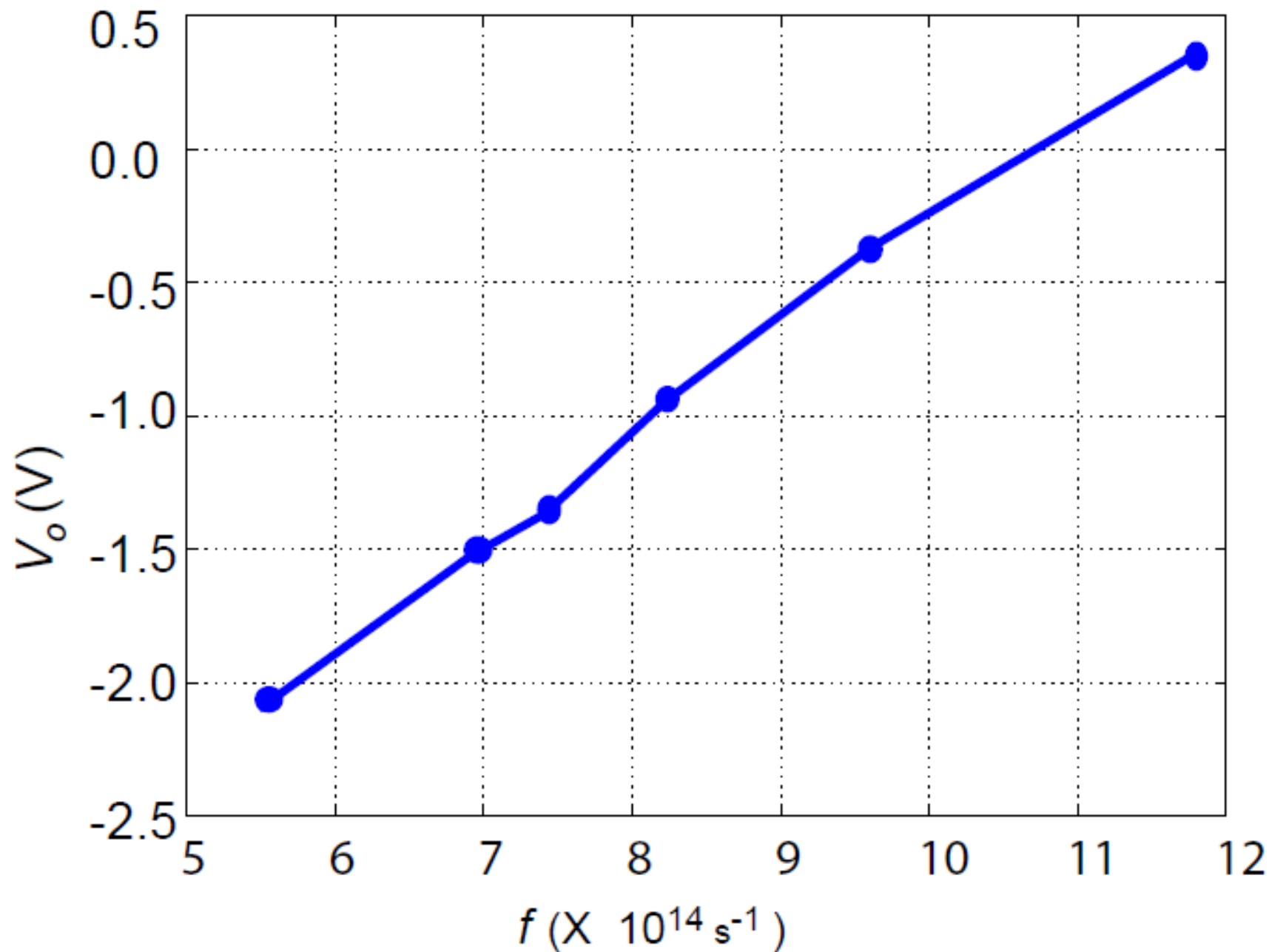
Stopping voltage V_o (V)	Wavelength λ (Å)	Frequency $f = c / \lambda$ ($\times 10^{14} \text{ s}^{-1}$)
-2.100	5466	5.488
-1.524	4339	6.914
-1.367	4047	7.413
-0.9478	3650	8.219
-0.3718	3126	9.597
+0.3720	2535	11.834

Possible Ways of Plotting

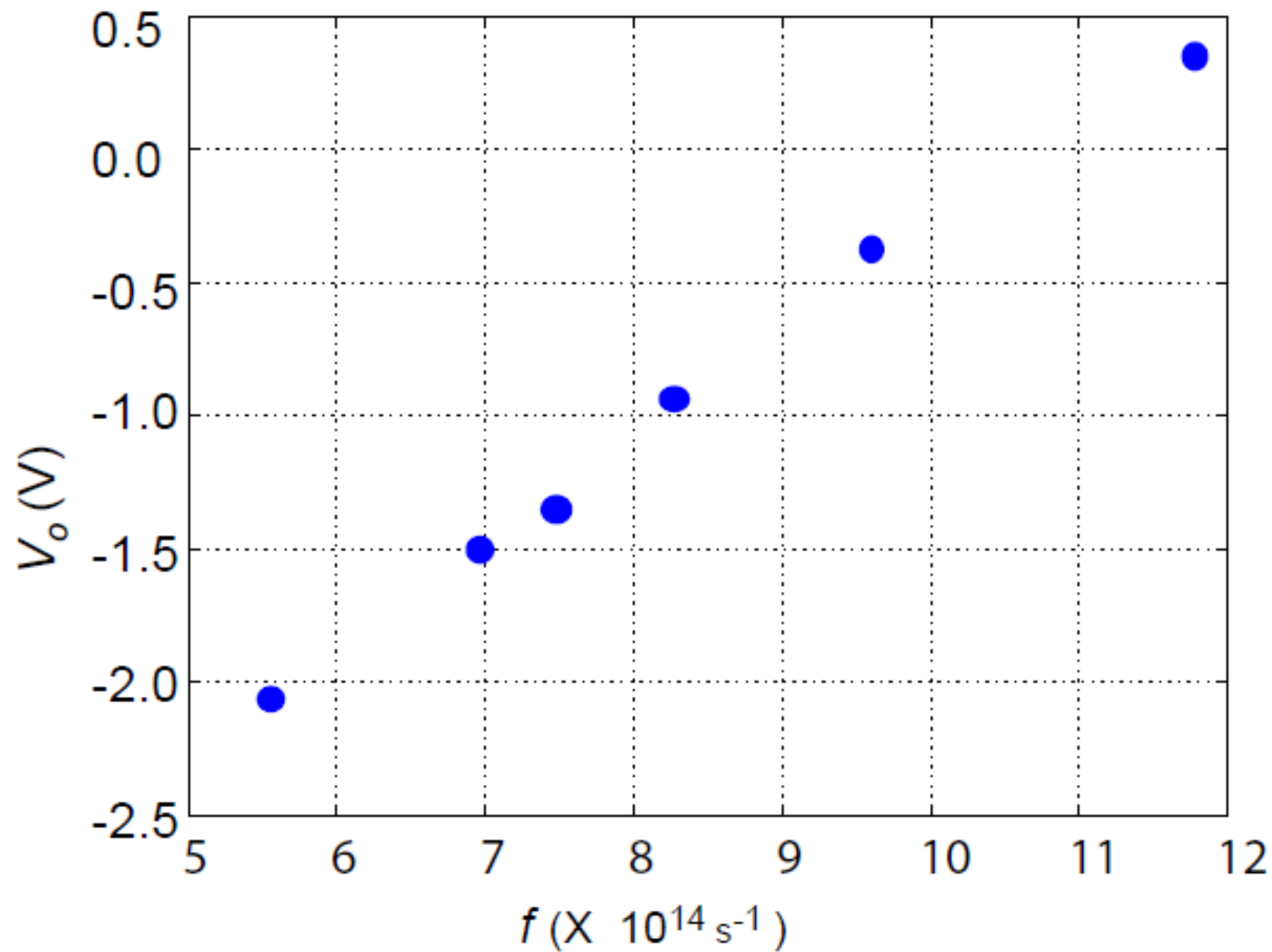
(a) Not acceptable



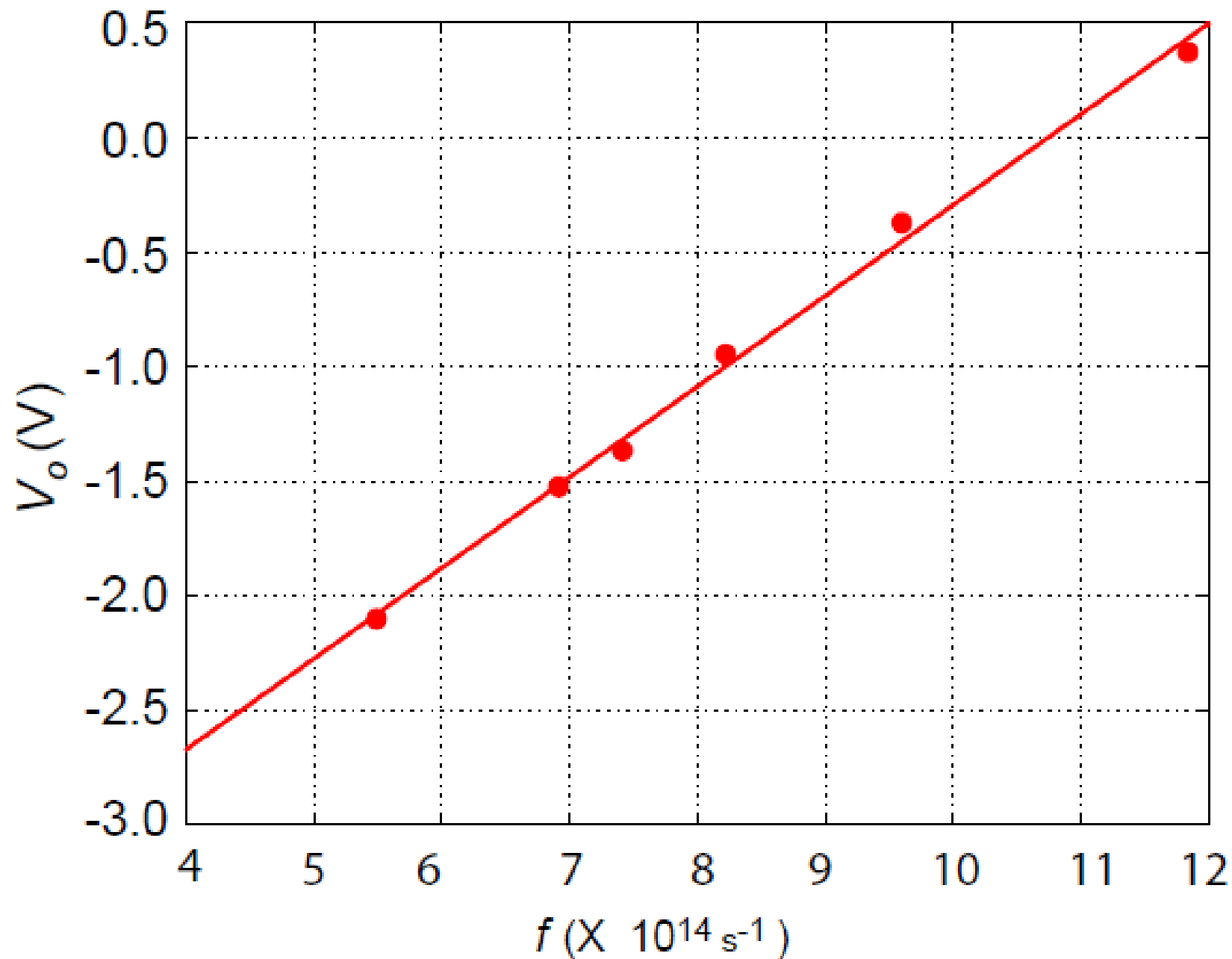
(b) Barely acceptable

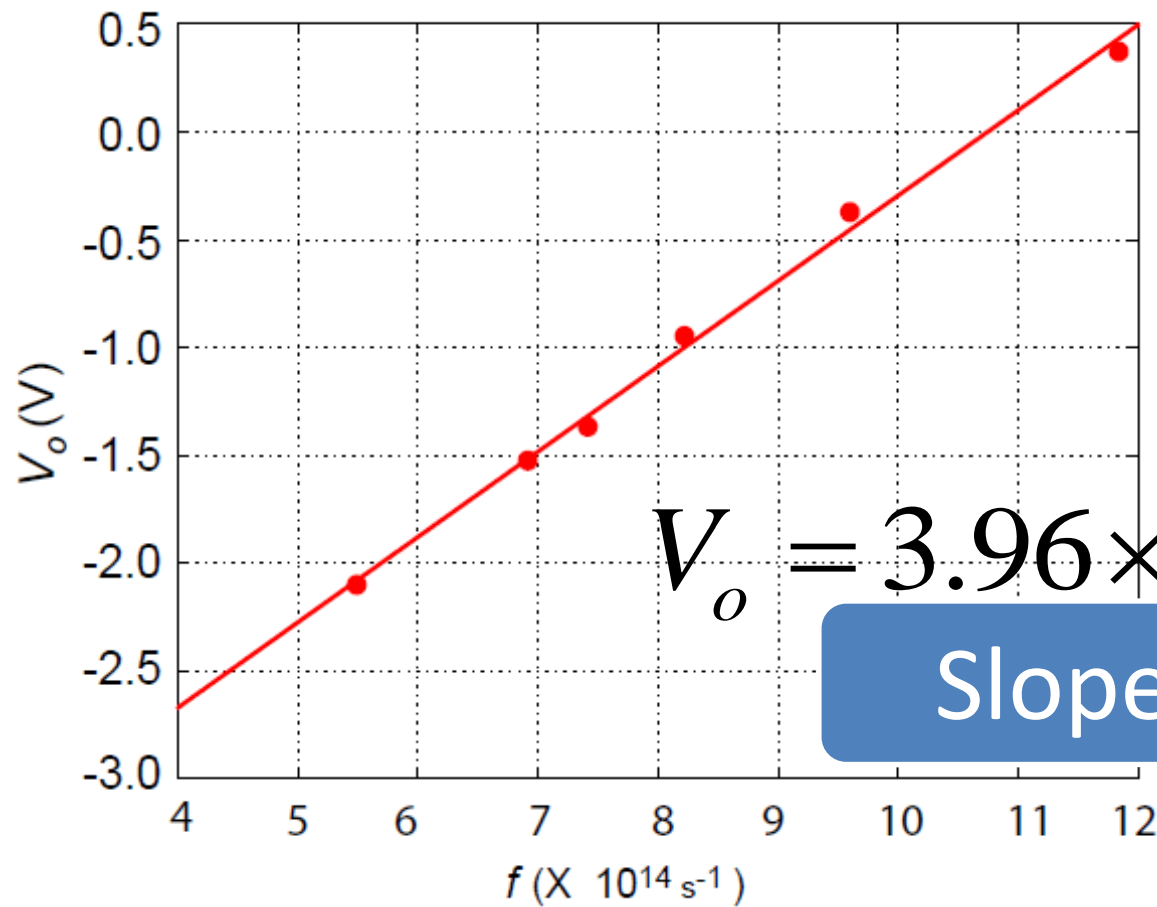


(c) Better



(d) Acceptable, good in all respects





$$V_o = \frac{h}{e} f - \frac{W}{e}$$

$$V_o = 3.96 \times 10^{-15} f - 4.25$$

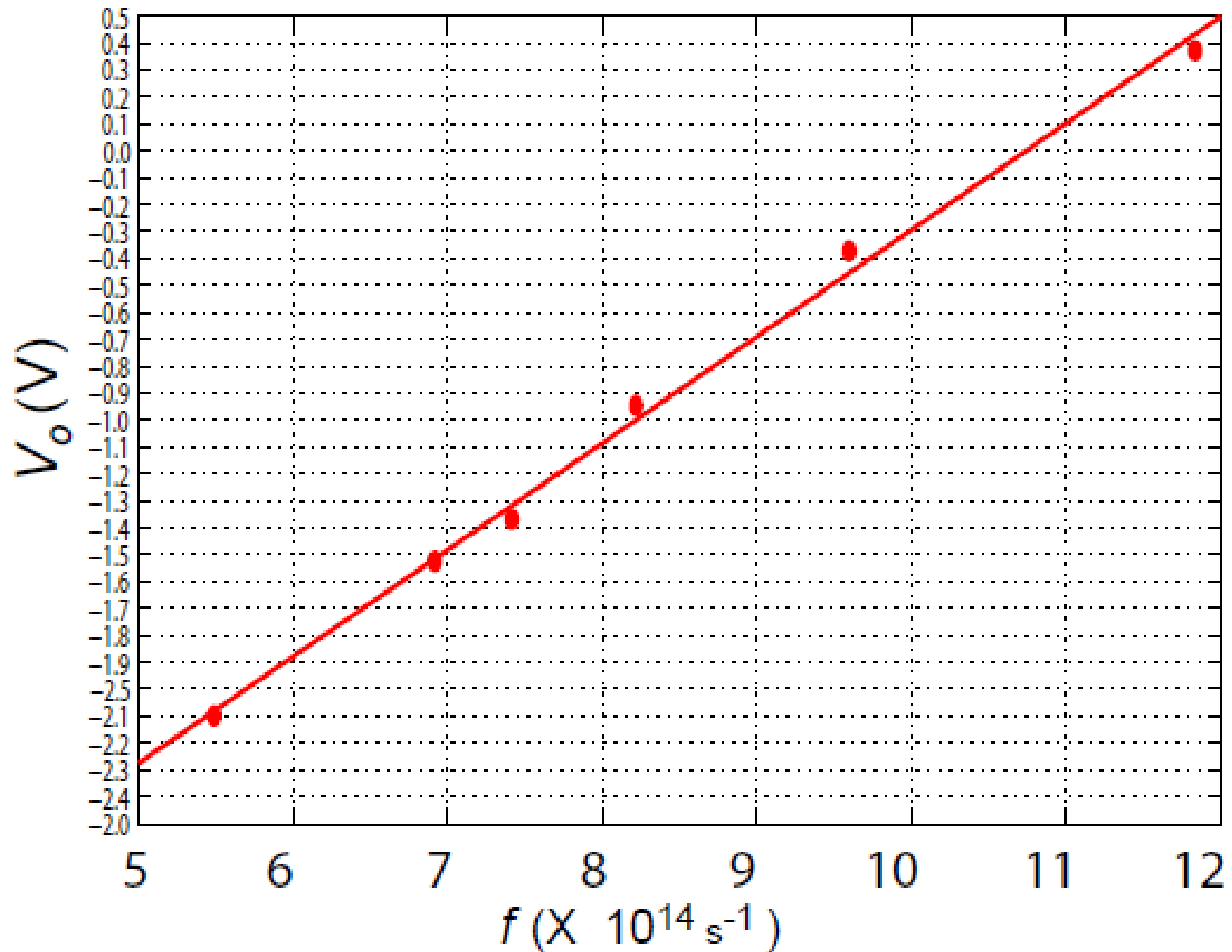
Slope

Intercept

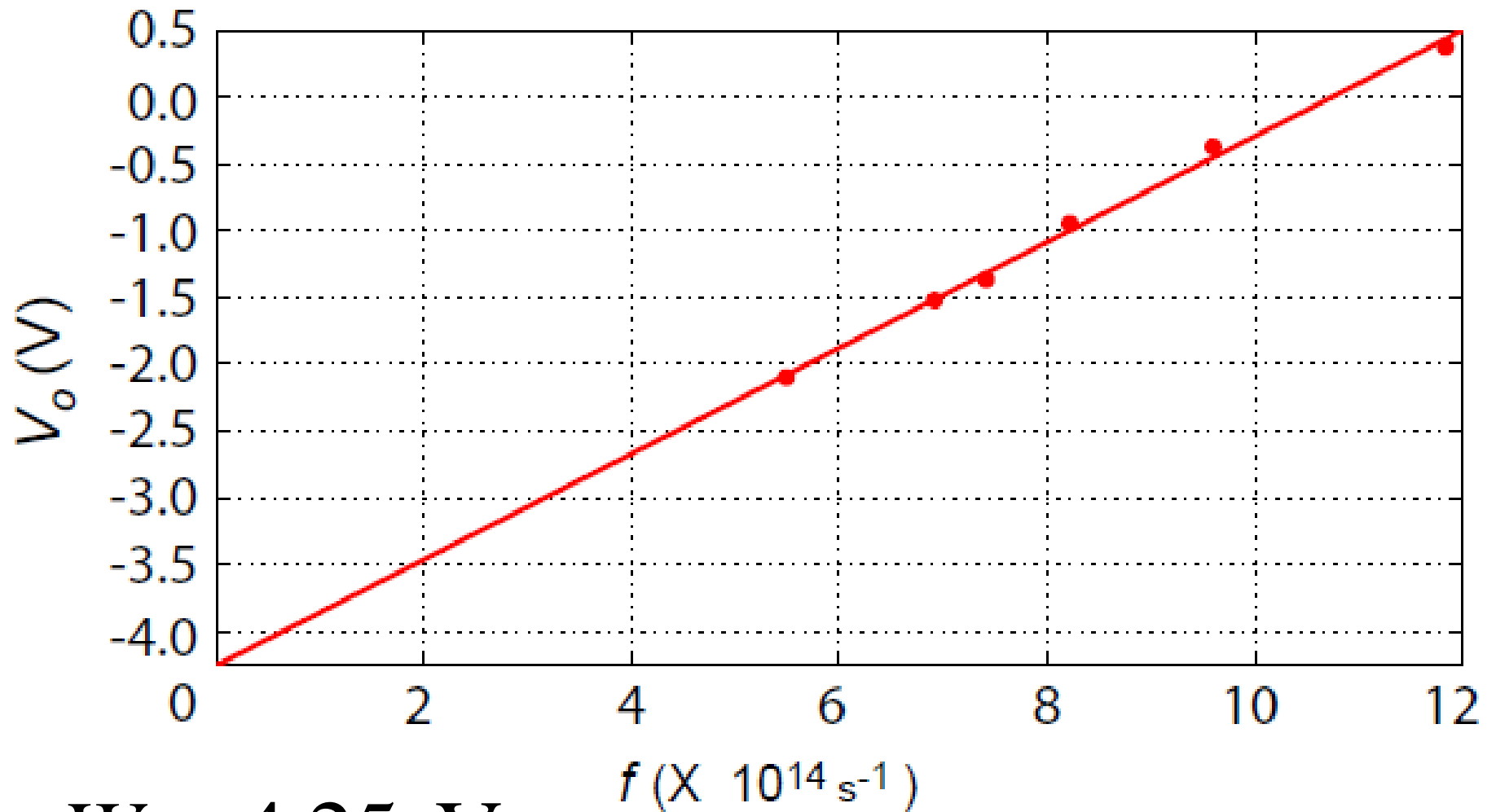
$$h = 6.34 \times 10^{-34} \text{ Js}$$

$$W = 4.25 \text{ eV}$$

(e) Unnecessary detail or embellishment

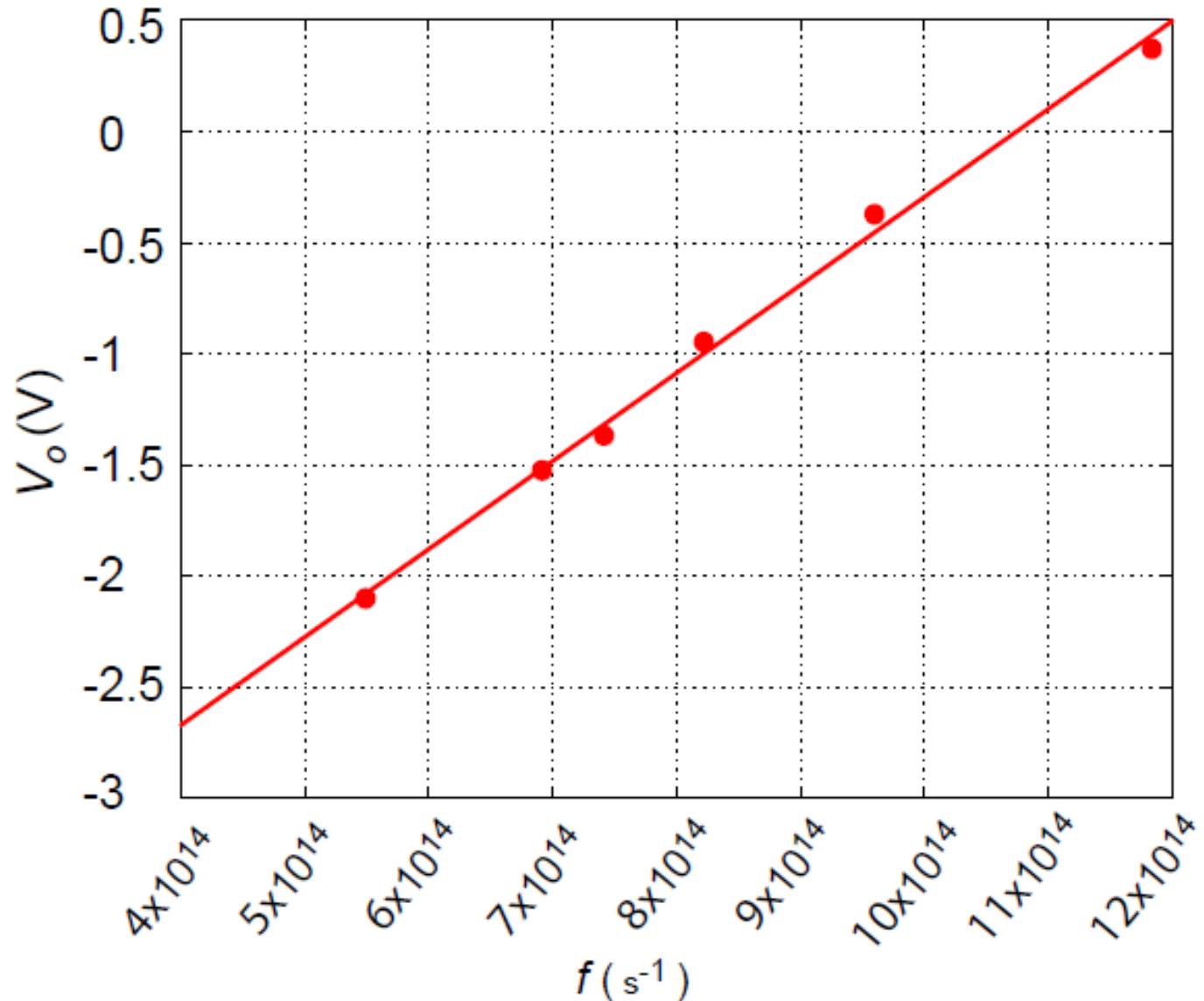


(f) Axes too long

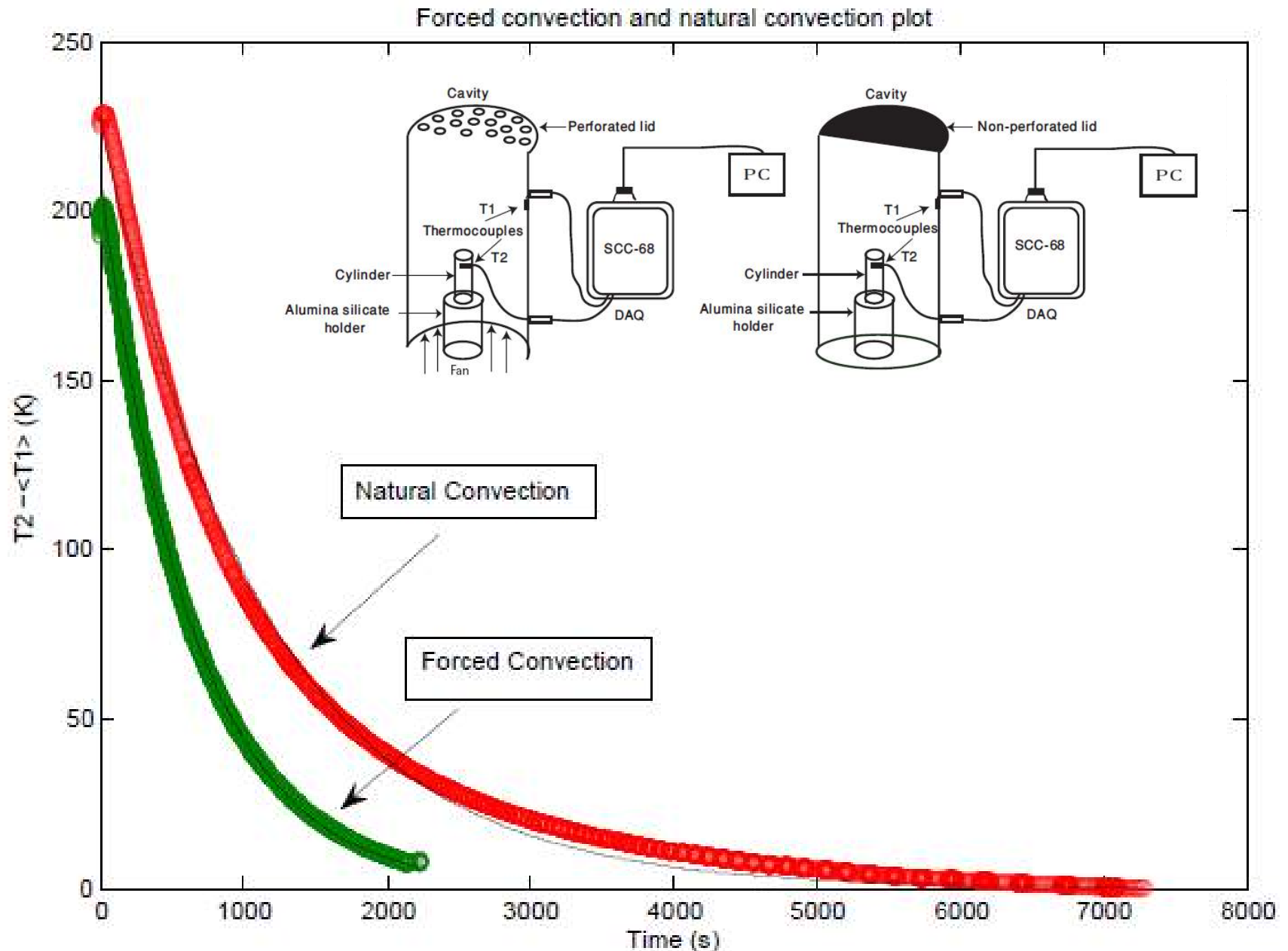


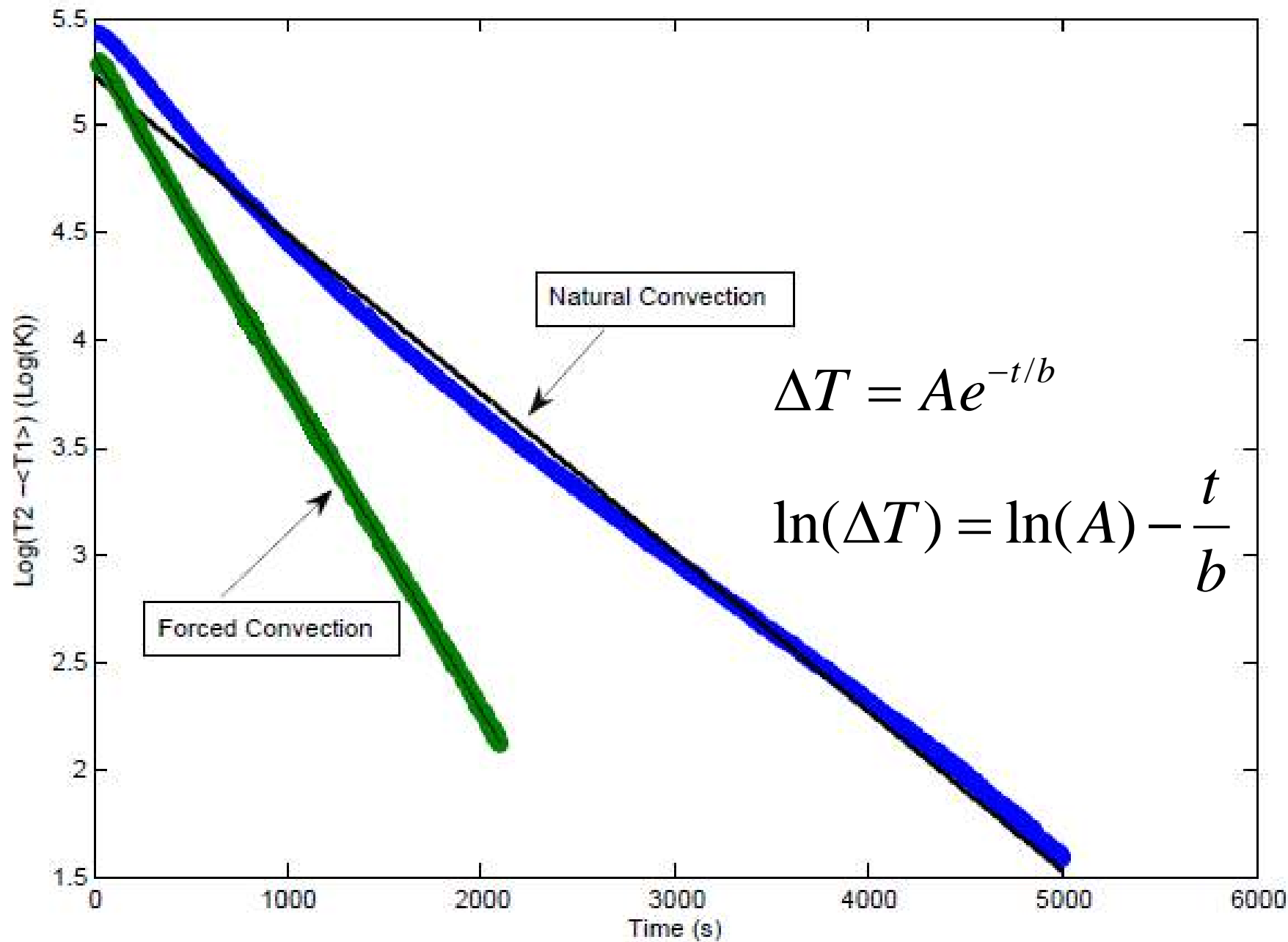
$$W = 4.25 \text{ eV}$$

(f) Axes tick marks are inconsistent and clumsy

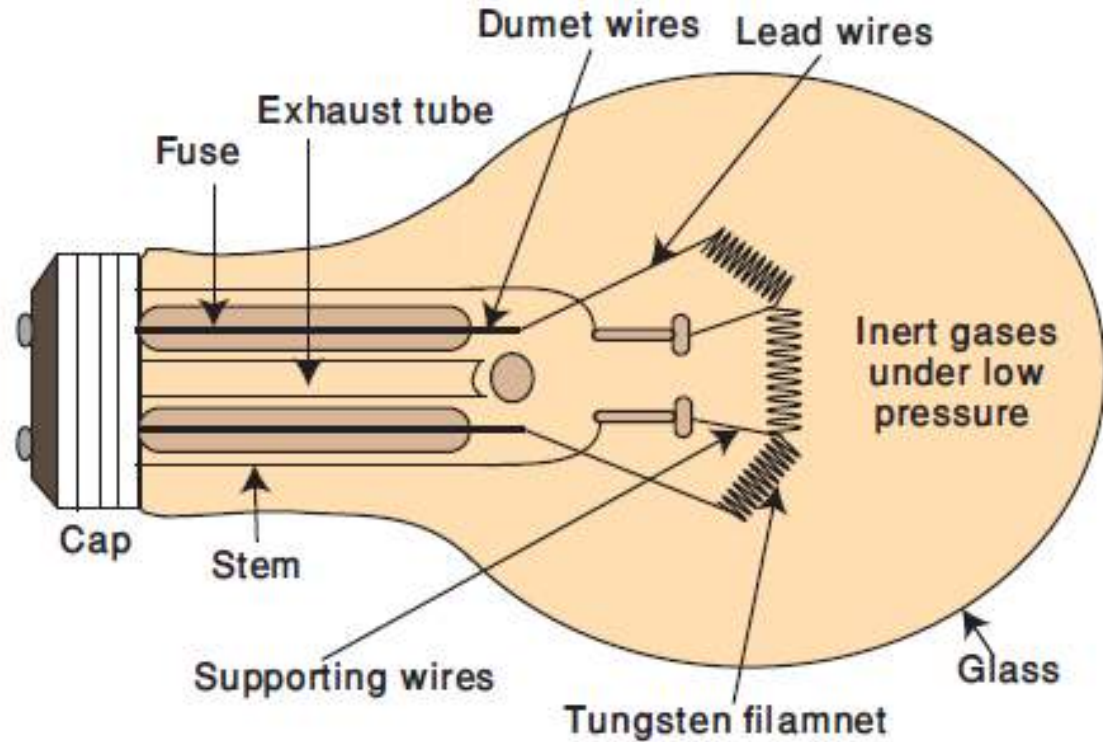


Linearizing Plots: Cooling Objects





Light Bulb (Power Law)



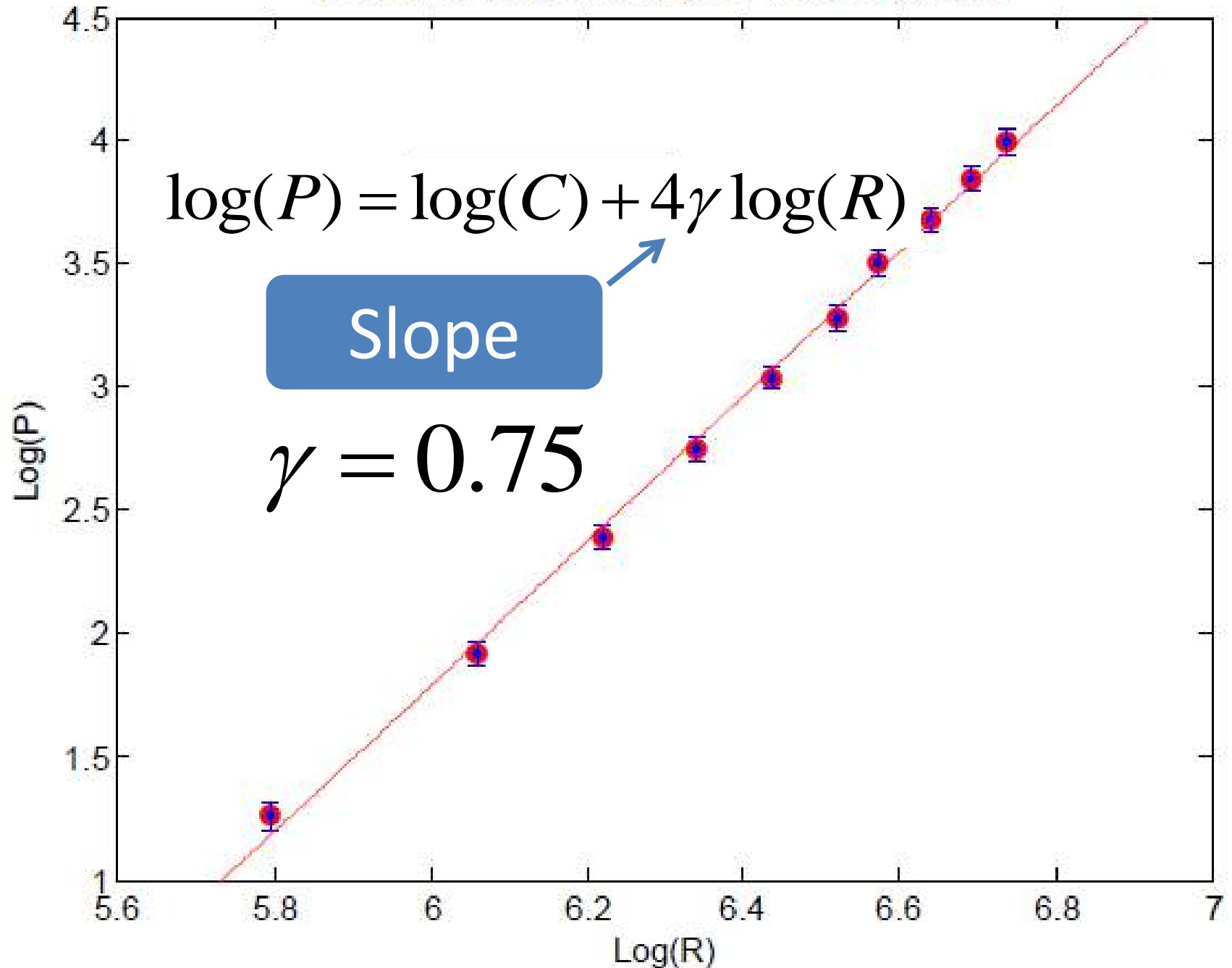
$$P_{\text{elec}} = \sigma AT^4$$

$$T = R^\gamma$$

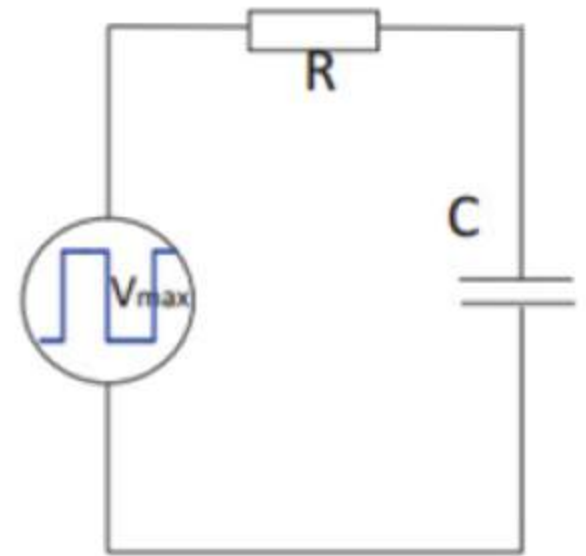
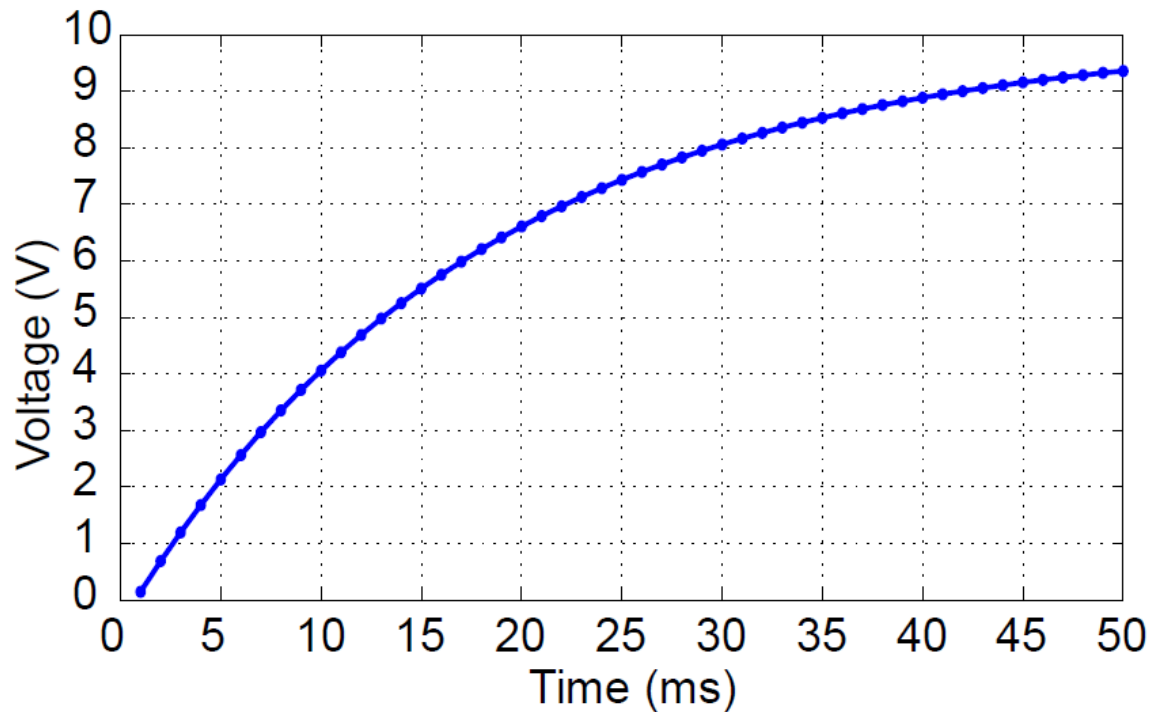
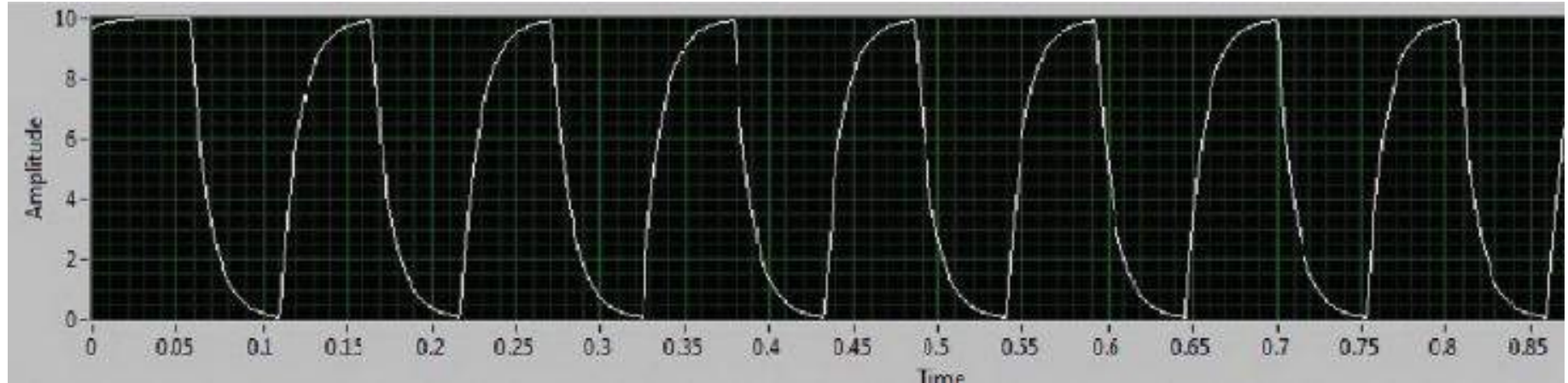
$$P_{\text{elec}} = \sigma AR^{4\gamma} = CR^{4\gamma}$$

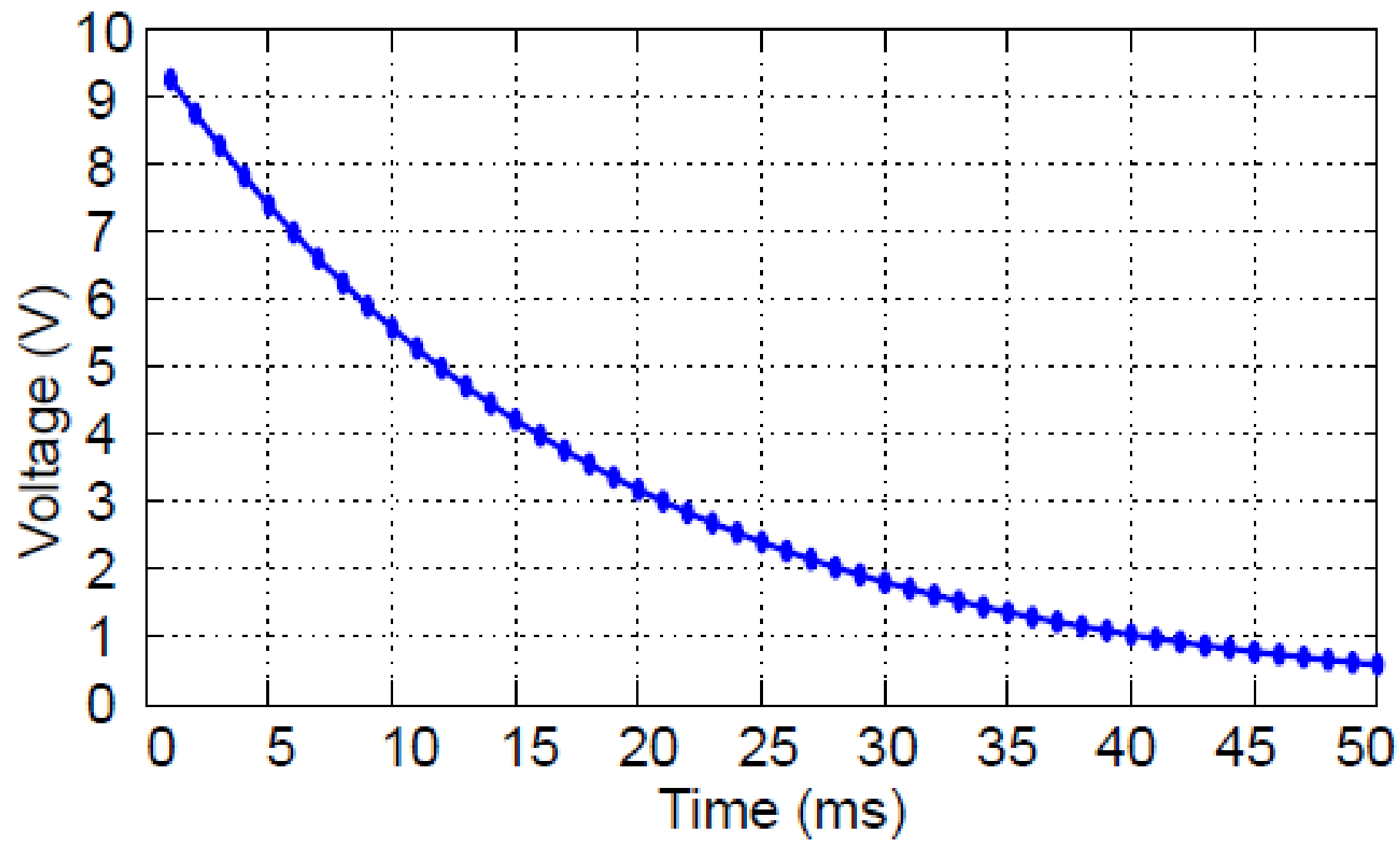
$$\log(P) = \log(C) + 4\gamma \log(R)$$

Logrithmic plot for finding the value of gamma

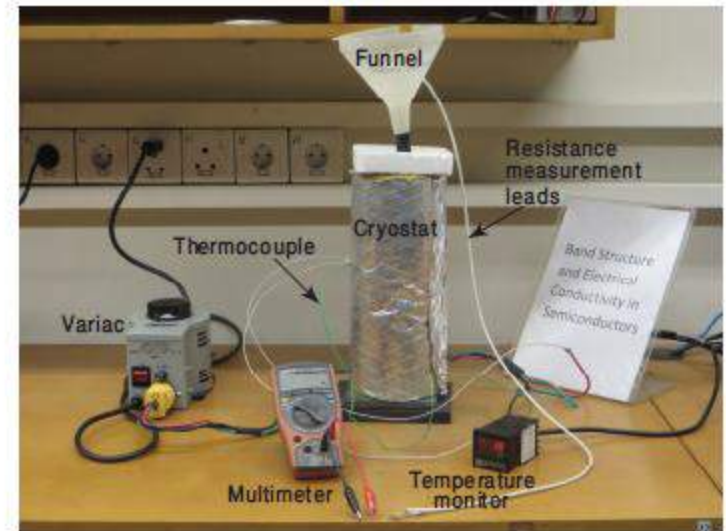
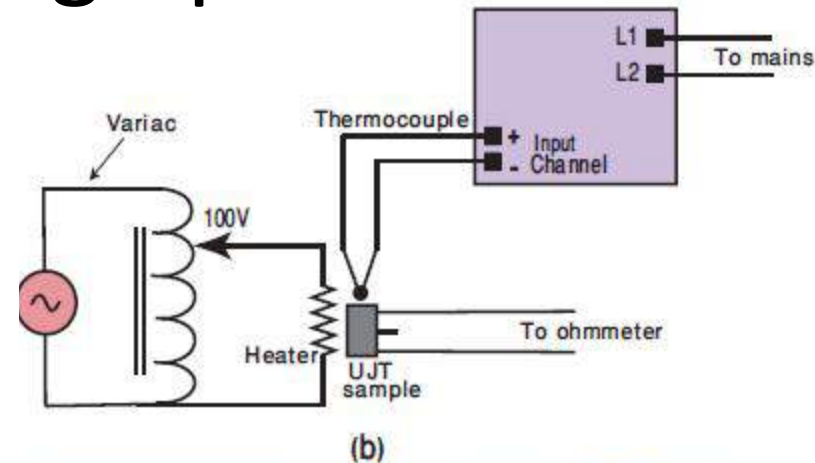
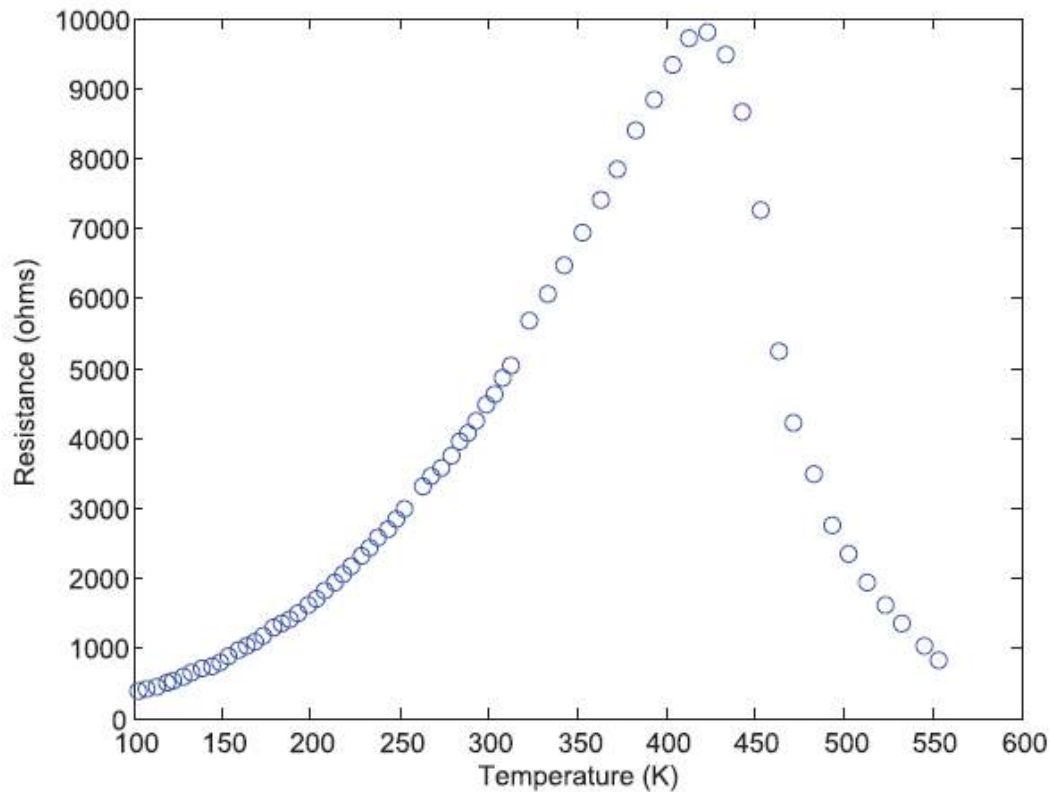


Piecewise graphs (voltage across capacitor)

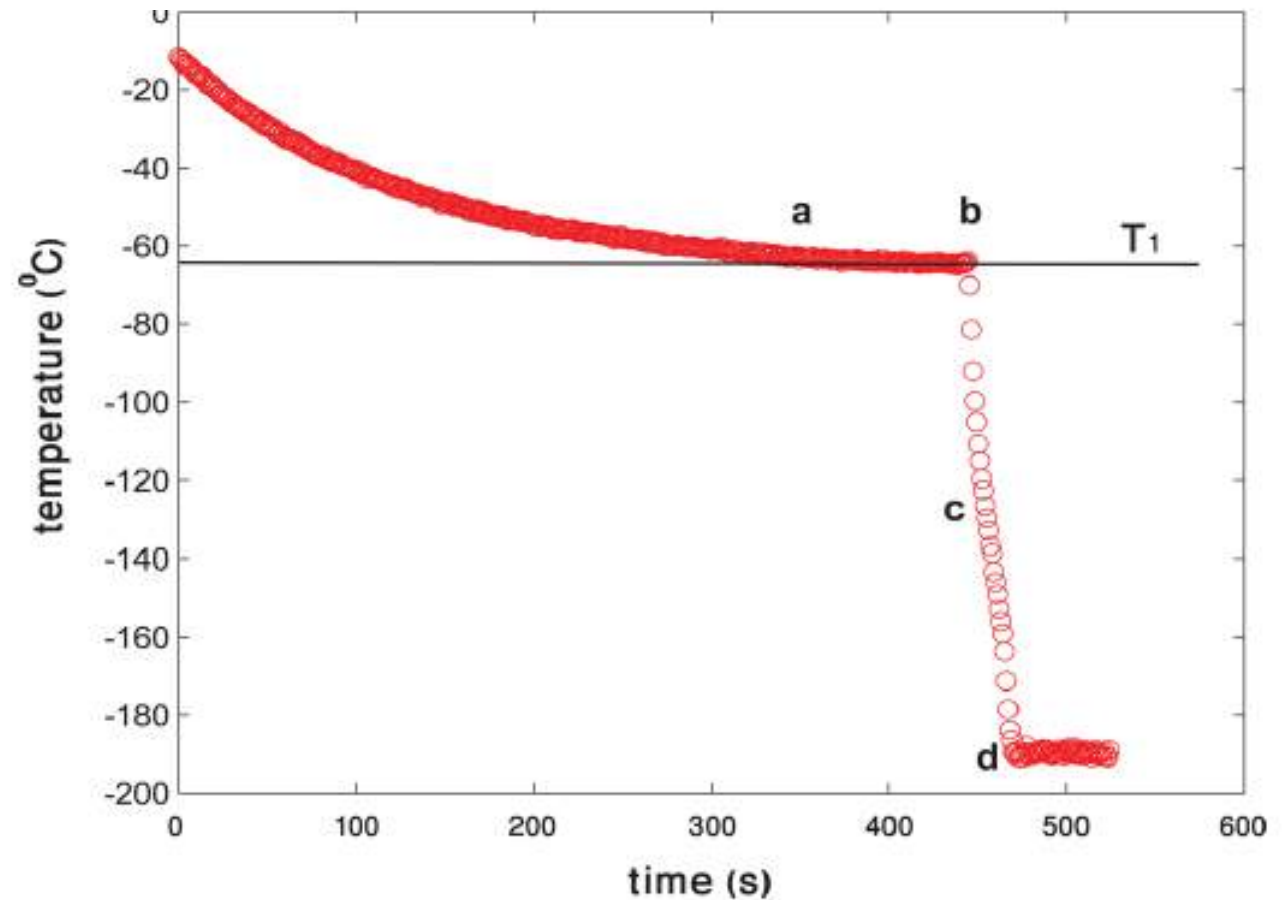
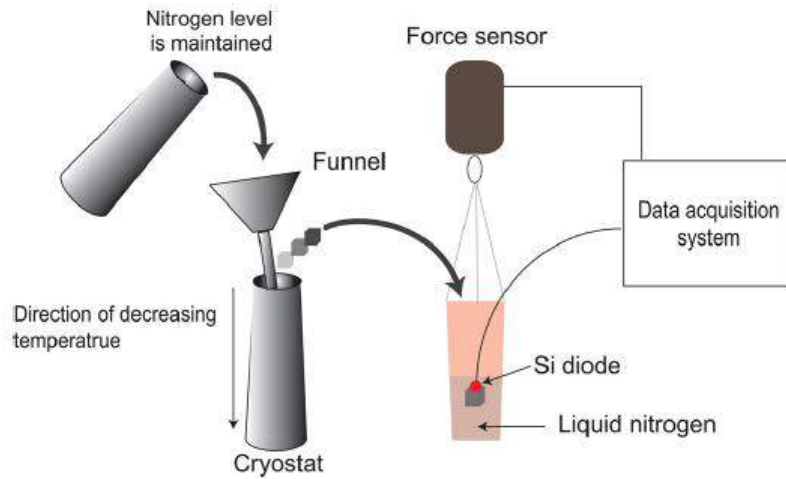




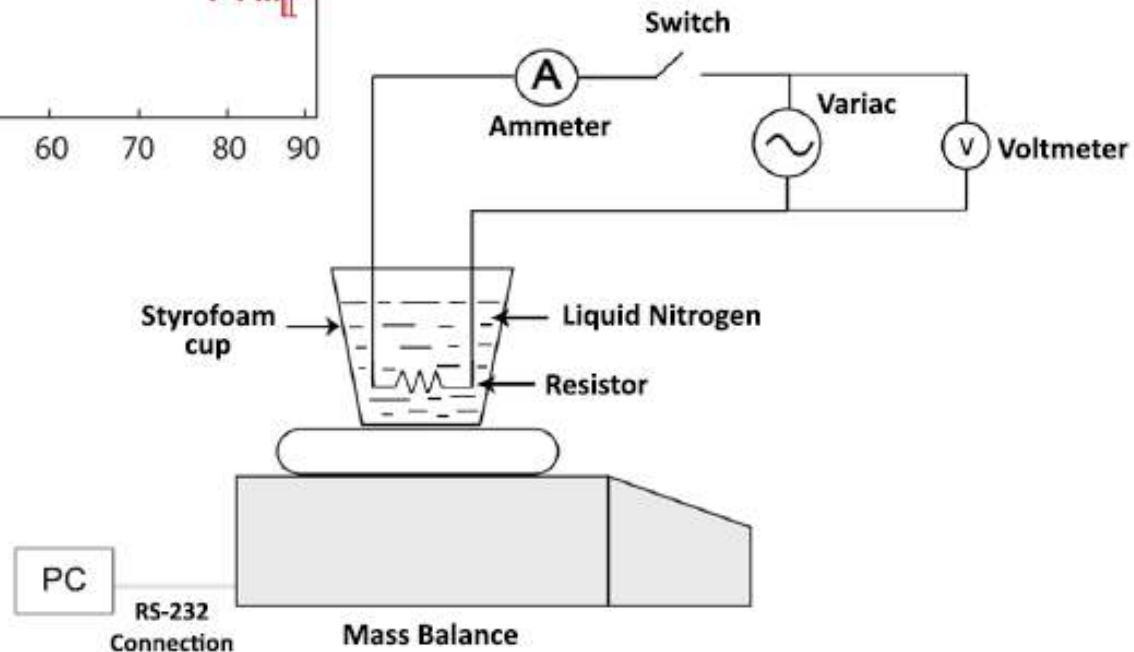
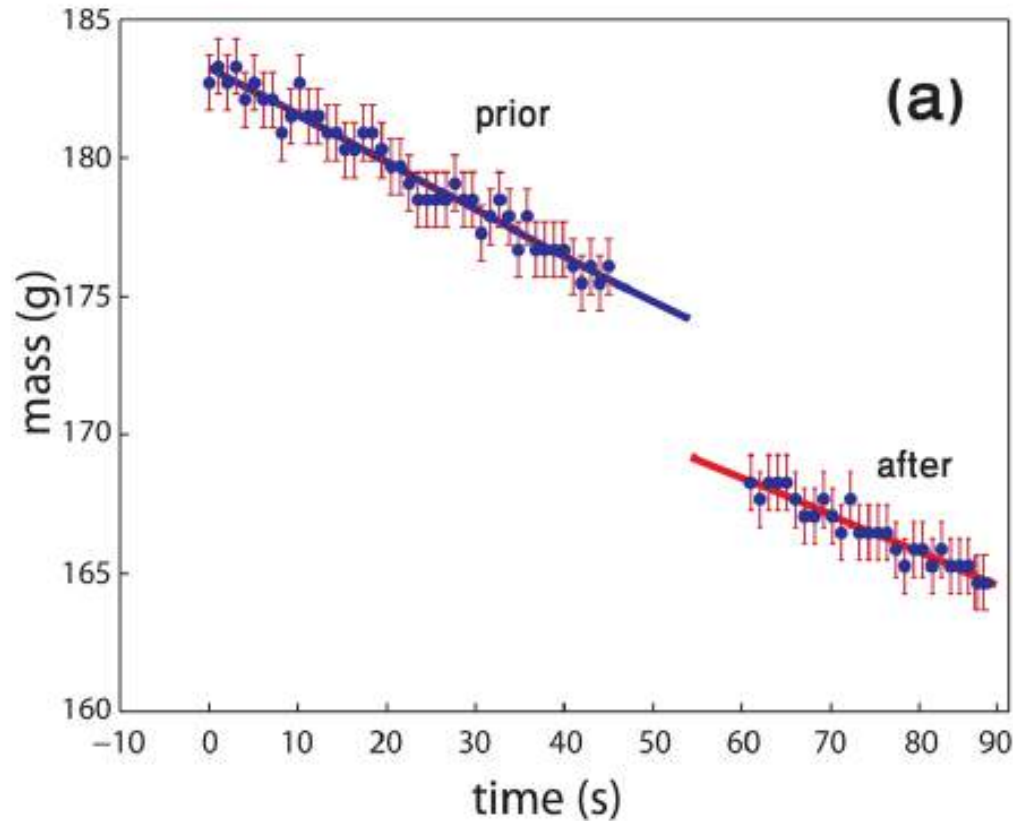
Extracting regimes of diverse behavior from a graph



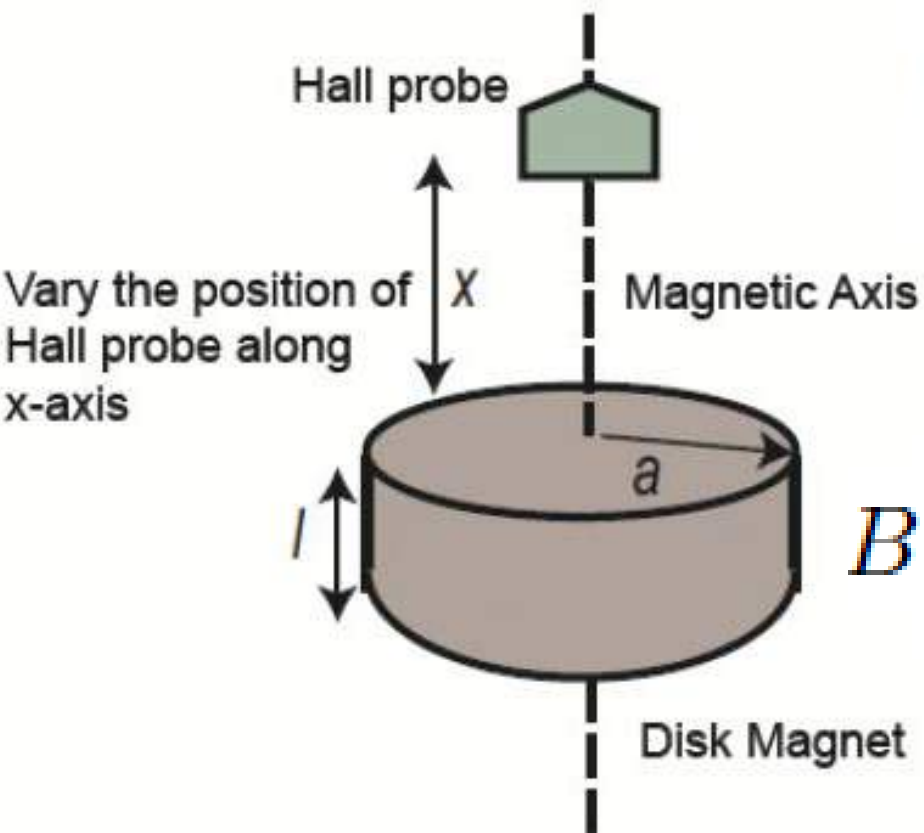
Controlled Discontinuities in experiments (example 1)



Controlled Discontinuities in experiments (example 2)



When does a model breakdown?

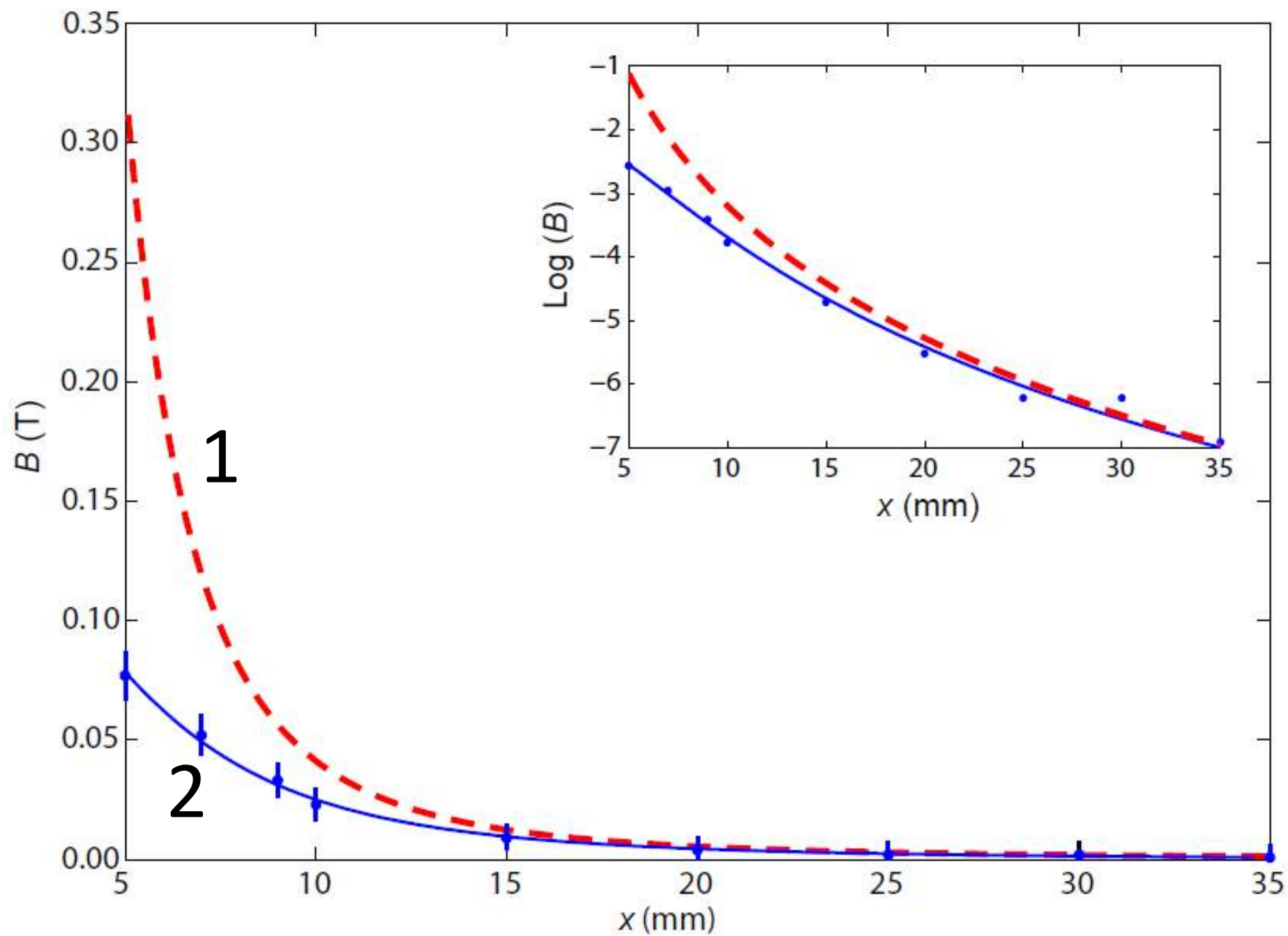


$$B = \frac{\mu_o m}{2\pi x_o^3}$$

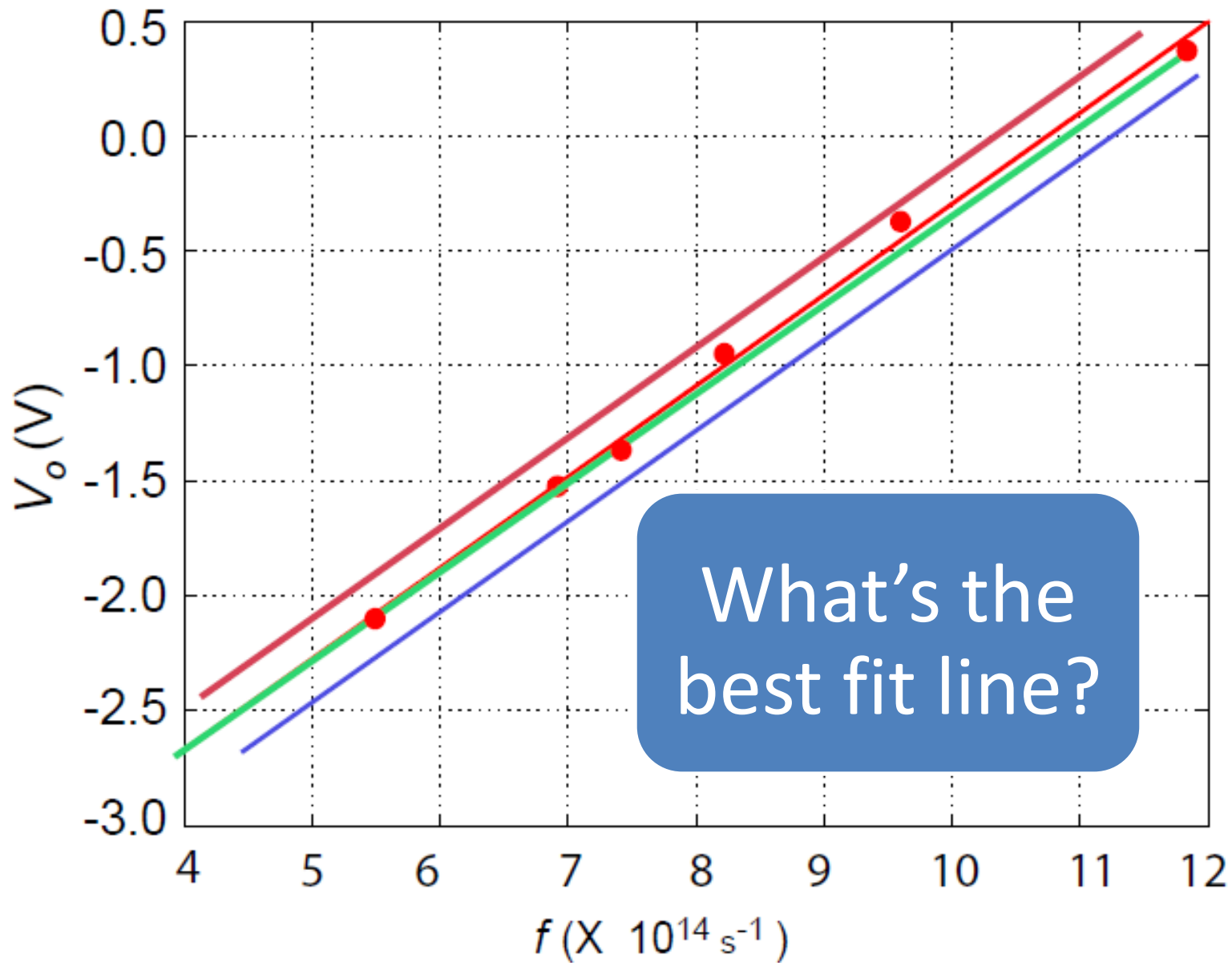
Model 1

$$B = \frac{\mu_o}{2} M \left[\frac{x_o + d/2}{(a^2 + (x_o + d/2)^2)^{1/2}} - \frac{x_o - d/2}{(a^2 + (x_o - d/2)^2)^{1/2}} \right]$$

Model 2



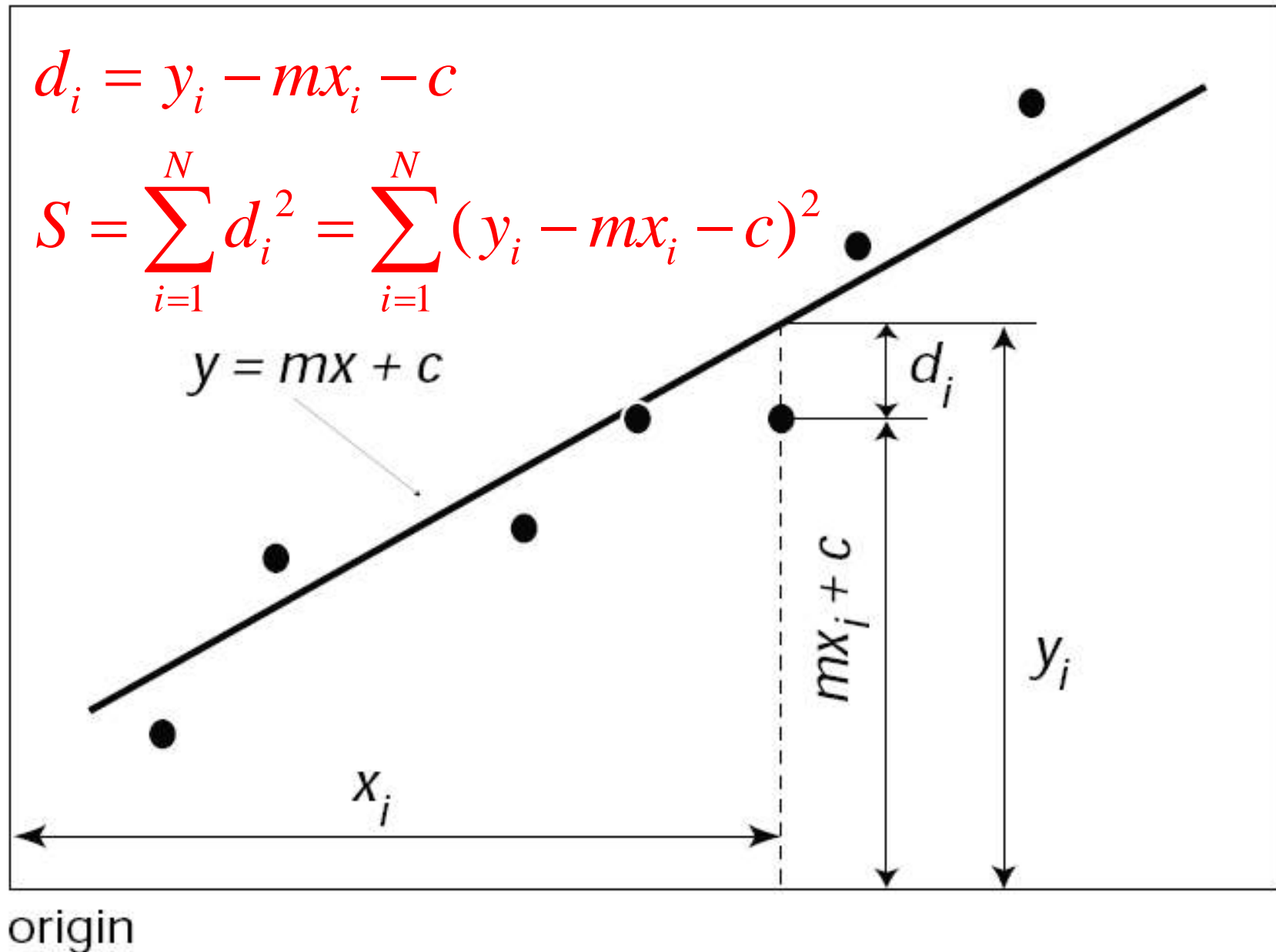
Fitting Experimental Data to a Model



Best fit in the least squares sense

$$d_i = y_i - mx_i - c$$

$$S = \sum_{i=1}^N d_i^2 = \sum_{i=1}^N (y_i - mx_i - c)^2$$



Least squares curve fitting is minimization of S

$$\frac{\partial S}{\partial m} = -2 \sum [x_i (y_i - mx_i - c)] = 0$$

$$\frac{\partial S}{\partial c} = -2 \sum (y_i - mx_i - c) = 0$$

Minimization

Simultaneous
Equations

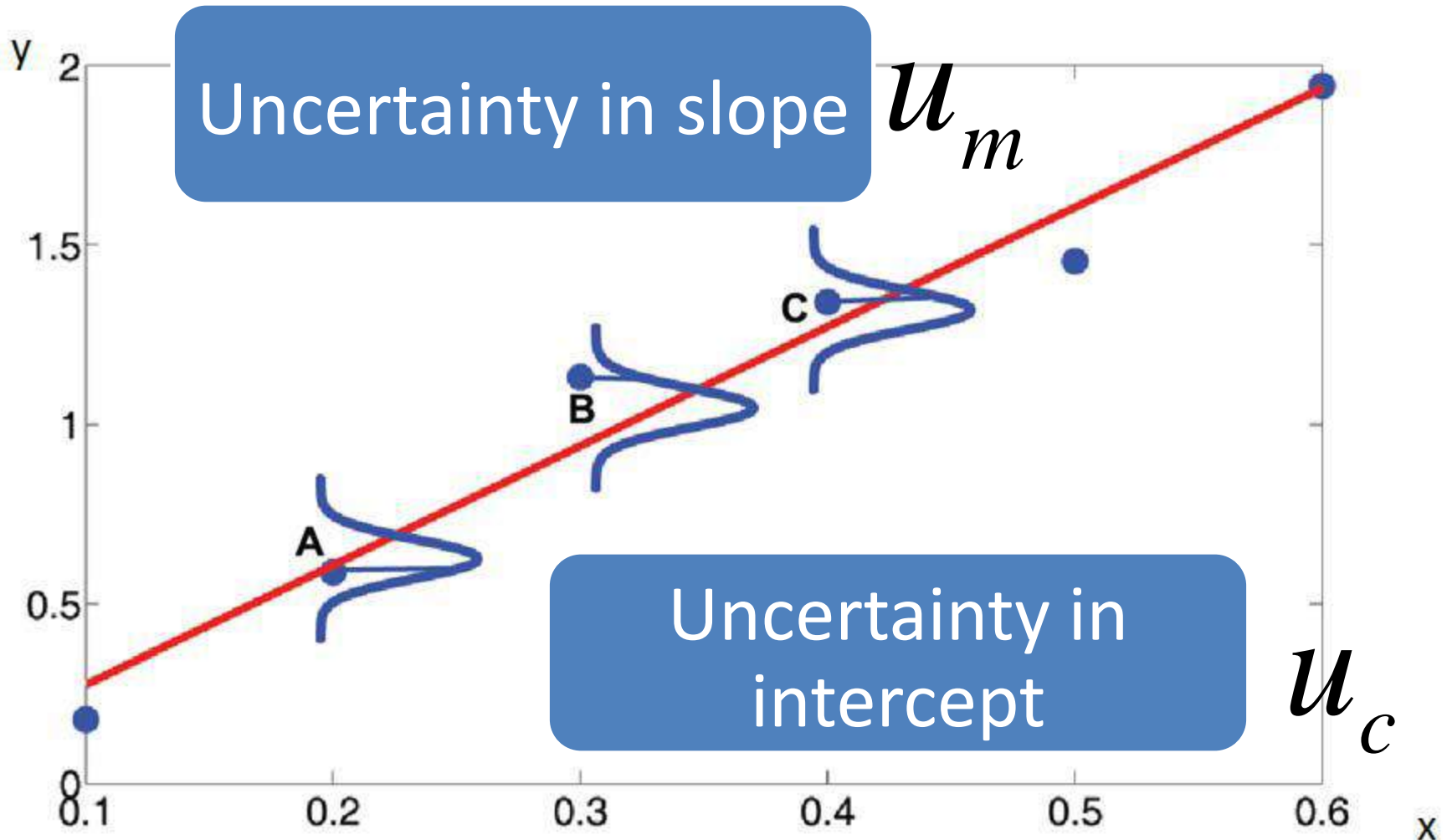
$$m = \frac{\sum y_i (x_i - \bar{x})}{\sum (x_i - \bar{x})^2}$$

Least-squares fit

$$c = \bar{y} - m\bar{x}$$

Detailed derivation (Available in the Data Processing Guide on the Physlab website).

Uncertainty in the least-squares fit



Uncertainty in slope and intercept

Uncertainty in slope

$$u_m = \sqrt{\frac{\sum_i^N d_i^2}{D(N-2)}}$$

Uncertainty in
intercept

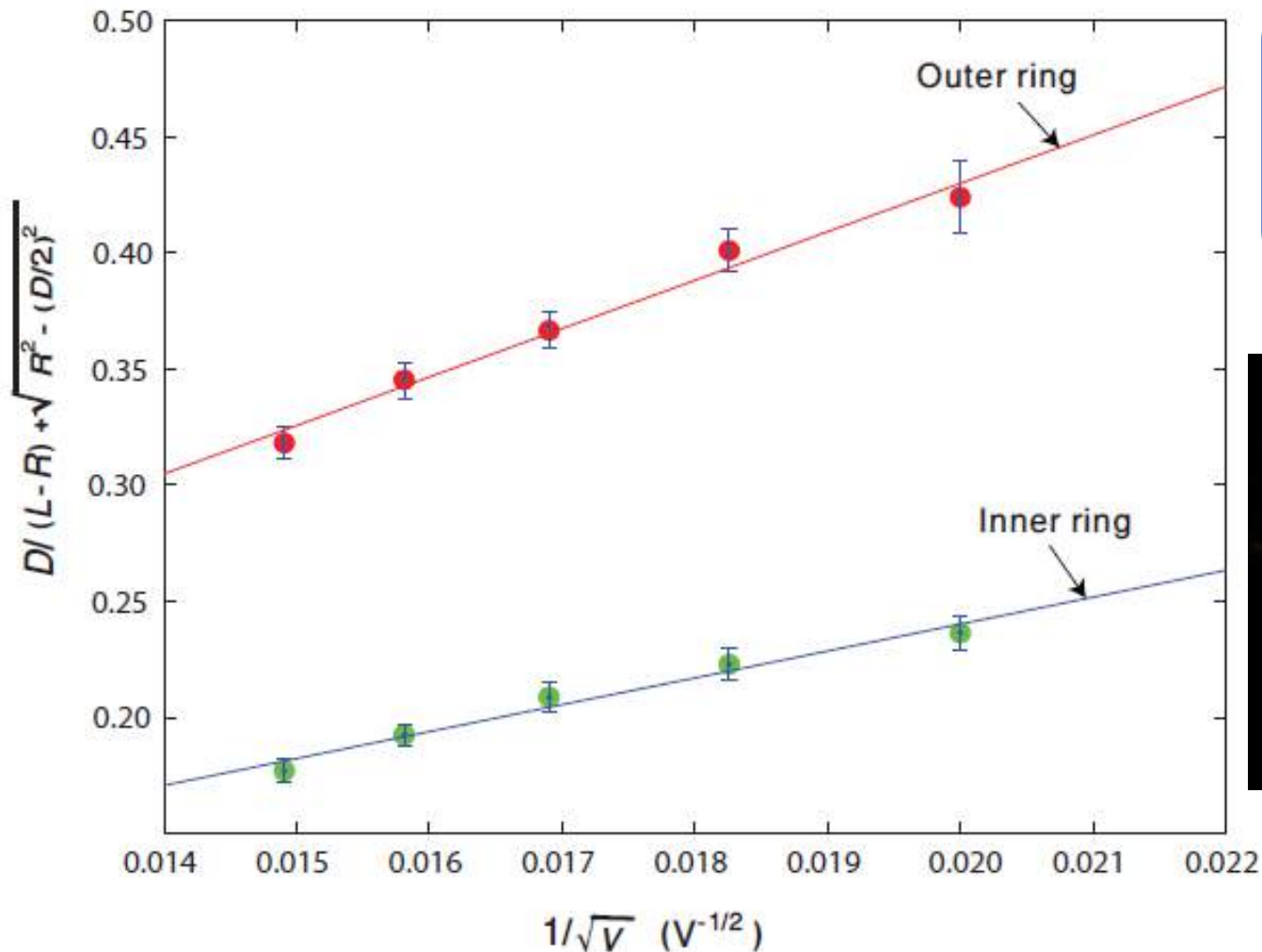
$$u_c = \sqrt{\left(\frac{1}{N} + \frac{\bar{x}^2}{D}\right) \left(\frac{\sum_i^N d_i^2}{(N-2)}\right)}$$

$$d_i = y_i - mx_i - c,$$

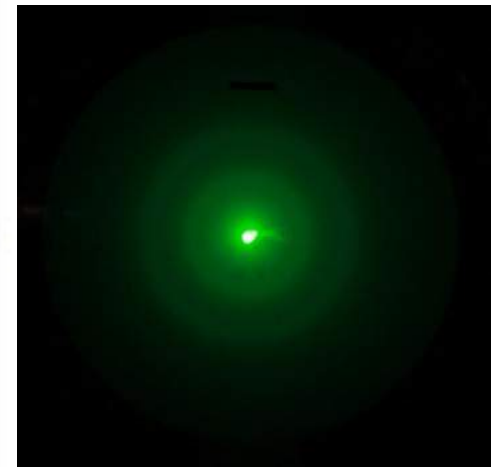
$$D = \sum_i^N (x_i - \bar{x})^2.$$

How Does Uncertainty in Data Creep in?

$$\left[\frac{D}{(L - R + \sqrt{R^2 - (D/2)^2})} \right] = \left[\frac{2(1.23 \times 10^{-9} \text{ m})}{d} \right] \frac{1}{\sqrt{V}}$$

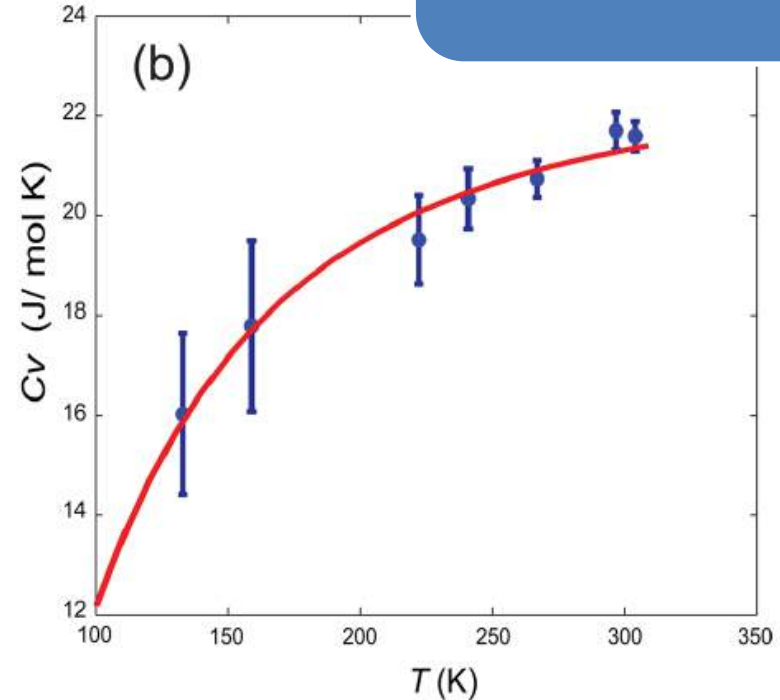
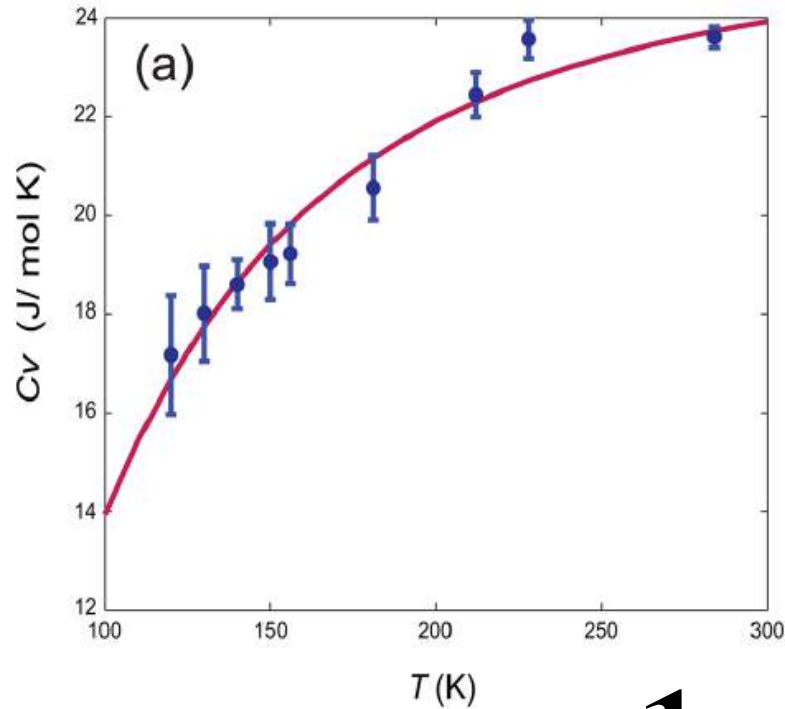


Diffraction of electrons from graphite



Concept of weighted fits

Measurement
of heat
capacities



$$w_i = \frac{1}{u_i^2}$$

Each data
point is
weighted
differently.

Formulas for weighted fits

Slope and intercept

$$m = \frac{\sum_i w_i \sum_i w_i (x_i y_i) - \sum_i (w_i x_i) \sum_i (w_i y_i)}{\sum_i w_i \sum_i (w_i x_i^2) - (\sum_i w_i x_i)^2},$$

$$c = \frac{\sum_i (w_i x_i^2) \sum_i (w_i y_i) - \sum_i (w_i x_i) \sum_i (w_i x_i y_i)}{\sum_i w_i \sum_i (w_i x_i^2) - (\sum_i w_i x_i)^2}$$

$$u_m = \sqrt{\frac{\sum_i w_i}{\sum_i w_i \sum_i (w_i x_i^2) - (\sum_i w_i x_i)^2}},$$

Uncertainties
therein

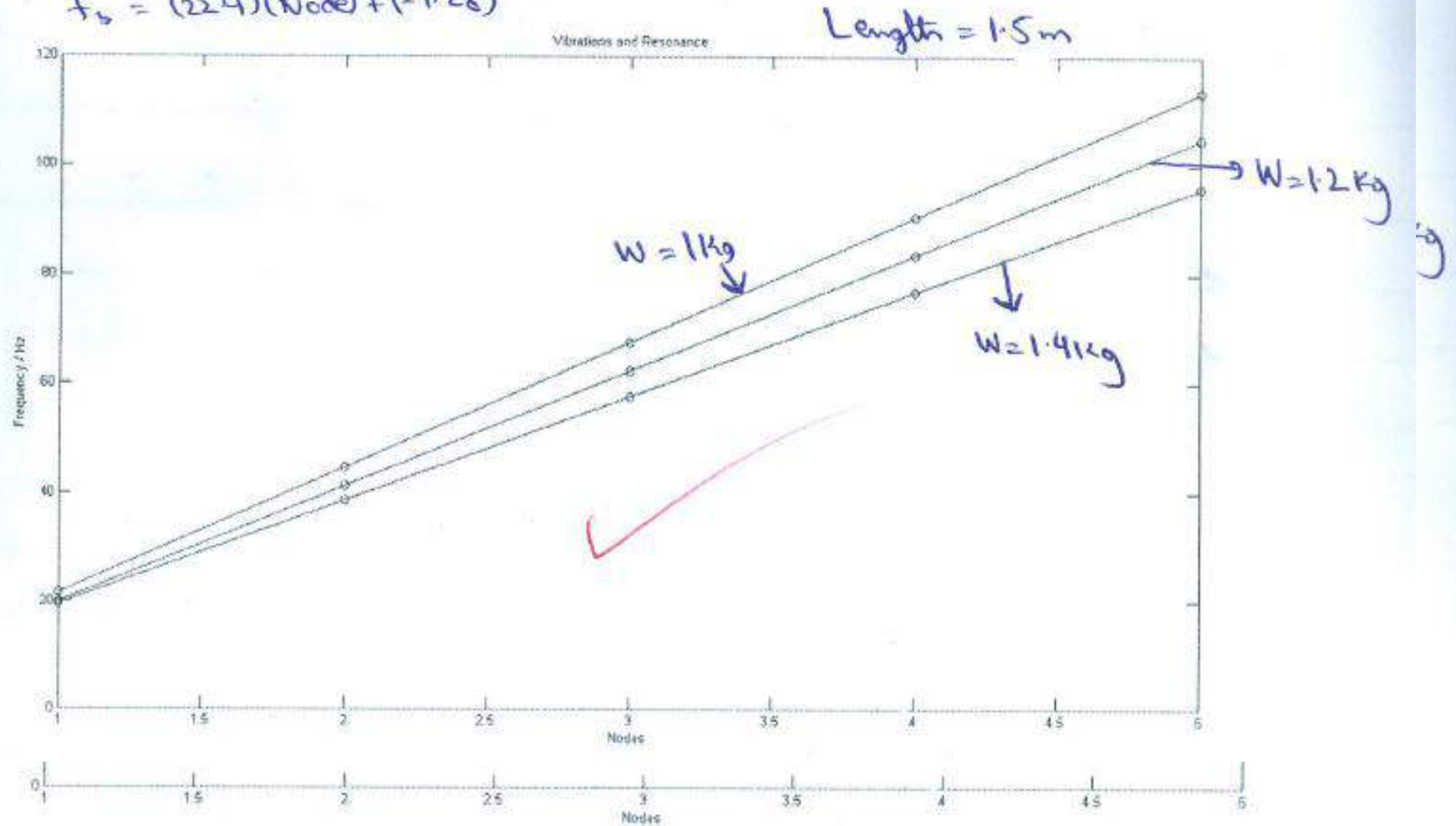
$$u_c = \sqrt{\frac{\sum_i (w_i x_i^2)}{\sum_i w_i \sum_i (w_i x_i^2) - (\sum_i w_i x_i)^2}}.$$

Sample Work from Students of PHY100/200

$$f_1 = (19)(\text{Node}) + 0.58$$

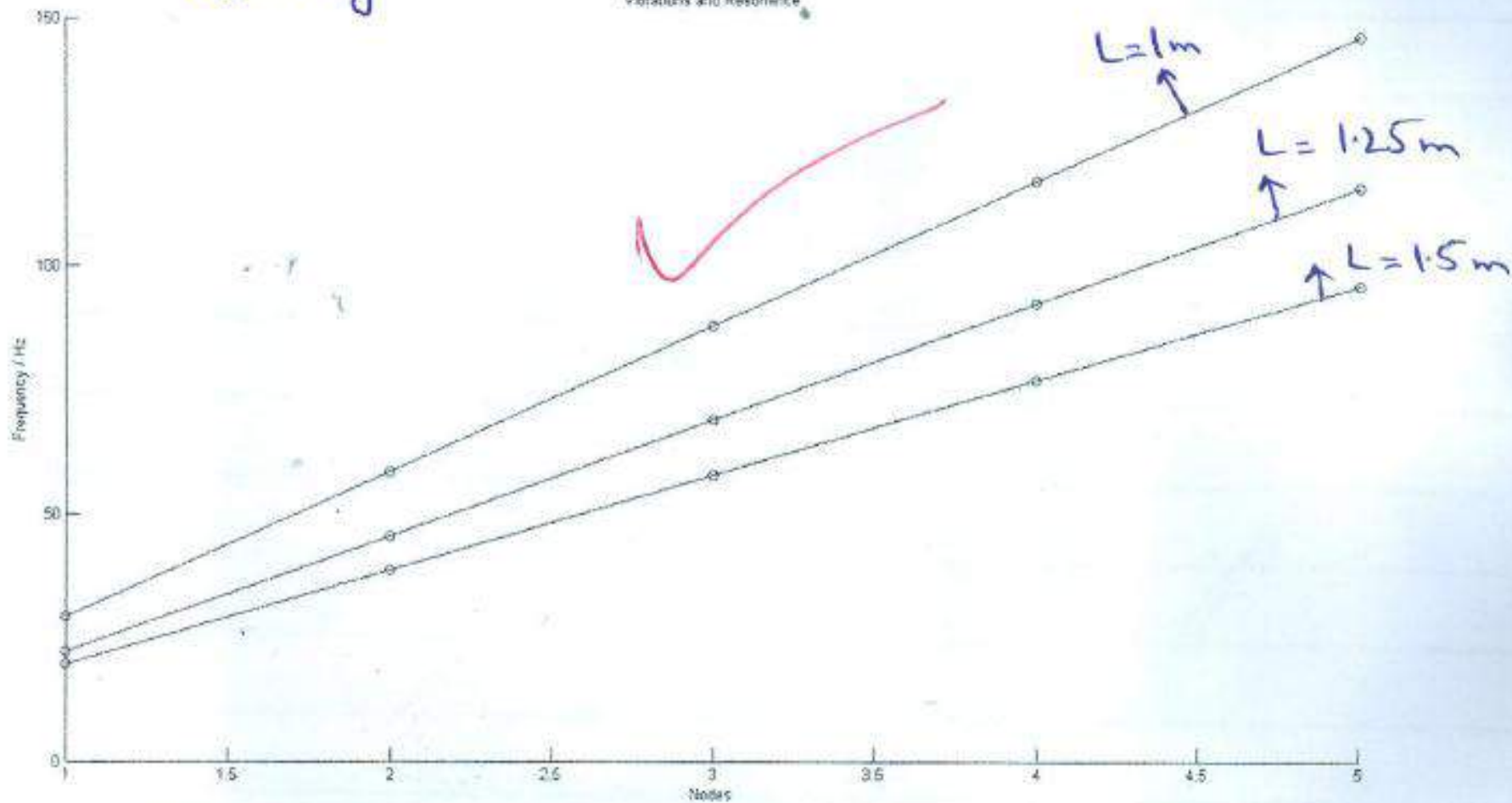
$$f_2 = (21.2)(\text{Node}) + (-1.26)$$

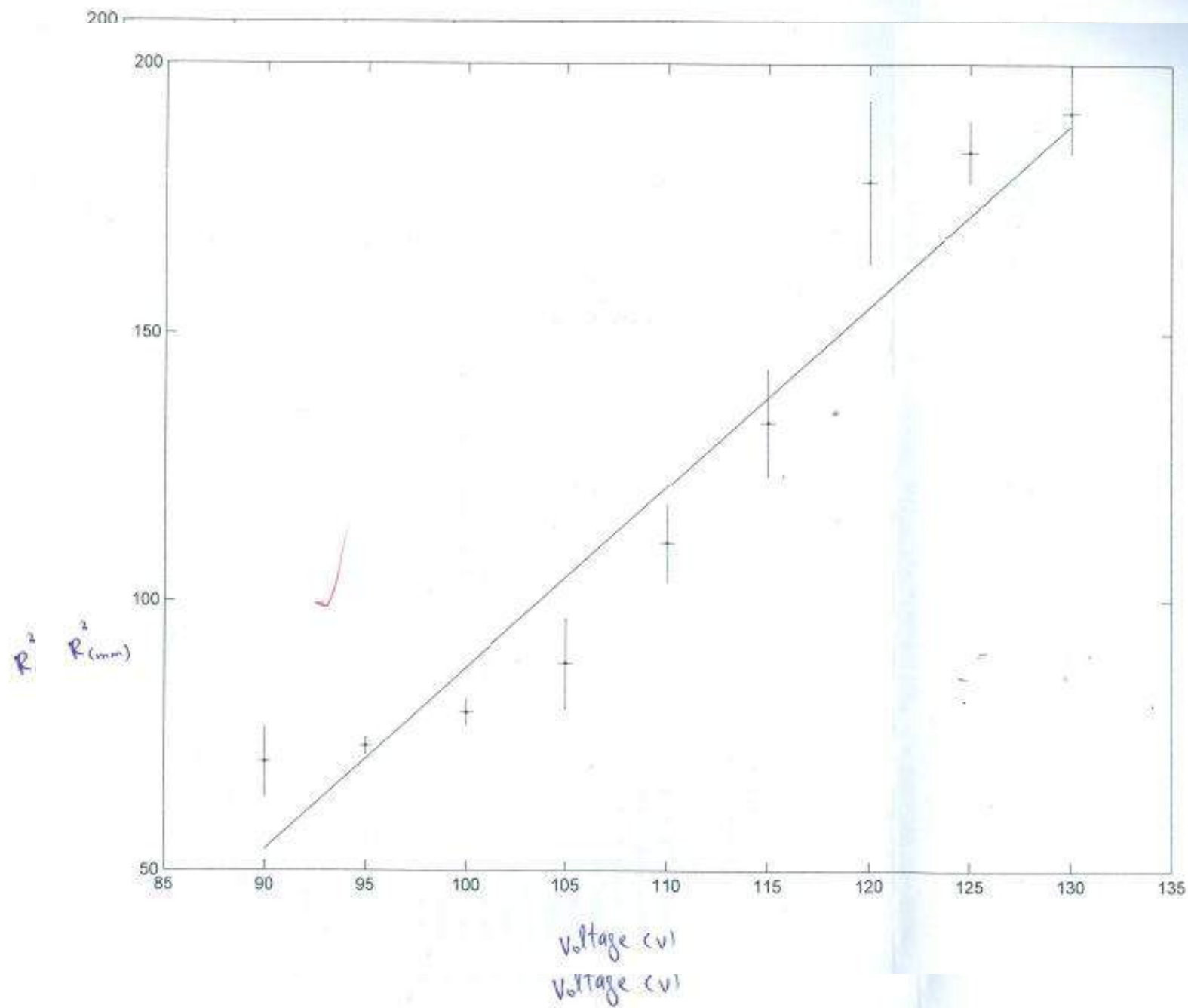
$$f_3 = (22.9)(\text{Node}) + (-1.28)$$



$W = 1 \text{ kg}$

Vibrations and Resonance





```

clc;
clear all;
close all
v=[90:5:130];
r= [8.379,8.555,8.908,9.408,10.525,11.554,13.3476,13.5534, 13.818];
r2 = r.^2;
plot(v,r2,'.')
dr = [0.382,0.0882,0.1323,0.441,0.3381,0.4263,0.5630,0.20433,0.26019]; %uncertainties✓
in r
a = v.*0.01; %Um ratings of v
p = sqrt((0.3).^2 + (a).^2); %uncertainties in v
q= (2.*r).*dr; %uncertainties in r square by formula deltaq = 2rdeltar
Utrans = 0.32.*p; %Utrans 0.32 is slope from graph
Utotal = sqrt((q).^2+(Utrans).^2); %Uncertainties of rsquare after transformation
w = 1./(Utotal.^2) %weight of uncertainties

%calculation of final slope fm

v2 = v.^2; %v square
sumw = sum(w); %sum of weights
pr_vr2 = v.*r2; %product of xy i.e v and r square
pr_w_vr2 = w.*pr_vr2; %product of weight and product of xy i.e v and r square
sumpr_w_vr2 = sum(pr_w_vr2); %sum of product of above two
pr_wv = w.*v; % product of weight and voltage
sumpr_wv = sum(pr_wv); % sum of product of weight and voltage
pr_wr2 = w.*r2; % product of weight and r square
sumpr_wr2 = sum(pr_wr2); % sum of p[roduct of weight and r square
pr_wv2 = w.*v2; % product of weight and v square
sumpr_wv2 = sum(pr_wv2); % sum of product of weight and v square
sumpr_wv_2 = (sumpr_wv).^2; % square of sum of product of weight and voltage

nume= ((sum(w)).*(sum(w.*(v.*r2)))) - ((sum(w.*v)).*sum(w.*r2))
denom= ((sum(w)).*(sum(w.*(v.^2)))) - ((sum(w.*v)).^2)

um=sqrt(sum(w)./denom)

final_m = nume/denom

% calculating c
nume_c = (((sum(w.*(v.^2)))*sum(w.*r2)) - ((sum(w.*v)).*(sum(w.*(v.*r2))))
final_c = nume_c/denom

uc = sqrt((sum(w.*(v.^2)))/denom)

y = ((final_m).*(v))+ final_c;
hold on

```


CALCULATIONS

cycle	Height (m)	Delta h (m)	N	Delta E (Joules)	W avg - (rad/sec^2)
1	0.61420	0	7.797	0	5.065
2	0.57090	0.04300	7.247	0.04250	4.816
3	0.53480	0.03610	6.789	0.03540	4.646
4	0.50840	0.02640	6.454	0.02590	4.676
5	0.47060	0.03780	5.974	0.03710	4.267
6	0.45560	0.01500	5.784	0.01470	4.148
7	0.42510	0.03050	5.396	0.02990	1.904
8	0.41010	0.01500	5.206	0.01470	4.148
9	0.39180	0.01830	4.974	0.01800	3.569
10	0.37480	0.01700	4.758	0.01670	3.220

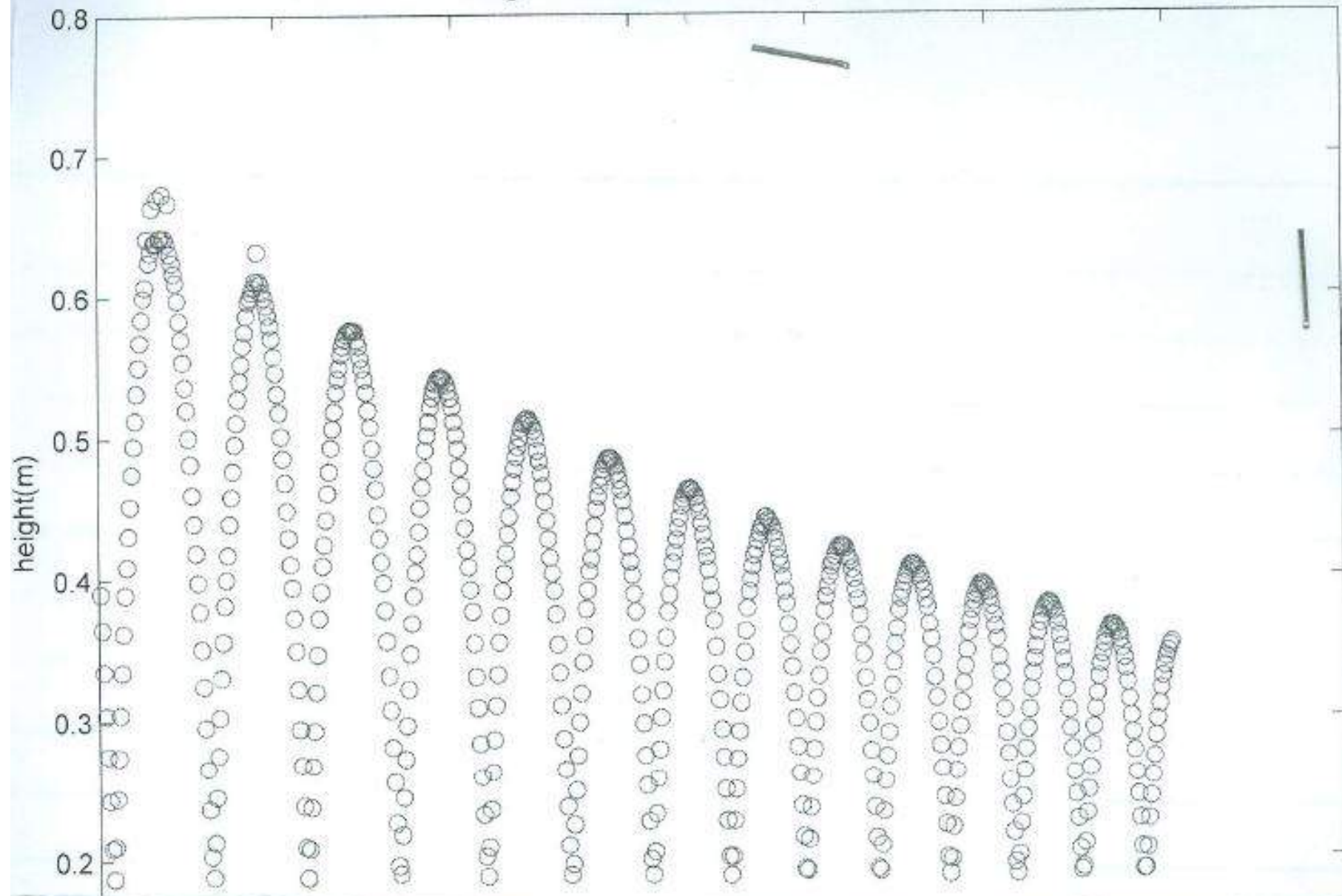
Uncertainty in height = $0.00005/(6)^{0.5}$

(Analog instrument)

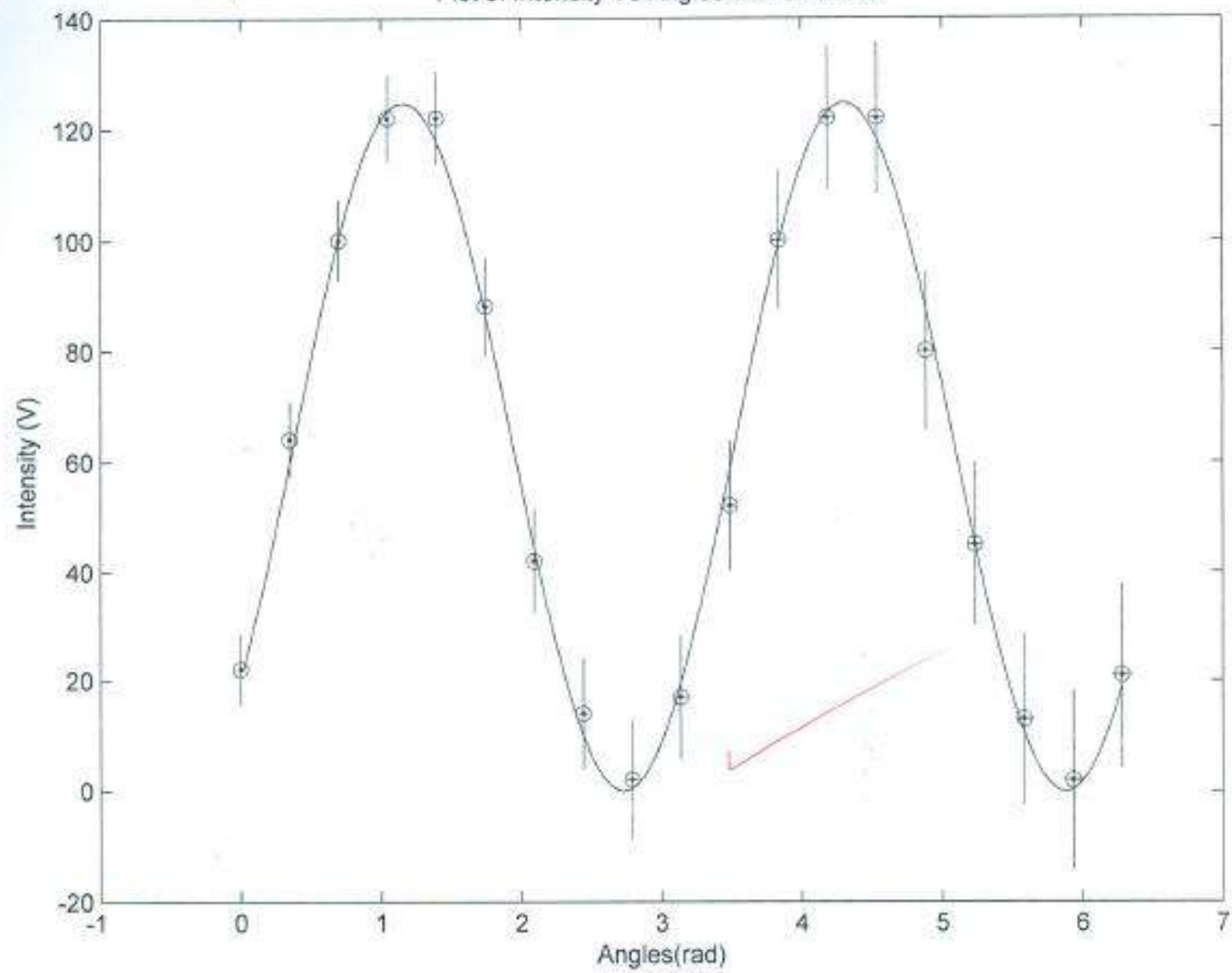
Uncertainty in radius = $0.005/(6)^{0.5} = 0.002$

(Analog instrument)

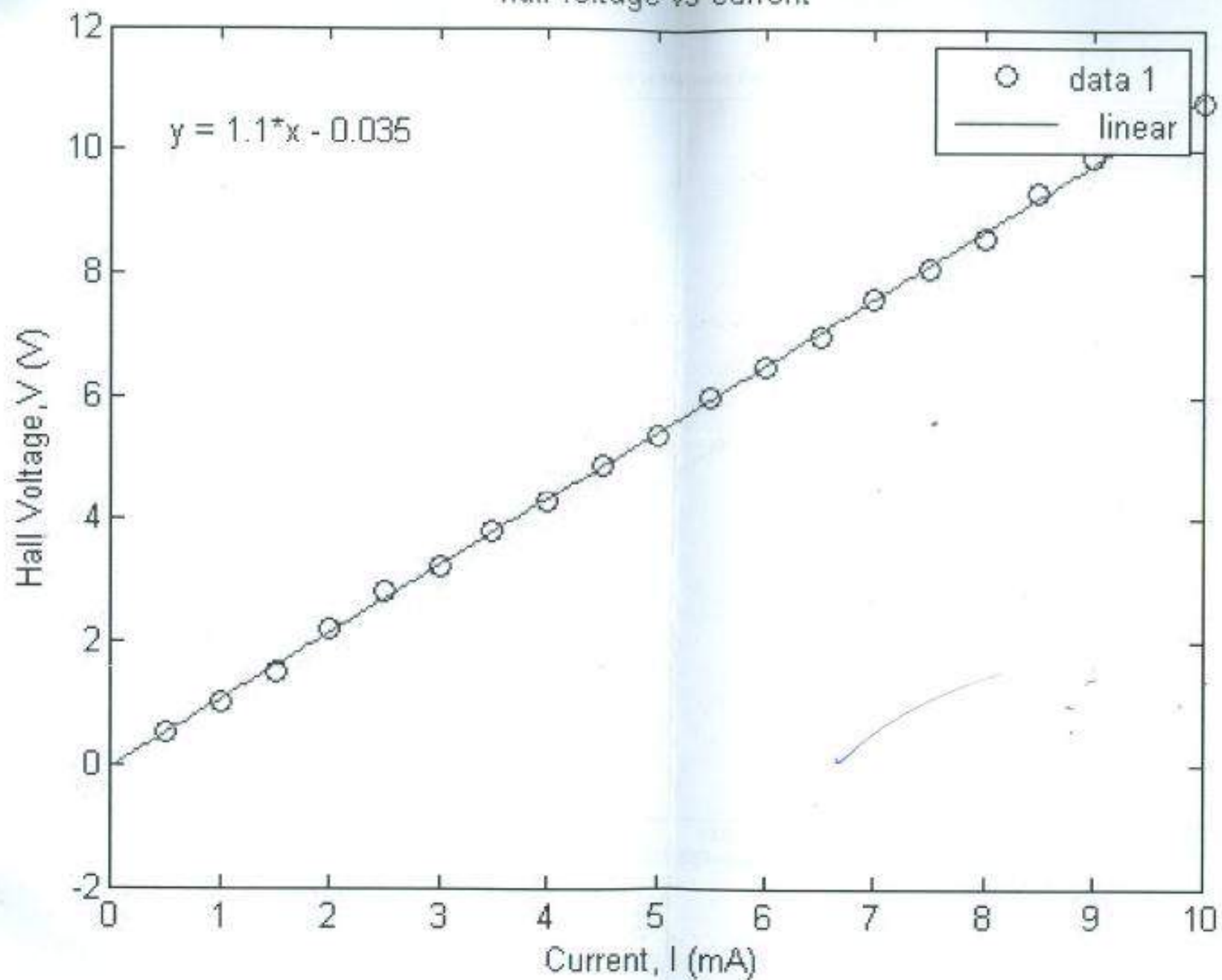
height loss of the mass hanger with time

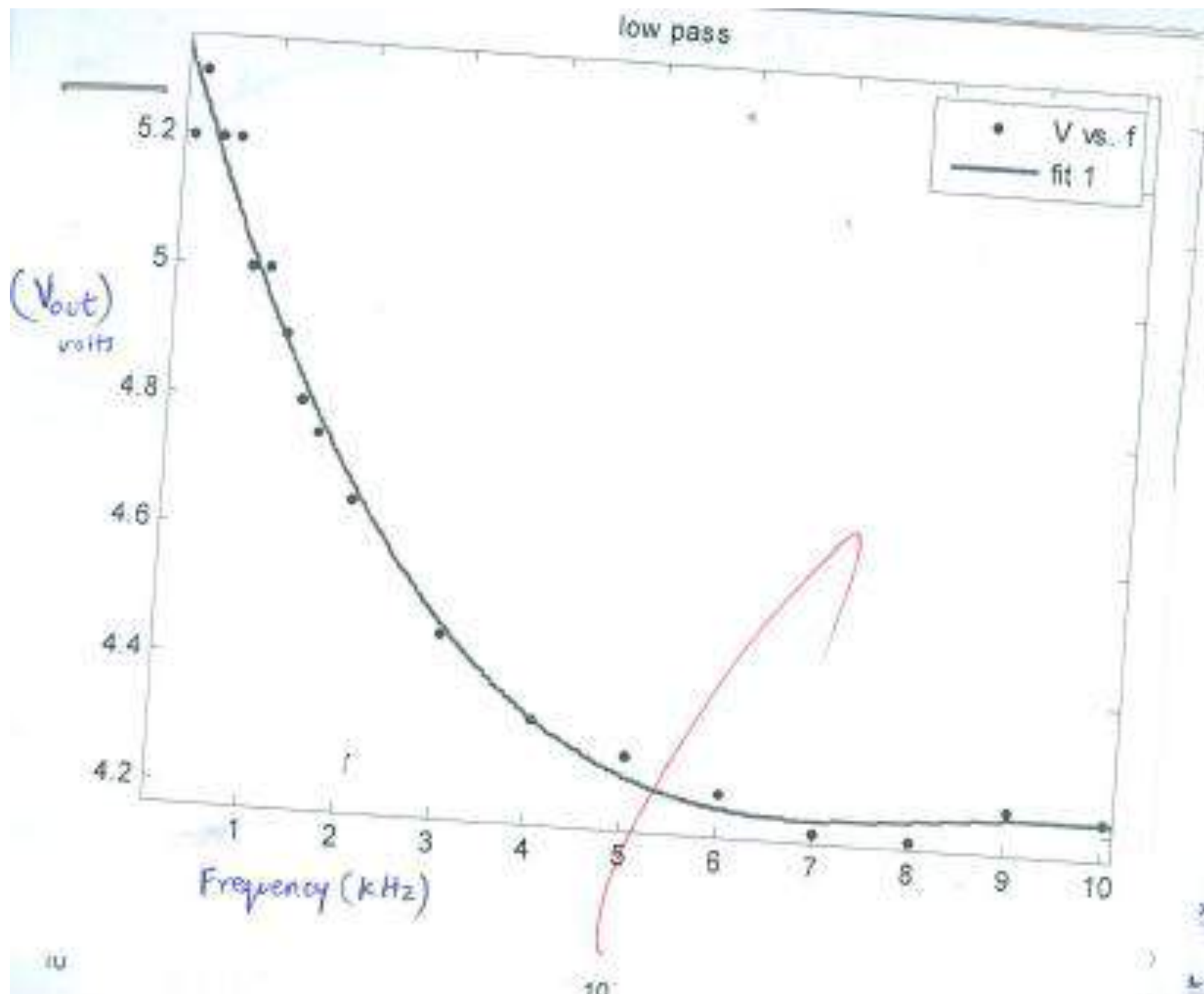


Plot of Intensity Vs Angles with errorbars

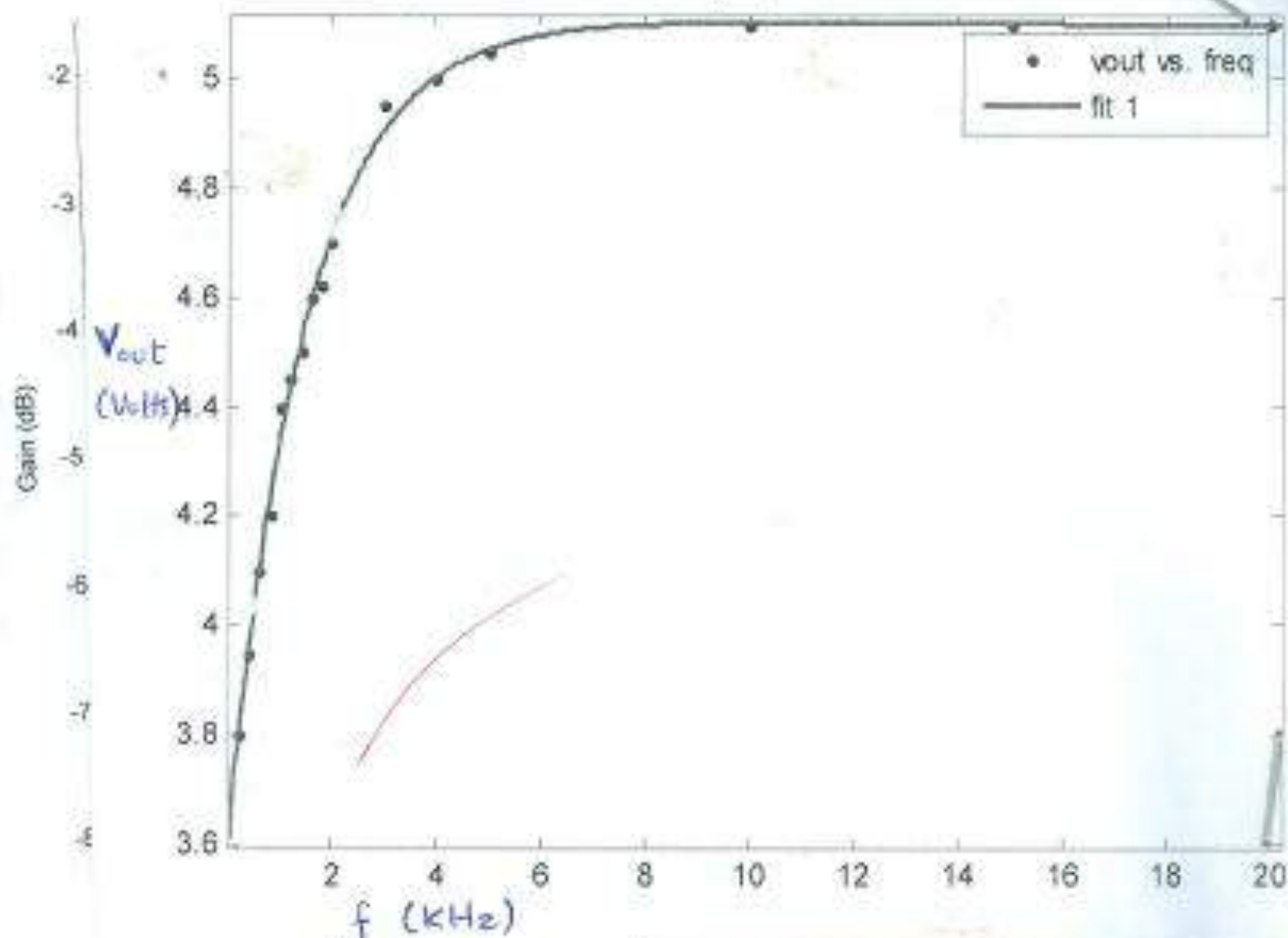


hall voltage vs current





high pass



- 5.75

|

4.2

Monday 10th Nov. 2014.

Experiment # 1.2A

Q1:- Moment of Inertia of tennis ball.

$$I = \frac{2}{5} M \left(\frac{R_o^5 - R_i^5}{R_o^3 - R_i^3} \right)$$

First we find respective quantities needed to measure the moment of inertia of a hollow sphere and a composite disk cylinder.

For composite disk cylinder

$$R_1 = 4.39 \text{ mm} = 0.439 \text{ cm}$$

$$R_2 = 14.96 \text{ mm} = 1.496 \text{ cm}$$

$$h_1 = 5.78 \text{ mm} = 0.578 \text{ cm}$$

$$h_2 = 16.90 \text{ mm} = 1.690 \text{ cm}$$

$$T_{\text{tot}} = \frac{26.10}{20} = 1.305 \text{ secs}$$

I for tall section

$$I_{\text{tot}} = \frac{1}{2} \pi \rho h_2 R_2^4$$

$$I_{\text{tot}} = \frac{1}{2} (\pi) (2.7 \times 10^{-3} \text{ g/cm}^3) (5.78) (4.39)^4$$

$$I_{\text{tot}} = 8.627 \text{ g cm}^2 = 0.087 \text{ g cm}^2$$

For tennis ball (hollow sphere)

$$R_o = 32.07 \text{ mm} = 3.207 \text{ cm}$$

$$R_i = 26.38 \text{ mm} = 2.638 \text{ cm}$$

$$M = 62.95 \text{ g}$$

$$T_{\text{tot}} = \frac{38.71}{10} = 3.871 \text{ secs}$$

I for short section

$$I_{\text{sh}} = \frac{1}{2} \pi \rho h_2 (R_2^4 - R_1^4)$$

$$I_{\text{sh}} = 0.5 \times \pi \times 2.7 \times \cancel{16.4} \times 1.69 (1.496^4 - 0.939^4)$$

$$I_{\text{short}} = 35.646 \text{ g cm}^2$$

$$I_{\text{total}} = I_{\text{tall}} + I_{\text{short}} = 35.733 \text{ g cm}^2$$

$$I_{\text{cylinder}} = 35.733 \text{ g cm}^2$$

We know that

$$T = 2\pi \sqrt{I/K}$$

or

$$K = \frac{4\pi^2 I}{T^2}$$

$$K = 828.339 \text{ g cm}^2/\text{s}^2$$

Now

$$I_{\text{cmm}} = \frac{K T_{\text{cmm}}^2}{4\pi^2}$$

$$I_{\text{tennis}} = \frac{(828.339)(3.871)^2}{4\pi^2}$$

$$I_{\text{tennis}} = 314.409 \text{ g cm}^2$$

Theoretical value of moment of inertia of tennis ball

$$I_{\text{tennis, theoretical}} = \frac{2}{5} (62.95) \left(\frac{32.07^2 - 25.30^2}{32.07^2 - 25.30^2} \right)$$

$$I_{\text{tennis, theoretical}} = 364.087 \text{ g cm}^2$$

Uncertainties

* Uncertainties in measurements done with vernier calliper. (Δr)

$$\Delta r = \frac{0.02}{2\sqrt{6}} = 4.08 \times 10^{-3} \text{ mm} = 4.08 \times 10^{-4} \text{ cm}$$

* Uncertainties in measurements done with stop watch (ΔT)

$$\Delta T = \frac{0.01}{2\sqrt{3}} = 2.887 \times 10^{-3} \text{ secs.}$$

* Uncertainties in quantities measured with weighing balance (ΔM)

$$\Delta M = \frac{0.01}{2\sqrt{3}} = 2.887 \times 10^{-3} \text{ grams.}$$

Rating of digital devices not included in uncertainty.

Uncertainty in I_{tall}

$$\Delta I_{\text{tall}} = \sqrt{\left(\frac{\partial I_{\text{tall}}}{\partial h_1} \Delta h_1\right)^2 + \left(\frac{\partial I_{\text{tall}}}{\partial R_1} \Delta R_1\right)^2}$$

$$\Delta I_{\text{tall}} = \sqrt{\left(\frac{1}{2} \pi g R_1^4 \frac{1}{\Delta h_1}\right)^2 + \left(4 \times \frac{1}{2} \pi g h_1 R_1^3 \times \Delta R_1\right)^2}$$

$$\Delta I_{\text{tall}} = \sqrt{\left(0.5(\pi)(2.7)(0.454)^4(7.0 \times 10^{-4})\right)^2 + \left(2 \times (\pi)(2.7)(0.578)(0.454)^3(9.08 \times 10^{-4})\right)^2}$$

$$\Delta I_{\text{tall}} = \sqrt{3.77 \times 10^{-9} + 1.07 \times 10^{-7}}$$

$$\Delta I_{\text{tall}} = 3.35 \times 10^{-4} \text{ g cm}^2$$

Uncertainty in I_{short}

$$\Delta I_{\text{short}} = \sqrt{\left(\frac{1}{2} \pi g (R_2^4 - R_1^4) \frac{1}{\Delta h_1}\right)^2 + \left(\frac{1}{2} \pi g h_2 R_2^3 \times 4 \times \Delta R_2\right)^2 + \left(-\frac{1}{2} \pi g h_2 R_1^3 \times 4 \times \Delta R_1\right)^2}$$

$$\Delta I_{\text{short}} = \sqrt{7.4 \times 10^{-5} + 1.5 \times 10^{-3} + 9.1 \times 10^{-7}}$$

$$\Delta I_{\text{short}} = 0.04 \text{ g cm}^2$$

$$\Delta I_{\text{cylinder}} = (3.33 \times 10^{-4} + 0.04) \text{ g cm}^2$$

$$\Delta I_{\text{cylinder}} = 0.04 \text{ g cm}^2$$

Uncertainty in $I_{\text{theoretical}}$

$$\frac{\partial I_{\text{tt}}}{\partial R_e} = \frac{2}{5} M \left[\frac{-5 R_e^4 + 5 R_e^4 R_i^3 - 3 R_e^4 + 3 R_e^4 R_i^3}{(R_e^3 - R_i^3)^2} \right]$$

$$= -2075.99$$

$$\frac{\partial I_{\text{tt}}}{\partial R_i} = \frac{2}{5} M \left[\frac{(R_e^3 - R_i^3)(-5 R_i^4) - (R_e^3 - R_i^3)(-3 R_i^4)}{(R_e^3 - R_i^3)^2} \right]$$

$$= 102.83$$

$$\frac{\partial I_{\text{tt}}}{\partial M} = \frac{2}{5} \left[\frac{R_e^3 - R_i^3}{R_e^3 - R_i^3} \right] = 5.78$$

$$\Delta I_{\text{tt}} = \sqrt{\left(\frac{\partial I_{\text{tt}}}{\partial R_e} \Delta R_e \right)^2 + \left(\frac{\partial I_{\text{tt}}}{\partial R_i} \Delta R_i \right)^2 + \left(\frac{\partial I_{\text{tt}}}{\partial M} \Delta M \right)^2}$$

Q1

$$\text{Ans 1:- } I_{\text{cylinder theoretical}} = (364.89 \pm 0.85) \text{ g cm}^2$$

Now

$$\Delta K = \sqrt{\left(\frac{4\pi^2}{T^2} \times \Delta I_{\text{cylinder}}\right)^2 + \left(4\pi^2 \frac{I}{T^3} \times 2 \times \Delta T\right)^2}$$

$$\Delta K = 6.5 \text{ g cm}^2/\text{s}^2$$

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$$\text{Ans 2:- } \text{Torsional constant (K)} = (828 \pm 6) \text{ g cm}^2/\text{s}^2$$

Now

$$I = \frac{KT^2}{4\pi^2}$$

~~Ans 3:-~~
10.11.2015

$$\Delta I_{\text{cylinder experimental}} = \sqrt{\left(\frac{T^2}{4\pi^2} \times \Delta K\right)^2 + \left(\frac{2TK}{4\pi^2} \times \Delta T\right)^2}$$

$$\Delta I_{\text{cylinder experimental}} = 2.48 \text{ g cm}^2$$

$$\text{Ans 3:- } I_{\text{cylinder experimental}} = (314.4 \pm 2.5) \text{ g cm}^2$$

