

Solving #3
(Solution)

$$(1)(a) \quad \hat{L}^2 = \hat{L}_x^2 + \hat{L}_y^2 + \hat{L}_z^2 \Rightarrow \hat{L}_x^2 + \hat{L}_y^2 = \hat{L}^2 - \hat{L}_z^2.$$

$$\begin{aligned} (\hat{L}_x^2 + \hat{L}_y^2)|l, m\rangle &= (\hat{L}^2 - \hat{L}_z^2)|l, m\rangle \\ &= \hat{L}^2|l, m\rangle - \hat{L}_z^2|l, m\rangle \\ &= (\hbar^2(l)(l+1) - \hbar^2 m^2)|l, m\rangle \\ &= \hbar^2(l^2 + l - m^2)|l, m\rangle. \end{aligned}$$

\therefore the measured value is $\hbar^2(l^2 + l - m^2)$.

$$\begin{aligned} (b) \quad \langle \hat{L}_x \rangle &= \frac{1}{2} \langle \Psi | (\hat{L}_+ + \hat{L}_-) |\Psi \rangle = \frac{1}{4} \left(\langle l, 1 | + \langle l, -1 | \right) (\hat{L}_+ + \hat{L}_-) \\ &\quad (|l, 1\rangle + |l, -1\rangle) \\ &= \frac{1}{4} (\langle l, 1 | + \langle l, -1 |) (\hbar\sqrt{2} |l, 0\rangle + \hbar\sqrt{2} |l, 0\rangle) \\ &= \hbar (\langle l, 1 | + \langle l, -1 |) (|l, 0\rangle) \left(\frac{\sqrt{2}}{2} \right) \\ &= 0. \end{aligned}$$

$$\begin{aligned} \langle \hat{L}_y \rangle &= \frac{1}{2i} \langle \Psi | (\hat{L}_+ - \hat{L}_-) |\Psi \rangle = \frac{1}{4i} \left(\langle l, 1 | + \langle l, -1 | \right) (\hat{L}_+ - \hat{L}_-) \\ &\quad (|l, 1\rangle + |l, -1\rangle) \\ &= \frac{1}{4i} (\langle l, 1 | + \langle l, -1 |) (\hbar\sqrt{2} |l, 0\rangle - \hbar\sqrt{2} |l, 0\rangle) \\ &= 0. \end{aligned}$$

$$\begin{aligned} \langle \hat{L}_z \rangle &= \langle \Psi | \hat{L}_z | \Psi \rangle = \frac{1}{2} (\langle l, 1 | + \langle l, -1 |) \hat{L}_z (|l, 1\rangle + |l, -1\rangle) \\ &= \frac{1}{2} (\langle l, 1 | + \langle l, -1 |) (\hbar |l, 1\rangle - \hbar |l, -1\rangle) \\ &= 0. \end{aligned}$$

$$\begin{aligned}
 (2)(a) \quad & \langle \hat{J}_y \rangle = \frac{1}{2} (\langle \frac{1}{2}, \frac{1}{2} | + \langle \frac{1}{2}, -\frac{1}{2} |) \hat{J}_y (| \frac{1}{2}, \frac{1}{2} \rangle + | \frac{1}{2}, -\frac{1}{2} \rangle) \\
 & = \frac{1}{2} (\langle \frac{1}{2}, \frac{1}{2} | + \langle \frac{1}{2}, -\frac{1}{2} |) \left(\frac{\pm}{2} | \frac{1}{2}, \frac{1}{2} \rangle - \frac{\mp}{2} | \frac{1}{2}, -\frac{1}{2} \rangle \right) \\
 & = \frac{1}{2} \left(\frac{\pm}{2} - \frac{\mp}{2} \right) \\
 & = 0.
 \end{aligned}$$

(b) Consider the uncertainty relations

$$\Delta J_y \Delta J_x \geq \frac{\hbar}{2} \| \langle \hat{J}_x \rangle \|$$

and

$$\Delta J_y \Delta J_x \geq \frac{\hbar}{2} \| \langle \hat{J}_y \rangle \|.$$

$$\begin{aligned}
 \| \langle \hat{J}_x \rangle \| &= \| \langle \psi | \hat{J}_x | \psi \rangle \| = \frac{1}{4} \| (\langle \frac{1}{2}, \frac{1}{2} | + \langle \frac{1}{2}, -\frac{1}{2} |) (\hat{J}_x + \hat{J}_z) \\
 &\quad (| \frac{1}{2}, \frac{1}{2} \rangle + | \frac{1}{2}, -\frac{1}{2} \rangle) \| \\
 &= \frac{1}{4} \| (\langle \frac{1}{2}, \frac{1}{2} | + \langle \frac{1}{2}, -\frac{1}{2} |) (\mp | \frac{1}{2}, \frac{1}{2} \rangle + \mp | \frac{1}{2}, -\frac{1}{2} \rangle) \| \\
 &= \frac{1}{4} \| 2\mp \| \\
 &= \frac{\hbar}{2}.
 \end{aligned}$$

$$\begin{aligned}
 \| \langle \hat{J}_y \rangle \| &= \| \langle \psi | \hat{J}_y | \psi \rangle \| = \frac{1}{4} \| (\langle \frac{1}{2}, \frac{1}{2} | + \langle \frac{1}{2}, -\frac{1}{2} |) (\hat{J}_x - \hat{J}_z) \\
 &\quad (| \frac{1}{2}, \frac{1}{2} \rangle + | \frac{1}{2}, -\frac{1}{2} \rangle) \| \\
 &= \frac{1}{4} \| (\langle \frac{1}{2}, \frac{1}{2} | + \langle \frac{1}{2}, -\frac{1}{2} |) (\mp | \frac{1}{2}, \frac{1}{2} \rangle - \mp | \frac{1}{2}, -\frac{1}{2} \rangle) \| \\
 &= 0.
 \end{aligned}$$

Clearly, $\Delta J_y \Delta J_x \geq \frac{\hbar}{2} \| \hat{J}_x \| = \frac{\hbar}{2} \left(\frac{\hbar}{2} \right) = \frac{\hbar^2}{4} \Rightarrow \Delta J_y > 0$. This thing implies that we cannot know \hat{J}_y . Even though $|\psi\rangle = \frac{1}{\sqrt{2}} (| \frac{1}{2}, \frac{1}{2} \rangle + | \frac{1}{2}, -\frac{1}{2} \rangle)$ is an eigenstate of \hat{J}_x (compare $|\psi\rangle$ with

$|+x\rangle = \frac{1}{\sqrt{2}}|+z\rangle + \frac{1}{\sqrt{2}}|-z\rangle$, something implying that we know \hat{J}_x , we cannot know \hat{J}_y simultaneously. Same goes for \hat{J}_z .
 For $\Delta\hat{J}_y\Delta\hat{J}_z \geq \frac{\hbar^2}{4}$ implies that $\Delta\hat{J}_z > 0$.

(c) The only such state is $|0, 0\rangle$

(3) $[\hat{J}^2, \hat{J}_z]$

$$= [\hat{J}_x^2 + \hat{J}_y^2 + \hat{J}_z^2, \hat{J}_z]$$

$$= [\hat{J}_x^2, \hat{J}_z] + [\hat{J}_y^2, \hat{J}_z] + [\hat{J}_z^2, \hat{J}_z]$$

$$= \hat{J}_x[\hat{J}_x, \hat{J}_z] + [\hat{J}_x, \hat{J}_z]\hat{J}_x + \hat{J}_y[\hat{J}_y, \hat{J}_z] + [\hat{J}_y, \hat{J}_z]\hat{J}_y + 0$$

$$= -i\hbar\hat{J}_x\hat{J}_y - i\hbar\hat{J}_y\hat{J}_x + i\hbar\hat{J}_y\hat{J}_x + i\hbar\hat{J}_x\hat{J}_y$$

= 0. Q.E.D.