

HW6

Q1.

→ Transforming operator is
$$e^{\underbrace{+i\hbar\omega'_A \hat{a}_A^\dagger \hat{a}_A}_U^+} e^{\underbrace{+i\hbar\omega'_B \hat{a}_B^\dagger \hat{a}_B}_U^+} = U^+(t).$$

→ In the interaction frame

$$\tilde{H} = U^+ H U - H = -\hbar g \left(U_A^+ (\hat{a}_A - \hat{a}_A^\dagger) U_A \right) \left(U_B^+ (\hat{a}_B - \hat{a}_B^\dagger) U_B \right)$$

→ After the RWA in the interaction picture:

$$\tilde{H} = +\hbar g \left[\hat{a}_A \hat{a}_B e^{-i\hbar(\omega'_A - \omega'_B)t} + \hat{a}_A^\dagger \hat{a}_B^\dagger e^{+i\hbar(\omega'_A - \omega'_B)t} \right]$$

$$= \hbar g \left(\hat{a}_A \hat{a}_B e^{-i\Delta t} + \hat{a}_A^\dagger \hat{a}_B^\dagger e^{+i\Delta t} \right) \quad \Delta = \omega'_A - \omega'_B.$$

→ TDSE:

$$i\hbar \dot{C}_A(t) |10\rangle + i\hbar \dot{C}_B(t) |01\rangle$$

$$= \hbar g \left(c_A e^{-i\Delta t} \hat{a}_A \hat{a}_B^\dagger |10\rangle + c_A e^{+i\Delta t} \hat{a}_A^\dagger \hat{a}_B |10\rangle \right)$$

$$+ c_B e^{-i\Delta t} \hat{a}_A \hat{a}_B^\dagger |01\rangle + c_B e^{+i\Delta t} \hat{a}_A^\dagger \hat{a}_B |01\rangle$$

$$= \hbar g \left(c_A(t) e^{-i\Delta t} |10\rangle + c_B(t) e^{+i\Delta t} |10\rangle \right)$$

Projections:

$$\left[\begin{array}{l} i\hbar \dot{C}_A(t) = \hbar g e^{+i\Delta t} C_B(t) \\ i\hbar \dot{C}_B(t) = \hbar g e^{-i\Delta t} C_A(t) \end{array} \right] \begin{array}{l} \text{--- ①} \\ \text{--- ②} \end{array}$$

Solve ① and ② simultaneously. Differentiating ①:

$$i\hbar \ddot{c}_A(t) = i\Delta \hbar g e^{i\Delta t} c_B(t) + \hbar g e^{i\Delta t} \dot{c}_B(t)$$

From ②

$$\dot{c}_B(t) = -\frac{i}{\hbar} \hbar g e^{-i\Delta t} c_A(t)$$

Insert above

$$i\hbar \ddot{c}_A(t) = i\Delta \hbar g e^{i\Delta t} c_B(t) + \hbar g^2 e^{i\Delta t} (-i) e^{-i\Delta t} c_A(t)$$

Inserting $c_B(t) = \frac{i\dot{c}_A(t)}{g} e^{-i\Delta t}$ from ①

$$i\hbar \ddot{c}_A(t) = i\Delta \hbar g e^{i\Delta t} \left(\frac{i\dot{c}_A(t)}{g} e^{-i\Delta t} \right) - i\hbar g^2 c_A(t)$$

$$i\hbar \ddot{c}_A(t) = -\hbar \Delta \dot{c}_A(t) - i\hbar g^2 c_A(t)$$

$$\ddot{c}_A(t) = i\Delta \dot{c}_A(t) - g^2 c_A(t)$$

$$\boxed{\ddot{c}_A(t) - i\Delta \dot{c}_A(t) + g^2 c_A(t) = 0}$$

Solution is

$$c_A(t) = e^{i\frac{\Delta}{2}t} \left(A e^{\frac{i\sqrt{\Delta^2+4g^2}}{2}t} + B e^{-\frac{i\sqrt{\Delta^2+4g^2}}{2}t} \right)$$

$$\dot{c}_A(t) = e^{i\frac{\Delta}{2}t} \left(i\left(\frac{\Delta}{2} + \frac{\sqrt{\Delta^2+4g^2}}{2}\right) A e^{\frac{i\sqrt{\Delta^2+4g^2}}{2}t} + i\left(\frac{\Delta}{2} - \frac{\sqrt{\Delta^2+4g^2}}{2}\right) B e^{-\frac{i\sqrt{\Delta^2+4g^2}}{2}t} \right)$$

From (1)

$$c_B(t) = \frac{i}{g} e^{-i\delta t} \dot{c}_A(t)$$

$$\therefore c_B(t) = -\frac{1}{g} \left[\left(\frac{\Delta}{2} + \sqrt{\frac{\Delta^2 + 4g^2}{2}} \right) A e^{\frac{i\sqrt{\Delta^2 + 4g^2}}{2} t} + \left(\frac{\Delta}{2} - \sqrt{\frac{\Delta^2 + 4g^2}{2}} \right) B e^{-\frac{i\sqrt{\Delta^2 + 4g^2}}{2} t} \right]$$

At $t=0$, $c_B(t) = 0$, $c_A(t) = 1$, imply the following:

$$\boxed{1 = A + B} \text{ and } 0 = A \left(\frac{\Delta}{2} + \sqrt{\frac{\Delta^2 + 4g^2}{2}} \right) + B \left(\frac{\Delta}{2} - \sqrt{\frac{\Delta^2 + 4g^2}{2}} \right) = 0$$

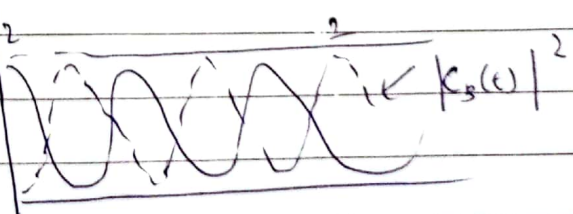
$$\boxed{\frac{\Delta}{2} (A+B) + \left(\sqrt{\frac{\Delta^2 + 4g^2}{2}} \right) (A-B) = 0}$$

→ On resonance: $\Delta = 0 \Rightarrow A = B$.

$$\begin{aligned} \text{So } c_B(t) &= -\frac{1}{g} \left[\cancel{2g} A e^{igt} - \cancel{g} A e^{-igt} \right] \\ &= -A (e^{igt} - e^{-igt}) = -2i A \sin(gt). \end{aligned}$$

$$\text{And } c_A(t) = 2A \cos(gt) \left| c_A \right|^2 \left| c_B(t) \right|^2$$

Hence Rabi flopping.



Q2

(a) From (3) :

$$ik \frac{1}{2\sqrt{n_1}} e^{i\theta_1} \frac{dn_1}{dt} + ik(i)\sqrt{n_1} \frac{d\theta_1}{dt} e^{i\theta_1} = -ev\sqrt{n_1} e^{i\theta_1} + K\sqrt{n_2} e^{i\theta_2}$$

$$ik e^{i\theta_1} \frac{dn_1}{dt} - 2kn_1 \frac{d\theta_1}{dt} e^{i\theta_1} = -2evn_1 e^{i\theta_1} + 2K\sqrt{n_1 n_2} e^{i\theta}$$

$$\left[ik \frac{dn_1}{dt} - 2kn_1 \frac{d\theta_1}{dt} = -2evn_1 + 2K\sqrt{n_1 n_2} e^{i\theta} \right] \quad (A)$$

From (4) :

$$\left[ik \frac{dn_2}{dt} - 2kn_2 \frac{d\theta_2}{dt} = 2evn_2 + 2K\sqrt{n_1 n_2} e^{+i\theta} \right] \quad (B)$$

where $\theta = \theta_1 - \theta_2$.

b)

$$\text{Re(A)}: \quad -2kn_1 \frac{d\theta_1}{dt} = -2evn_1 + 2K\sqrt{n_1 n_2} \cos\theta$$

$$\left[\frac{d\theta_1}{dt} = \frac{ev}{k} - \frac{K}{k} \sqrt{\frac{n_2}{n_1}} \cos\theta \right] \quad (C)$$

$$\text{Im}(A): \quad \hbar \frac{dn_1}{dt} = -2\kappa \sqrt{n_1 n_2} \sin \theta$$

$$\boxed{\frac{dn_1}{dt} = -\frac{2\kappa}{\hbar} \sqrt{n_1 n_2} \sin \theta} \quad \text{---(D)}$$

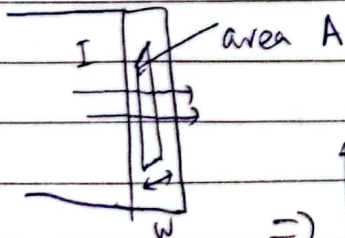
$$\text{Re}(B): \quad -2\hbar n_2 \frac{d\theta}{dt} = 2e\hbar n_2 + 2\kappa \sqrt{n_1 n_2} \cos \theta$$

$$\boxed{\frac{d\theta}{dt} = -\frac{e\hbar}{\hbar} - \frac{\kappa}{\hbar} \sqrt{\frac{n_1}{n_2}} \cos \theta} \quad \text{---(E)}$$

$$\text{Im}(B): \quad \cancel{-2\hbar n_2} \quad \hbar \frac{dn_2}{dt} = 2\kappa \sqrt{n_1 n_2} \sin \theta$$

$$\boxed{\frac{dn_2}{dt} = \frac{2\kappa}{\hbar} \sqrt{n_1 n_2} \sin \theta = -\frac{dn_1}{dt}} \quad \text{---(F)}$$

$$\boxed{(C)} \quad \bar{I}_1 = -\frac{\partial}{\partial t} (-2en_1) Aw = 2e \left(\frac{\partial n_1}{\partial t} \right) Aw$$



$$= 2e \left(-\frac{2\kappa}{\hbar} \right) \sqrt{n_1 n_2} Aw \sin \theta$$

$$\Rightarrow \boxed{|\bar{I}_1| = |\bar{I}_c| \sin \theta} \quad \leftarrow \text{first JJ eqn.}$$

$$|\bar{I}_c| = \left(\frac{4e^2 \kappa}{\hbar} \sqrt{n_1 n_2} Aw \right) \checkmark$$

second JJ eqn.

(c) From (c) and (E):

$$\frac{d(\theta_1 - \theta_2)}{dt} = \frac{d\theta}{dt} = \frac{2ev}{\hbar} \quad (n_1 = n_2)$$

(d) $I_1 = I_c \sin \theta$

$$\frac{dI_1}{dt} = I_c \cos \theta \frac{d\theta}{dt}$$

$$= I_c \sqrt{1 - \sin^2 \theta} \left(\frac{2ev}{\hbar} \right)$$

$$\frac{dI_1}{dt} = I_c \sqrt{1 - \left(\frac{I_1}{I_c} \right)^2} \left(\frac{2ev}{\hbar} \right)$$

$$v = \left(\frac{\hbar}{2ev I_c \sqrt{1 - \left(\frac{I_1}{I_c} \right)^2}} \right) \frac{dI_1}{dt}$$

L_{eff} becomes a function of I_1 , $L_{eff} = \frac{\hbar}{2ev I_c \sqrt{1 - \left(\frac{I_1}{I_c} \right)^2}}$

and non linear.

Q3

$$I_1 + I_2 = 0$$

current entering a node = current leaving the node.

$$I_c \sin \theta + \frac{d}{dt} (C_J v) = 0$$

$$I_c \sin \theta + C_J \frac{dv}{dt} = 0$$

As $v = \frac{d\Phi}{dt} \Rightarrow \boxed{I_c \sin \theta + C_J \frac{d^2 \Phi}{dt^2} = 0}$

(b) Second JJ eqn, part d) of Q2:

$$\frac{d\theta}{dt} = \frac{2e}{\hbar} \frac{d\Phi}{dt}$$

$$\frac{d\Phi}{dt} = \frac{\hbar}{2e} \frac{d\theta}{dt} \Rightarrow \frac{d^2 \Phi}{dt^2} = \frac{\hbar}{2e} \frac{d^2 \theta}{dt^2}$$

$$\boxed{I_c \sin \theta + C_J \frac{\hbar}{2e} \frac{d^2 \theta}{dt^2} = 0} \quad (G)$$

$$\frac{\hbar}{2e} \theta = \Phi$$

$$\theta = \frac{2e}{\hbar} \Phi$$

$$I_c \sin \left(\frac{2\pi \Phi}{\Phi_0} \right) + C_J \frac{\hbar}{2e} \frac{d^2 \theta}{dt^2} = 0$$

$$= \frac{2e}{\hbar} \frac{2\pi \Phi}{dt^2}$$

$$= 2\pi \Phi / \Phi_0$$

(c) L is unknown, but $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\Phi}} \right) =$

Derived answer $\Rightarrow \boxed{I_c \sin \left(\frac{2\pi \Phi}{\Phi_0} \right) + C_J \frac{d}{dt} \dot{\Phi} = 0} \quad (H)$

L is unknown

$$I_c \sin \left(\frac{2\pi \Phi}{\Phi_0} \right) + C_J \frac{d}{dt} \dot{\Phi} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\Phi}} \right) - \frac{\partial L}{\partial \Phi}$$

This would imply $\frac{\partial L}{\partial \Phi} = -I_c \sin \left(\frac{2\pi \Phi}{\Phi_0} \right)$

$$L(\Phi, \dot{\Phi}) = \frac{\Phi_0 I_c}{2\pi} \cos(2\pi \Phi / \Phi_0)$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\Phi}} \right) = C_J \frac{d}{dt} \dot{\Phi}$$

$$\frac{\partial L}{\partial \dot{\Phi}} = C_J \dot{\Phi} \Rightarrow L = \frac{C_J \dot{\Phi}^2}{2}$$

In this question,
equation of motion
is known,
Lagrangian =
unknown

$$\Rightarrow L(\Phi, \dot{\Phi}) = \frac{I_c \Phi_0}{2\pi} \cos(2\pi \Phi / \Phi_0) + \frac{C_J \dot{\Phi}^2}{2}$$

$$\textcircled{1} \quad Q = \frac{\partial L}{\partial \dot{\Phi}} = C_J \dot{\Phi}$$

$$\textcircled{2} \quad H = Q\dot{\Phi} - L$$

$$H = C_J \dot{\Phi}^2$$

$$H = C_J \dot{\Phi}^2 - \frac{C_J \dot{\Phi}^2}{2} - \frac{I_c \Phi_0}{2\pi} \cos(2\pi \Phi / \Phi_0)$$

$$\hat{H} = \frac{1}{2} C_J \dot{\Phi}^2 - \frac{I_c \Phi_0}{2\pi} \cos(2\pi \Phi / \Phi_0)$$

From this point onward, everything is straightforward. Expand the cos factor in $\hat{H}$, substitute the ladder operators, and keep the energy preserving terms.